Modicon M171 Performance Logic Controller

Hardware User Manual

09/2014









Schneider Electric

The information provided in this documentation contains general descriptions and/or technical characteristics of the performance of the products contained herein. This documentation is not intended as a substitute for and is not to be used for determining suitability or reliability of these products for specific user applications. It is the duty of any such user or integrator to perform the appropriate and complete risk analysis, evaluation and testing of the products with respect to the relevant specific application or use thereof. Neither Schneider Electric nor any of its affiliates or subsidiaries shall be responsible or liable for misuse of the information contained herein.

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All pertinent state, regional, and local safety regulations must be observed when installing and using this product. For reasons of safety and to help ensure compliance with documented system data, only the manufacturer should perform repairs to components.

When devices are used for applications with technical safety requirements, the relevant instructions must be followed.

Failure to use Schneider Electric software or approved software with our hardware products may result in injury, harm, or improper operating results.

Failure to observe this information can result in injury or equipment damage.

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ABOUT THE BOOK



How to use this manual

This manual uses the following conventions to highlight certain parts of the text:

Note

Indicates further information on the subject concerned that the user should take into account.



Tip

A suggestion that could help the user to understand and make better use of the information provided

*, **, (*), (**), (¹), (²), (§)

Fig. 1, 1 - Fig. 1, etc.

Provides further specifications on an explanation provided previously

Provides references to figures, details in figures, parts of the text. Figures are referred to using an approximation in hold (Fig. "Fig.") and a number identifying the reference (Fig. Fig. 1).

abbreviation in bold (E.g. "**Fig.**") and a number identifying the reference (E.g. **Fig. 1**). For components inside figures, the references are given using a letter or number (E.g. **1 - Fig. 1**).

References to parts of the text are given using the number and title of the relative chapters,

sub-chapters, paragraphs and page number.

Document Scope

This document describes the **Modicon M171 performance logic controllers** and accessories including installation and wiring information.

Validity Note

This document is valid for **SoMachine HVAC**.

Related Documents

Title of Documentation	Reference Document Code
Modicon M171 Optimized Controllers Hardware User Manual	EIO0000002032 (ENG)
Modicon M171 Electronic Expansion Valve Drivers User Manual	EIO000002034 (ENG)
SoMachine HVAC software Quick Start	EIO0000002035 (ENG)
SoMachine HVAC software HelpOnLine Manual	EIO0000002036 (ENG)
TM171 Performance 27 IO Instruction Sheet	EAV96004
TM171 Performance Flush 3 IO Instruction Sheet	EAV96006
TM171 Performance Communication Instruction Sheet	EAV960007
TM171 Performance Display Instruction Sheet	EAV96014

You can download these technical publications and other technical information from our website at: www.schneider-electric.com

SAFETY INFORMATION



Important Information

Read these instructions carefully, and look at the equipment to become familiar with the device before trying to install, operate, or maintain it. The following special messages may appear throughout this documentation or on the equipment to inform of potential hazards or to call attention to information that clarifies or simplifies a procedure.



The addition of this symbol to a Danger safety label indicates that an electrical hazard exists, which will result in personal injury if the instructions are not followed.



This is the safety alert symbol. It is used to alert you to potential personal injury hazards. Obey all safety messages that follow this symbol to avoid possible injury or death.

A DANGER

DANGER indicates an imminently hazardous situation which, if not avoided, results in death or serious injury.

A WARNING

WARNING indicates a potentially hazardous situation which, if not avoided, can result in death or serious injury.

A CAUTION

CAUTION indicates a potentially hazardous situation which, if not avoided, **can result in** minor or moderate injury.

NOTICE

NOTICE is used to address practices not related to physical injury.

PLEASE NOTE

Electrical equipment should be installed, operated, serviced, and maintained only by qualified personnel. No responsibility is assumed by Schneider Electric for any consequences arising out of the use of this material. A qualified person is one who has skills and knowledge related to the construction and operation of electrical equipment and its installation, and has received safety training to recognize and avoid the hazards involved.

Permitted use

This product is used to control HVAC applications.

For safety reasons, the device must be installed and used in accordance with the instructions provided. In particular, parts carrying dangerous voltages must not be accessible under normal conditions.

The device must be adequately protected from water and dust with regard to the application, and must only be accessible using tools (with the exception of the front panel).

The device is also suitable for use in household and commercial refrigeration appliances and/or similar equipment and has been tested for safety aspects in accordance with the harmonized European reference standards.

Prohibited use

Any use other than that expressed above under Permitted use is strictly prohibited.

The relay contacts supplied are of an electromechanical type and subject to wear. Functional safety protection devices, specified in international or local standards, must be installed externally to this device.

Liability and residual risks

Schneider Electric liability is limited to the proper and professional use of this product under the guidelines contained in the present and other supporting documents, and does not extend to damages caused by (but not limited to):

- Unspecified installation/use and, in particular, in contravention of the safety requirements of established legislation or specified in this document;
- Use on equipment which does not provide adequate protection against electrocution, water and dust in the actual installation conditions;
- · Use on equipment in which dangerous components can be accessed without the use of specific tools;
- Installation/use on equipment which does not comply with established legislation and standards.

Disposal



The appliance (or the product) must be disposed of separately in compliance with the local standards in force on waste disposal.

Product Related Information

A A DANGER

HAZARD OF ELECTRIC SHOCK, EXPLOSION OR ARC FLASH

- Disconnect all power from all equipment including connected devices, prior to removing any covers or doors, or installing or removing any accessories, hardware, cables, or wires.
- Always use a properly rated voltage sensing device to confirm the power is removed.
- Replace and secure all covers, accessories, hardware, cables, and wires and confirm that a proper ground connection exists before applying power to the unit.
- · Use only the specified voltage when operating this equipment and any associated products.

Failure to follow these instructions will result in death or serious injury.

This equipment has been designed to operate outside of any hazardous location. Only install this equipment in zones known to be free of hazardous atmosphere.

A DANGER

POTENTIAL FOR EXPLOSION

Install and use this equipment in non-hazardous locations only.

Failure to follow these instructions will result in death or serious injury.

A WARNING

LOSS OF CONTROL

- The designer of any control scheme must consider the potential failure modes of control paths and, for certain critical control functions, provide a means to achieve a safe state during and after a path failure. Examples of critical control functions are emergency stop and overtravel stop, power outage and restart.
- Separate or redundant control paths must be provided for critical control functions.
- System control paths may include communication links. Consideration must be given to the implications of unanticipated transmission delays or failures of the link.
- Observe all accident prevention regulations and local safety guidelines.⁽¹⁾
- Each implementation of this equipment must be individually and thoroughly tested for proper operation before being placed into service.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

(1) For additional information, refer to NEMA ICS 1.1 (latest edition), "Safety Guidelines for the Application, Installation, and Maintenance of Solid State Control" and to NEMA ICS 7.1 (latest edition), "Safety Standards for Construction and Guide for Selection, Installation and Operation of Adjustable-Speed Drive Systems" or their equivalent governing your particular location.

A WARNING

UNINTENDED EQUIPMENT OPERATION

- · Only use software approved by Schneider Electric for use with this equipment.
- · Update your application program every time you change the physical hardware configuration.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

CHAPTER 1

Introduction

1.1. General description

The **Modicon M171P** is a **Schneider Electric** range of programmable controller, suitable for managing a wide range of HVAC/R and many other applications, from the simplest to the most complex.



In this manual, the photos are intended to show the **Modicon M171P** programmable controller and are for indication purposes only. The dimensions shown in the figures are not to scale.

The Modicon M171P offer is made of:

- M171 Performance
- M171 Display Graphic (TM171DGRP)
- M171 Performance Flush

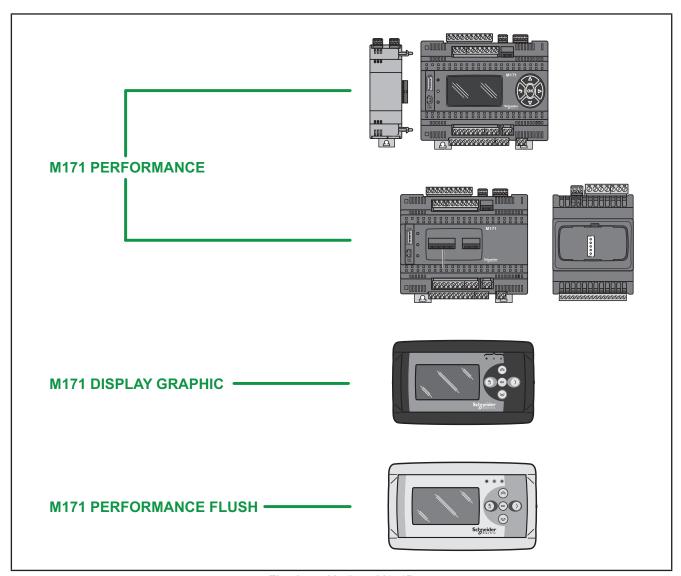


Fig. 1. Modicon M171P

M171 Performance delivers high performance in terms of memory, connectivity and user interface as well as straightforward programming, maintenance and servicing.

The references are available as 8 DIN rail-mounted versions, which saves considerable time in terms of wiring. The 8DIN format provides maximum flexibility and easy installation.

A wide range of plug-in, 2DIN rail-mounted modules will allow integration with industrial systems, BMS and Ethernet networks.

Lastly, ratiometric pressure sensors and displays can also be connected with no need for any further serial interfaces.

M171 Performance Flush can be used as a system controller, with gateway functions; used in combination with the M171 Performance and the Modicon M171O or third-party controllers it delivers high performance in terms of memory, connectivity and user interface as well as straightforward programming, maintenance and servicing.

M171 Performance Flush is designed for panel mounting, and can also be wall-mounted using a special backplate, available as an accessory.

M171 Performance Flush can be used to:

- manage a local menu created with the TM171SW (SoMachineHVAC) User Interface;
- manage up to 10 remote menus, created with the TM171SW (SoMachineHVAC) User Interface and uploaded from the respective M171 Performance devices connected to the network;
- share network variables (binding).

In association with the **Modicon M171P** hardware, there is also the **TM171SW** (**SoMachineHVAC**) development tool to quickly and reliably program and customize new programmes for any application.

The use of several different programming languages in accordance with IEC61131-3 regulations (programming standard for industrial control), makes it possible to develop new algorithms or entire programmes totally unassisted, which can then be uploaded to the **Modicon M171P** modules via PC or (only **M171 Performance**) standard USB.

WEB functionalities

The **Modicon M171P** also features WEB functionalities, offering makers of machinery and systems integrators full remote access. Having a web-based connection in machines significantly reduces support and maintenance costs by minimizing call-out charges. End users also benefit, as they can monitor their own systems both locally and from distance, using the easy-to-understand graphics interface of any common browser via smartphone, tablet or PC.

Main WEB functionalities

- · Web-based access.
- · Remote reading and support.
- · Local and remote system control, including alarms management.
- · Preventive and predictive maintenance.
- · Email alarm alerts.
- · Next generation system interface on PC, tablet and smartphone.

1.1.1. Specifications

	TM171PDM27 ● / TM171PBM27R is equipped with 27 inputs/ outputs, including 5 analog outputs, 6 analog inputs, 7 relay digital outputs (or 5 relays + 2 SSRs) and 9 digital inputs. TM171PDM27 ● / TM171PBM27R comes in 2 different refe- rences, giving the choice of integrated serial as standard,	TM171PDM27● has a built-in graphical user display.	
M171 Performance 24V~/ or 48V power supply	with or without on-board USB as standard (TM171PDM27 • references). Analog Inputs configurable as NTC 103AT/NTCNK103, PT1000, 420mA, 05V ratiometric, 010V, or hΩ(NTC)/ daΩ(PT1000) from parameters. Parameter settings via display or PC. USB port for downloading or uploading parameter maps.	TM171PBM27R has no display and must be connected to a remote M171 Display Graphic (TM171DGRP) for the configuration of BIOS parameters.	
	M171 Performance can be expanded to include up to 12 extra modules. The M171 Performance TM171EP27R expansion has 27 inputs/outputs, including 5 analog outputs and 6 analog inputs.		
M171 Performance 24V~/ power supply	M171 Performance can be expanded to include up to 12 extra modules. The M171 Performance TM171EP14R expansion has 14 inputs/outputs, including 2 analog outputs and 4 analog inputs.		
M171 Performance Plug-in(s)	M171 Performance has plug-ins that can be connected to TM171PDM27● / TM171PBM27R to interface with CAN, RS232, RS485, TCP/IP, Profibus: plug-in TM171A●●● modules provide additional serial ports for integration with industrial systems, BMS and Ethernet.		
M171 Performance Flush 24V~/ or 48V power supply	TM171PFE03 is equipped with serial CAN, RS485 and ETHERNET, 3 inputs (1 on-board NTC + 1 remote configurable NTC/DI +1 remote current/voltage configurable). TM171PFE03HR is equipped with serial CAN, RS485 and ETHERNET, 3 inputs (1 on-board humidity module + 1 on-board NTC + 1 remote configurable NTC/DI). M171 Performance Flush comes with a built-in 128x64px graphical user display.		

CHAPTER 2

Mechanical installation

2.1. Before Starting

Read and understand this chapter before beginning the installation of your system. The use and application of the information contained herein require expertise in the design and programming of automated control systems. Only you, the user, machine builder or integrator, can be aware of all the conditions and factors present during installation and setup, operation, and maintenance of the machine or process, and can therefore determine the automation and associated equipment and the related safeties and interlocks which can be effectively and properly used. When selecting automation and control equipment, and any other related equipment or software, for a particular application, you must also consider any applicable local, regional or national standards and/or regulations. Pay particular attention in conforming to any safety information, different electrical requirements, and normative standards that would apply to your machine or process in the use of this equipment.

The use and application of the information contained herein require expertise in the design and programming of automated control systems. Only you, the user, machine builder or system integrator can be aware of all the conditions and factors present during installation and setup, operation, and maintenance of the machine or process, and can therefore determine the automation and associated equipment and the related safeties and interlocks which can be effectively and properly used. When selecting automation and control equipment, and any other related equipment or software, for a particular application, the user or integrator must also consider any applicable local, regional or national standards and/or regulations.

A WARNING

REGULATORY INCOMPATIBILITY

Be sure that all equipment applied and systems designed comply with all applicable local, regional and national regulations and standards.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

2.2. Disconnecting Power

All options and modules should be assembled and installed before installing the control system on a mounting rail, into a panel door or onto a mounting surface. Remove the control system from its mounting rail, mounting plate or panel before disassembling the equipment.

A A DANGER

HAZARD OF ELECTRIC SHOCK, EXPLOSION OR ARC FLASH

- Disconnect all power from all equipment including connected devices, prior to removing any covers or doors, or installing or removing any accessories, hardware, cables, or wires.
- Always use a properly rated voltage sensing device to confirm the power is removed.
- Replace and secure all covers, accessories, hardware, cables, and wires and confirm that a proper ground connection exists before applying power to the unit.
- Use only the specified voltage when operating this equipment and any associated products.

Failure to follow these instructions will result in death or serious injury.

2.3. Programming Considerations

The products described in this manual have been designed and tested using Schneider Electric programming, configuration and maintenance software products.

WARNING

UNINTENDED EQUIPMENT OPERATION

- · Only use software approved by Schneider Electric for use with this equipment.
- · Update your application program every time you change the physical hardware configuration.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

2.4. Operating Environment

This equipment has been designed to operate outside of any hazardous location. Only install this equipment in zones known to be free of a hazardous atmosphere.

A DANGER

POTENTIAL FOR EXPLOSION

Install and use this equipment in non-hazardous locations only.

Failure to follow these instructions will result in death or serious injury.

A WARNING

UNINTENDED EQUIPMENT OPERATION

Install and operate this equipment according to the conditions described in the General Specifications.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

2.5. Installation Considerations

WARNING

UNINTENDED EQUIPMENT OPERATION

- Use appropriate safety interlocks where personnel and/or equipment hazards exist.
- Install and operate this equipment in an enclosure, or other locations that are appropriate for its rated environment.
- Power line and output circuits must be wired and fused in compliance with local and national regulatory requirements for the rated current and voltage of the particular equipment.
- · Do not use this equipment in safety-critical machine functions.
- · Do not disassemble, repair, or modify this equipment.
- · Do not connect any wiring to reserved, unused connections, or to connections designated as Not Connected (N.C.).
- · Do not mount devices in extremely damp and/or dirt-laden areas

Failure to follow these instructions can result in death, serious injury, or equipment damage.

NOTE: JDYX2 or JDYX8 fuse types are UL-recognized and CSA approved.

For mechanical dimensions, see 4.6. Mechanical dimensions on pag. 69.

The Modicon M171P devices are intended for DIN rail mounting, panel mounting or wall mounting.

Care must be taken to avoid damage from electrostatic sources when handling this equipment. In particular exposed connectors and, in some cases, exposed printed circuit boards are exceptionally vulnerable to electrostatic discharge.

WARNING

UNINTENDED EQUIPMENT OPERATION DUE TO ELECTROSTATIC DISCHARGE DAMAGE

- Keep equipment in the protective conductive packaging until you are ready to install the equipment.
- Only install equipment in approved enclosures and / or locations that prevent casual access and provide electrostatic discharge protection as defined by IEC 1000-4-2.
- Use a conductive wrist strap or equivalent field force protective device attached to an earth ground when handling sensitive equipment.
- · Always discharge yourself by touching a grounded surface or approved antistatic mat before handling the equipment.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

2.6. TM171PDM27● / TM171PBM27R / TM171EP●●R installation

The instrument is intended for 8DIN rail mounting (refer to Fig. 2 on pag. 18 and Fig. 3 on pag. 19). For DIN rail installation, follow the steps described below:

- 1. Move the two spring docking devices to their standby position (use a screwdriver to press against the relative compartments).
- 2. install the device on the DIN rail.
- 3. Pressing on the "spring docking devices" to put them into the locked position.
- 4. Once assembled on the DIN rail, the "spring docking devices" must be turned downwards.

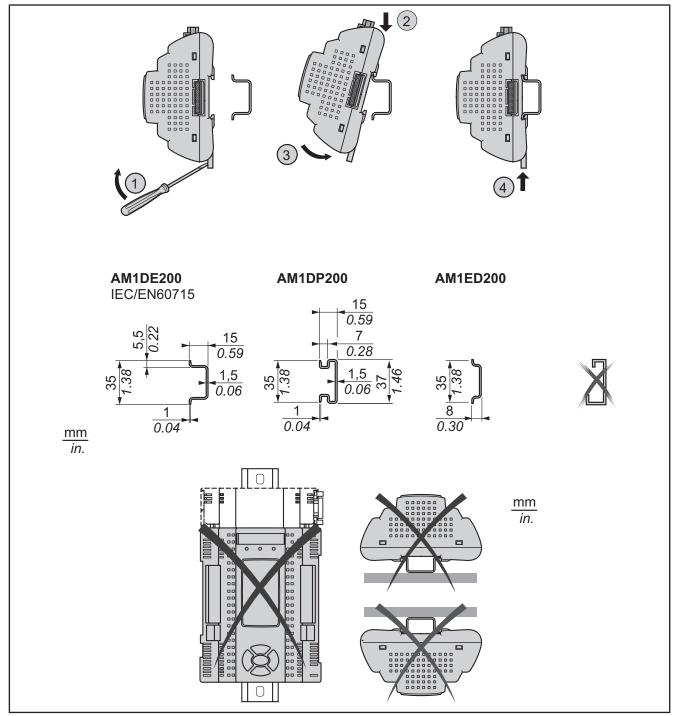


Fig. 2. Mounting

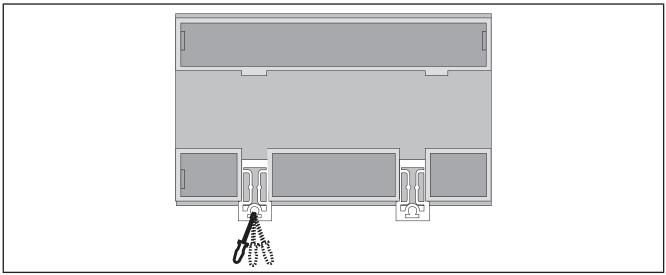


Fig. 3. Details of spring docking devices

The **M171 Performance logic controller** has been designed as an IP20 product and must be installed in an enclosure. Clearances must be respected when installing the product.

There are 3 types of clearances between:

- The M171P and all sides of the cabinet (including the panel door).
- The **M171P** terminal blocks and the wiring ducts. This distance reduces electromagnetic interference between the controller and the wiring ducts.
- The M171P and other heat generating devices installed in the same cabinet.

A WARNING

UNINTENDED EQUIPMENT OPERATION

- Place devices dissipating the most heat at the top of the cabinet and ensure adequate ventilation.
- Avoid placing this equipment next to or above devices that might cause overheating.
- Install the equipment in a location providing the minimum clearances from all adjacent structures and equipment as directed in this document.
- · Install all equipment in accordance with the specifications in the related documentation.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

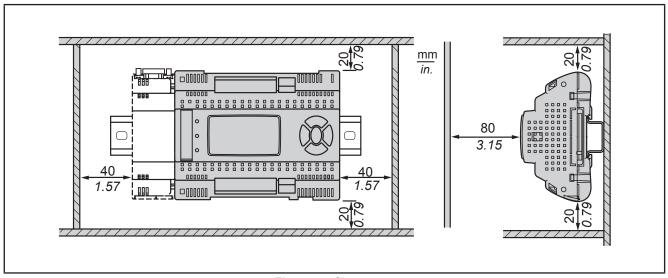


Fig. 4. Clearances

2.7. Assembling the TM171A●●● Plung-ins and installation with TM171PDM27● / TM171PBM27R

Plug-ins are 2DIN modules that connect to a M171 Performance TM171PDM27● / TM171PBM27R controller (refer to Fig. 5 on pag. 20 and Fig. 6 on pag. 20).

To assemble TM171A●●● to TM171PDM27● / TM171PBM27R, follow the steps described below:

- 2. Anchor TM171A●●●● to the TM171PDM27● / TM171PBM27R controller.
- · via the plug-in connector, behind the removable door.
- · with the fixing screws to which the plug-in is anchored to.

Follow the instructions below to install it on DIN rail:

- 1. Move the spring docking devices (two for TM171PDM27 / TM171PBM27R, one for TM171A ● ●) to his standby position (use a screwdriver).
- 2. Install TM171PDM27 / TM171PBM27R + TM171A • • on the DIN rail.
- 3. Press the "spring docking devices" which will go to the closing position.
- 4. Once the "BASE" is mounted on the DIN rail, the "Spring docking device" must be turned downwards.

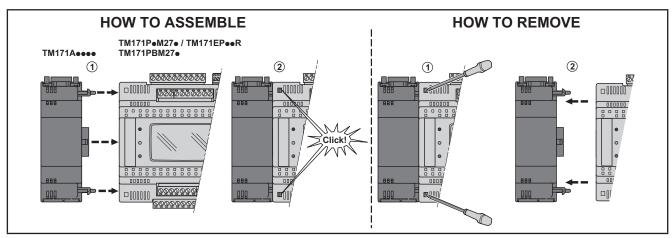


Fig. 5. Assembling the TM171A•●● plug-ins

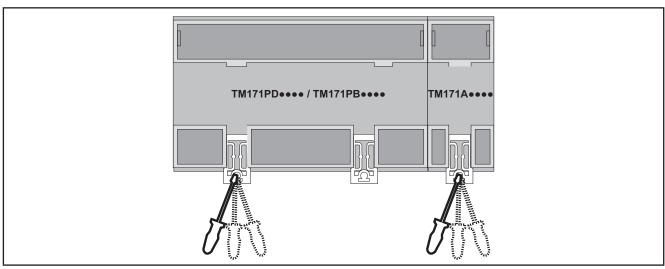


Fig. 6. Details of spring docking devices



TM171A●●●● plug-in / TM171EP●●R expansion connection is allowed for dedicated references only – see CHAPTER 3 Electrical connections on pag. 23 for details.

2.8. Assembling the M171 Performance Flush or M171 Display Graphic (TM171DGRP)

2.8.1. Panel mounting

The instrument is intended for panel mounting (refer to Fig. 7 on pag. 21).



The following figure shows M171 Performance Flush assembling; same steps are required for M171 Display Graphic (TM171DGRP) assembling.

For panel mounting, follow the steps described below:

- 1. Make a 138x68mm hole.
- 2. Remove the front panel and make 4 holes in the panel that the controller is to be mounted on or two holes of dia. 2.7 mm at the specified spacing.
- 3. Insert the device, fixing it with the screws.
- 4. Press the front of the M171 Performance Flush to close.

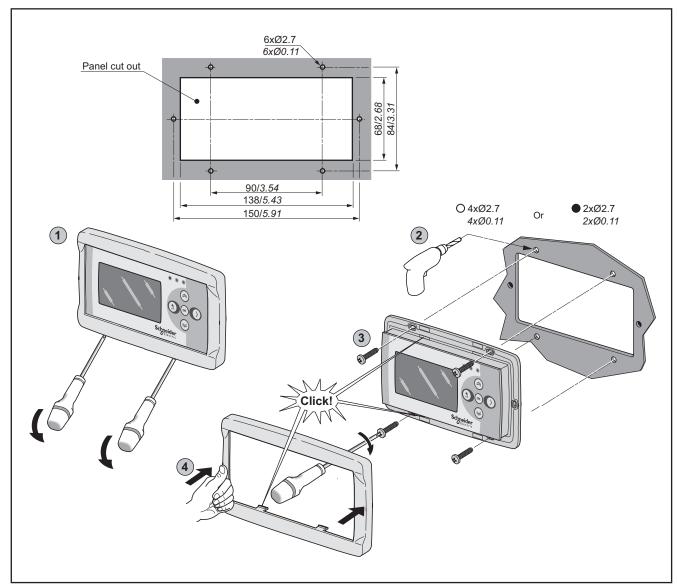


Fig. 7. Assembling the M171 Display Graphic (TM171DGRP) or M171 Performance Flush display

2.8.2. Accessories for Wall mounting

The instrument is also intended for wall mounting (refer to Fig. 8 on pag. 22). Contact the **Schneider Electric** Sales Department for wall-mounting accessories.

- 1. Make 4 holes of diameter 4.2mm in the wall at the specified spacing to fix the backplate. Alternatively use the two side slots, one at the bottom and one at the top, under the corresponding break-open removable doors, preventing the opening of holes in walls with recessed-wall wiring.
- 2. Make all the necessary connections.
- 3. Insert the M171 Performance Flush display (without front) in the backplate, which serves as a panel, following the instructions for panel mounting (see 2.8.1. Panel mounting on pag. 21).

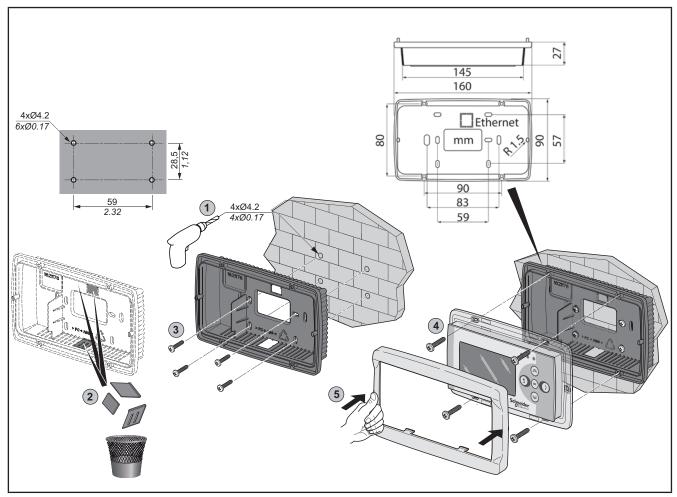


Fig. 8. Accessories for Wall mounting

Code	Description
TM171ABKPB	White backplate kit for wall mounting
TM171ABKPG	Black backplate kit for wall mounting



4 backplates for package.

CHAPTER 3

Electrical connections

3.1. Wiring Best Practices

The following information describes the wiring guidelines and associated best practices to be respected when using the M171 Performance Logic Controller.

A A DANGER

HAZARD OF ELECTRIC SHOCK, EXPLOSION OR ARC FLASH

- Disconnect all power from all equipment including connected devices, prior to removing any covers or doors, or installing or removing any accessories, hardware, cables, or wires.
- · Always use a properly rated voltage sensing device to confirm the power is removed.
- Replace and secure all covers, accessories, hardware, cables, and wires and confirm that a proper ground connection exists before applying power to the unit.
- · Use only the specified voltage when operating this equipment and any associated products.

Failure to follow these instructions will result in death or serious injury.

A WARNING

LOSS OF CONTROL

- The designer of any control scheme must consider the potential failure modes of control paths and, for certain critical control functions, provide a means to achieve a safe state during and after a path failure. Examples of critical control functions are emergency stop and overtravel stop, power outage and restart.
- Separate or redundant control paths must be provided for critical control functions.
- System control paths may include communication links. Consideration must be given to the implications of unanticipated transmission delays or failures of the link.
- Observe all accident prevention regulations and local safety guidelines.⁽¹⁾
- Each implementation of this equipment must be individually and thoroughly tested for proper operation before being placed into service.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

(1) For additional information, refer to NEMA ICS 1.1 (latest edition), "Safety Guidelines for the Application, Installation, and Maintenance of Solid State Control" and to NEMA ICS 7.1 (latest edition), "Safety Standards for Construction and Guide for Selection, Installation and Operation of Adjustable-Speed Drive Systems" or their equivalent governing your particular location.

3.1.1. Wiring Guidelines

The following rules must be applied when wiring a M171 Performance logic controllers:

- I/O and communication wiring must be kept separate from the power wiring. Route these two types of wiring in separate
 cable ducting.
- Verify that the operating conditions and environment are within the specification values.
- Use proper wire sizes to meet voltage and current requirements.
- Use copper conductors (required).
- Use twisted pair, shielded cables for analog, and/or fast I/O.
- Use twisted pair, shielded cables for networks, and fieldbus.

Use shielded, properly grounded cables for all analog and high-speed inputs or outputs and communication connections. If you do not use shielded cable for these connections, electromagnetic interference can cause signal degradation. Degraded signals can cause the controller or attached modules and equipment to perform in an unintended manner.

A WARNING

UNINTENDED EQUIPMENT OPERATION

- Use shielded cables for all fast I/O, analog I/O and communication signals.
- Ground cable shields for all analog I/O, fast I/O and communication signals at a single point (1).
- Route communication and I/O cables separately from power cables.
- Make connections as short as possible and do not wind them around electrically connected parts.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

(1) Multipoint grounding is permissible if connections are made to an equipotential ground plane dimensioned to help avoid cable shield damage in the event of power system short-circuit currents.

NOTE: Surface temperatures may exceed 60 °C. Route primary wiring (wires connected to power mains) separately and apart from secondary wiring (extra low voltage wiring coming from intervening power sources). If that is not possible, double insulation is required such as conduit or cable gains.

3.1.2. Rules for Removable Screw Terminal Block

The following table presents the cable types and wire sizes for a 5.08 or 5.00 pitch removable screw terminal block:

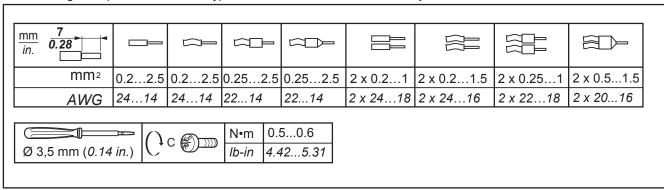


Fig. 9. Pitch 5.08 mm (0.20 in.) or 5.00 mm (0.197 in.)

The following table presents the cable types and wire sizes for a 3.81 or 3.50 pitch removable screw terminal block:

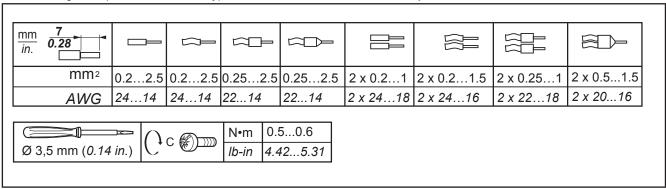


Fig. 10. Pitch 3.81 mm (0.15 in.) or 3.50 mm (0.14 in.)

The use of copper conductors is required.

A A DANGER

LOOSE WIRING CAUSES ELECTRIC SHOCK

- · Tighten connections in conformance with the torque specifications.
- Do not insert more than one wire per connector of the terminal block without the cable ends specified in the tables found in the Rules for Removable Screw Terminal Block information.

Failure to follow these instructions will result in death or serious injury.

A DANGER

FIRE HAZARD

- · Use only the recommended wire sizes for the current capacity of the I/O channels and power supplies.
- For relay output wiring of 2 A, use conductors of at least 0.5 mm² (AWG 20) with a temperature rating of at least 80 °C (176 °F).
- For relay output wiring of 3 A, use conductors of at least 1.5 mm² (AWG 16) with a temperature rating of at least 80 °C (176 °F).
- For common conductors of relay output wiring of 8 A, or relay output wiring greater than 3 A, use conductors of at least 2.0 mm² (AWG 12) with a temperature rating of at least 80 °C (176 °F).

Failure to follow these instructions will result in death or serious injury.

3.1.3. Protecting Outputs from Inductive Load Damage

Depending on the load, a protection circuit may be needed for the outputs on the controllers and certain modules. Inductive loads using DC voltages may create voltage reflections resulting in overshoot that will damage or shorten the life of output devices.

A CAUTION

OUTPUT CIRCUIT DAMAGE DUE TO INDUCTIVE LOADS

Use an appropriate external protective circuit or device to reduce the risk od inductive direct current load damage Failure to follow these instructions can result in injury or equipment damage.

If your controller or module contains relay outputs, these types of outputs can support up to 240 Vac. Inductive damage to these types of outputs can result in welded contacts and loss of control. Each inductive load must include a protection device such as a peak limiter, RC circuit or flyback diode. Capacitive loads are not supported by these relays.

WARNING

RELAY OUTPUTS WELDED CLOSED

- Always protect relay outputs from inductive alternating current load damage using an appropriate external protective circuit or device.
- · Do not connect relay outputs to capacitive loads.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

Protective circuit A: this protection circuit can be used for both AC and DC load power circuits.

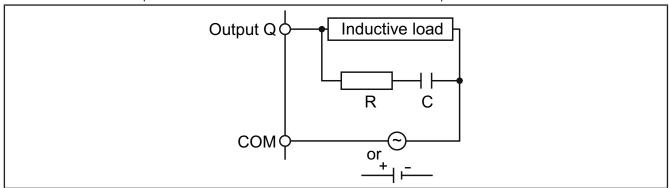


Fig. 11. Protective circuit A

 \boldsymbol{C} Value from 0.1 to 1 μF

R Resistor of approximately the same resistance value as the load

Protective circuit B: this protection circuit can be used for DC load power circuits.

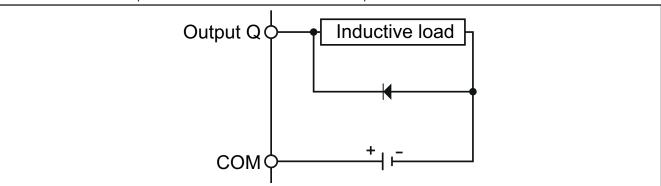


Fig. 12. Protective circuit B

Use a diode with the following ratings:

- Reverse withstand voltage: power voltage of the load circuit x 10.
- Forward current: more than the load current.

Protective circuit C: this protection circuit can be used for both AC and DC load power circuits.

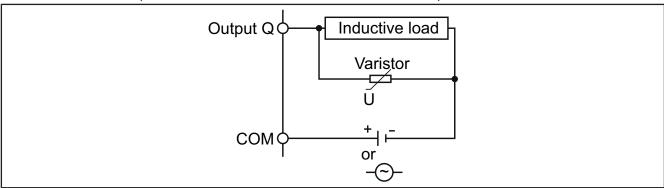


Fig. 13. Protective circuit C

In applications where the inductive load is switched on and off frequently and/or rapidly, ensure that the continuous energy rating (J) of the varistor exceeds the peak load energy by 20 % or more.

NOTE: Place protection devices as close to the load as possible.

3.1.4. Special handling considerations

Care must be taken to avoid damage from electrostatic sources when handling this equipment. In particular exposed connectors and, in some cases, exposed printed circuit boards are exceptionally vulnerable to electrostatic discharge.

WARNING

UNINTENDED EQUIPMENT OPERATION DUE TO ELECTROSTATIC DISCHARGE DAMAGE

- · Keep equipment in the protective conductive packaging until you are ready to install the equipment.
- Only install equipment in approved enclosures and / or locations that prevent casual access and provide electrostatic discharge protection as defined by IEC 1000-4-2.
- Use a conductive wrist strap or equivalent field force protective device attached to an earth ground when handling sensitive equipment.
- · Always discharge yourself by touching a grounded surface or approved antistatic mat before handling the equipment.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

3.1.5. Analog Inputs-Probes

Temperature probes have no connection polarity and can be extended using a normal bipolar cable (note that the extension of the probes influences the electromagnetic compatibility (EMC) of the instrument: take great care with the wiring).

NOTE: Probes which have a specific connection polarity, which must be observed.

NOTICE

INOPERABLE EQUIPMENT

Verify all wiring connections before applying power.

Failure to follow these instructions can result in equipment damage.

NOTE: Apply power to all externally powered devices after applying power to the M171 Performance logic controllers.

NOTE: Signal leads (probes, digital inputs, communication and the electronic supply) must be routed separately from power cables.

3.1.6. Serial connections

	The reference has on-board serial as standard
M171 Performance	CAN, RS485, USB
M171 Performance Flush	CAN, RS485, ETHERNET

Pay special attention when connecting serial lines. Miswiring may lead to malfunctioning or inoperable equipment.

NOTICE

INOPERABLE EQUIPMENT

- Do not connect instruments that communicate using RS485 serial to CAN terminals.
- · Do not connect CAN instruments to RS485 terminals.

Failure to follow these instructions can result in equipment damage.



Plug-in **TM171A●●●●** modules provide additional serial ports for integration with industrial systems, BMS and Ethernet.

Controller serials are defined as "on-board" (OB) whereas serials on **TM171A••••** are referred to as plug-ins (PI).

CAN

- Use a shielded and "twisted pair" cable with two 0.5 mm² conductors, plus braid ideally Belden cable reference 3105A (characteristic impedance 120 Ω) with PVC sleeve, 2 conductors plus braid, 22 AWG, nominal capacity between conductors 36pF/m, nominal capacity between conductor and shielding 68pF/m).
- Always follow regulations applicable to the routing and connection of cables. Make certain that data transmission circuits
 are properly separated from power lines.
- For connections over longer distances, it is better to end the line with resistors on both ends, inserting the two **R TERM** jumpers (available on the terminal strip beside the CAN serial as the default factory configuration).
- · The maximum distance depends on the baud setting.

Kb/s (Kbaud)	On-board CAN (m) - M171 Performance	On-board CAN (m) - M171 Performance Flush	Plug-In CAN (m)
50	1000	1000	1000
125	500	500	500
250	200	250	250
500	30	60	60

· 5-way terminal:

3-way ("GS", "H and "L") serial CAN
2-way POWER supply for M171 Display Graphic (TM171DGRP) terminal

RS485

- Use a shielded and "twisted pair" cable with two 0.5mm² conductors, plus braid (ideally Belden cable reference 8762 with PVC sleeve, 2 conductors plus braid, 20 AWG, nominal capacity between conductors 89 pF/m, nominal capacity between conductor and shielding 161 pF/m). See EN 50174 standard on IT cabling for indications on how cables should be routed.
- Make certain that data transmission circuits are properly separated from power lines.
- An RS485 network up to 1200 m in length with a maximum of 256* devices can be connected straight to the controller.



- * Example of **M171 Performance** Modbus Slave with single Master supervisor. This length can be extended and the number of devices for each channel increased using appropriate repeater modules.
- Single terminal strip with 3 conductors: use all 3 conductors ("+", "-" for the signal and "GS" for the braid).
- Attach the 120 Ω 1/4W resistors between the "+" and "-" terminals of the interface and the last controller in each branch
 of the network.
- Maximum settable speed 57600 baud. Higher speeds are envisaged for local connection to TM171SW (SoMachineHVAC)
 Device and tests.

Ethernet



M171 Performance: connection via ETHERNET requires the specific plug-in module TM171AETH / TM171AETHRS485.

M171 Performance Flush: connection via ETHERNET does NOT require any additional module.

The Ethernet connection allows the M171 Performance Flush to communicate on an Ethernet network using TCP/IP protocol.

The connection allows:

- connection of different controllers and/or applications exchanging variables and/or parameters (network).
- connection of a supervision system using Modbus TCP/IP protocol.
- connection of an IEC 61131-3 TM171SW (SoMachineHVAC) development system.



The Ethernet connector shield is internally connected to the earth of the instrument and therefore to the reference of the input and output channels.

USB on M171 Performance (TM171PDM27 • references only)

For **TM171PDM27**• references only, there are 2 USB connectors positioned on the inside of the door to the left of the LEDs, on the top part of the cap.

NOTE: The two USBs should not be used at the same time.



Components required for M171 Performance only: USB/485 adapter TSXCUSB485, cable VW3A83O6D3O

Definition. USB = connector for flash drive, or USB memory key.

USB	PURPOSE	NOTE
Type A (HOST)	Used to connect a standard USB memory key when downloading the application. This should be done from the controller keypad (TM171PDM27● references) or from the M171 Display Graphic (TM171DGRP) (TM171PBM27R reference).	Values on pag. 73 for information on how to
Type B (DEVICE)	Used to connect M171 Performance to a PC or third party device via mini A/B USB cable to up/download the application or documentation. The operations can be done from PC or another device.	Compatible with Windows XP Home and Professional, Windows 2000 and Windows Vista operating systems.

NOTE:

- TM171SW (SoMachineHVAC) does not communicate via USB with M171 Performance.
- TM171SW (SoMachineHVAC) does allow management of the USB serial interface via the fs_iec.pll software library in <C:\Programs>\Schneider Electric\SoMachineHVAC\Catalog\FreeEvolution\PLC

The library also contains target functions (target blocks) to be used for the management of files in the internal M171 Performance memory (see TM171SW (SoMachineHVAC) manual for details).

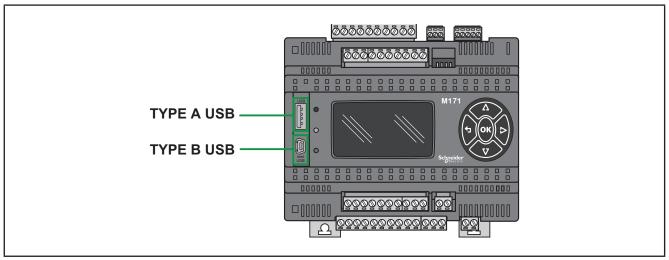


Fig. 14. M171 Performance: type A USB and type B USB

3.2. Wiring diagrams

Miswiring irreversibly damages the Modicon M171P.

NOTICE

INOPERABLE EQUIPMENT

Verify all wiring connections before applying power.

Failure to follow these instructions can result in equipment damage.

3.2.1. Modicon M171P wiring diagram

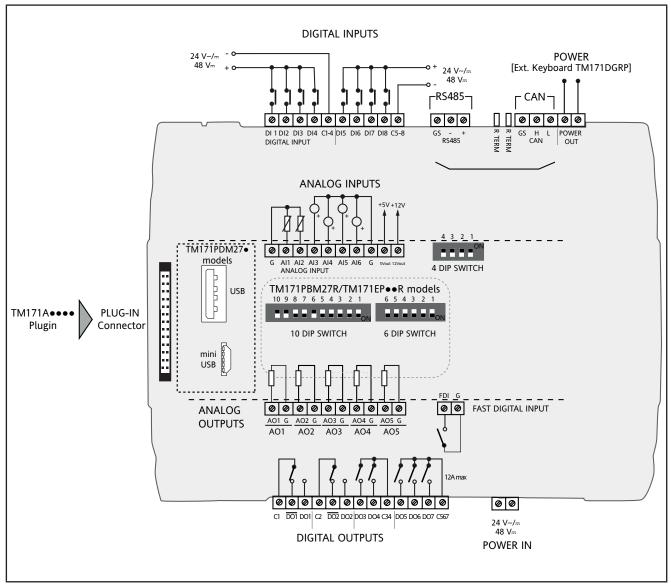


Fig. 15. Modicon M171P wiring diagram

3.2.2. Modicon M171EP14R wiring diagram

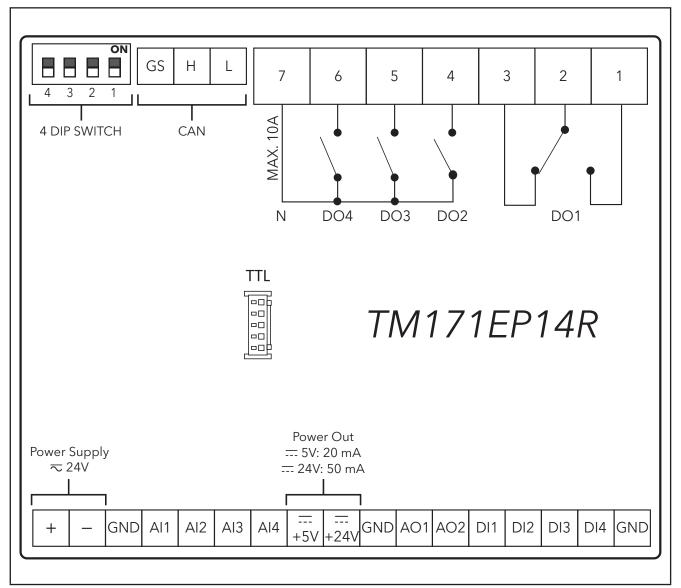


Fig. 16. Modicon M171EP14R wiring diagram

	LABEL	DESCRIPTION	NOTES
DIP SWITCH	4 DIP SWITCH	4-position selectors (Dip Switches)	All References Default OFF
	6 DIP SWITCH	6-position selectors (Dip Switches)	TM171PBM27R reference TM171EP27R expansion
	10 DIP SWITCH	10-position selectors (Dip Switches)	Located behind the panel
POWER	POWER IN	24V~/ or 48V power supply	
	POWER OUT	TM171EP14R reference 24V~/ power supply	POWER [Ext. Keyboard M171 Display Graphic (TM171DGRP)] output for display
ANALOG OUTPUTS	AO1AO5	Analog outputs 15	
	G	Ground	See CHAPTER 4 Technical data on pag. 61 for further details
	12Vout	12V output for analog inputs	
	5Vout	5V output for ratiometric analog inputs	
DIGITAL OUTPUTS	C1 DO1 DO1	Relay output 1	<u>DO</u> 1: Normally Open DO1: Normally Closed
	C2 DO2 DO2	Relay output 2	<u>DO2</u> : Normally Open DO2: Normally Closed
	DO3 DO4	Relay output 3-4 also available as SSR* outputs	*Contact Schneider Electric sales department for parts availability
	C34	Common - digital outputs 3-4	
	DO5 DO6 DO7	Relay output 5-6-7	
	C567	Common - digital outputs 5-6-7	12 A max
CAN	GS H L	Isolated CAN serial GS ground serial insulated from G	R TERM termination resistors for CAN
RS485	GS - +	Isolated RS485 serial GS ground serial insulated from G	Apply 120 Ω termination resistors
DIGITAL INPUTS	DI1DI4	Digital inputs 14	See CHAPTER 4 Technical data on pag. 61 for further details
	C1-4	Common - digital inputs 14	
	DI5DI8	Digital inputs 58	
	C5-8	Common - digital inputs 58	
FAST D.I.	FDI	FAST digital input	Pulse/frequency counter up to 1KHz
	G	Ground GND	
ANALOG INPUTS	Al1Al6	Analog inputs	See CHAPTER 4 Technical data on pag. 61 for further details
	G	Ground GND	

3.2.3. Examples of analog input connection (M171 Performance only)

Example: NTC/PT1000 probe connection

Analog inputs Al1...Al6 are available for NTC
Analog inputs Al3...Al6 are available for NTC/PT1000

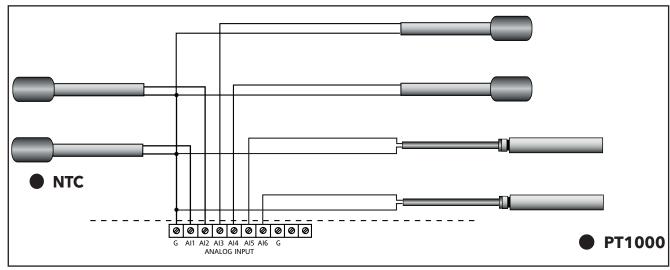


Fig. 17. NTC/PT1000 probe connection

Example: 0-10 V transducer connection

Analog Inputs Al3...Al6 are available

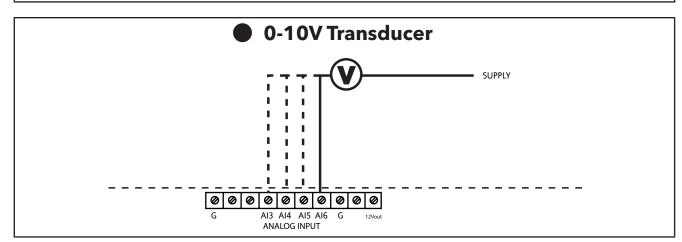


Fig. 18. 0-10V transducer connection

Example: 4...20 mA pressure transducer connection

Analog Inputs Al3...Al6 are available

NOTE: In the case of a generic 3-wire transducer, connect the earth wire to terminal G (GND) and the transducer power supply to 12 Vout.

NOTICE

INOPERABLE EQUIPMENT

Verify all wiring connections before applying power.

Failure to follow these instructions can result in equipment damage.

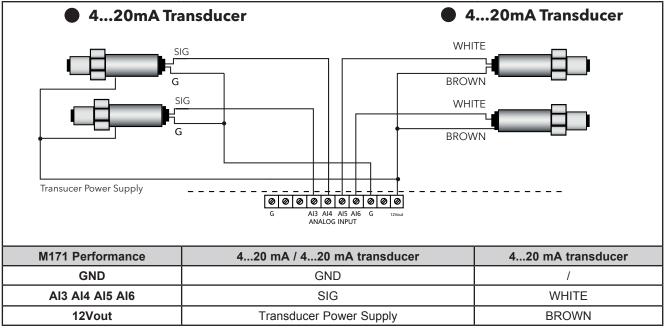


Fig. 19. 4...20 mA pressure transducer connection

Example: ratiometric transducer connection

Analog Inputs Al3...Al6 are available

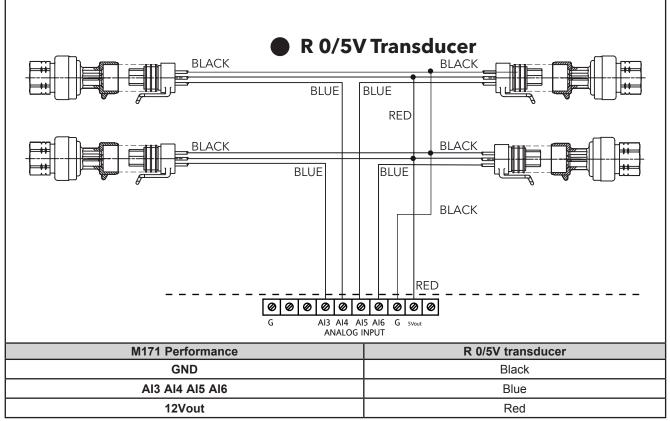


Fig. 20. Ratiometric transducer connection

Example: fan module connection

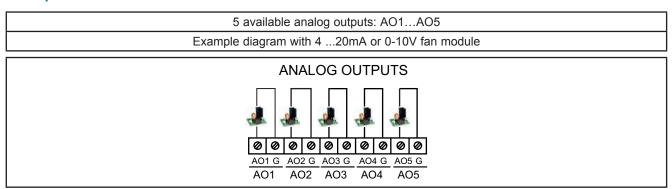


Fig. 21. Fan module connection

Example: Open Collector connection

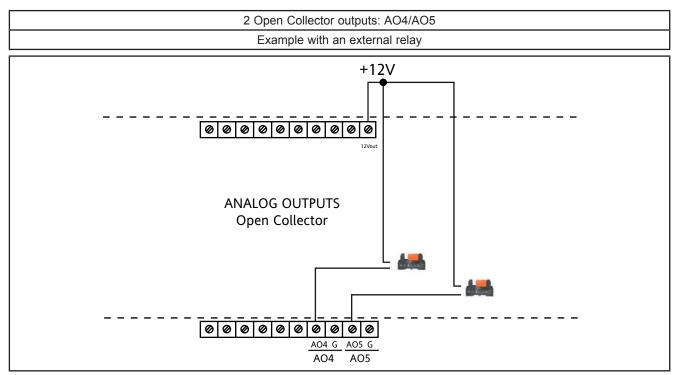


Fig. 22. Open Collector connection

3.2.4. M171 Performance / M171 Display Graphic (TM171DGRP) terminal connection

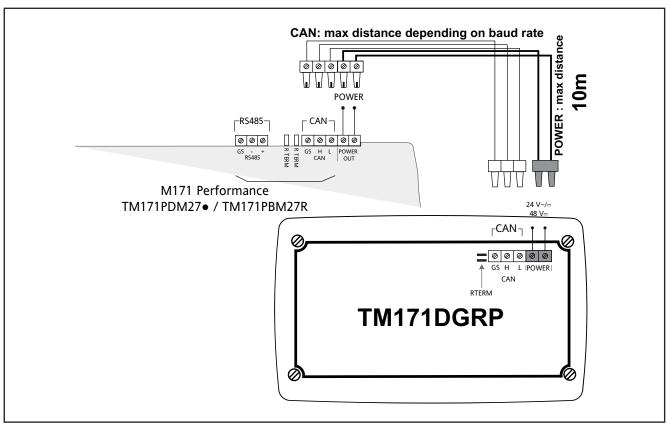


Fig. 23. M171 Performance / M171 Display Graphic (TM171DGRP) terminal connection

NOTE: When supplying power from the **M171 Performance logic controllers**, make the power connection cable as short as possible.

NOTICE

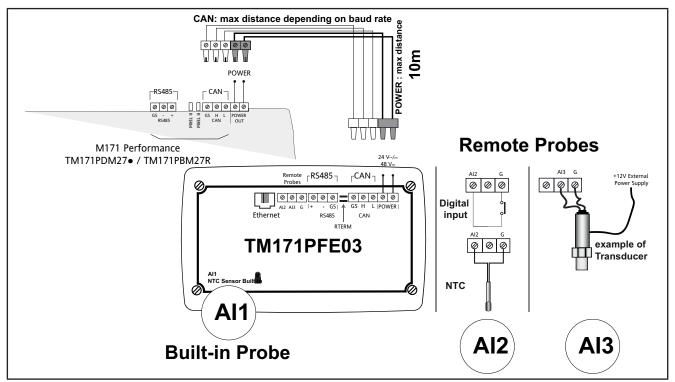
INOPERABLE EQUIPMENT

Do not connect a power cable longer than 10m.

Failure to follow these instructions can result in equipment damage.

	LABEL	DESCRIPTION	NOTES
POWER POWER I	DOWED IN	24V~/ or 48V power supply	Maximum cable length 10m
	POWER IN		from TM171PDM27● or separate power supply
CAN GS H L	Isolated CAN serial	R TERM termination resistors for CAN	
	GS H L	GS ground serial insulated from G	Maximum cable length See 3.1.6. Serial connections on pag. 27

3.2.5. M171 Performance Flush TM171PFE03 and TM171PFE03HR connection



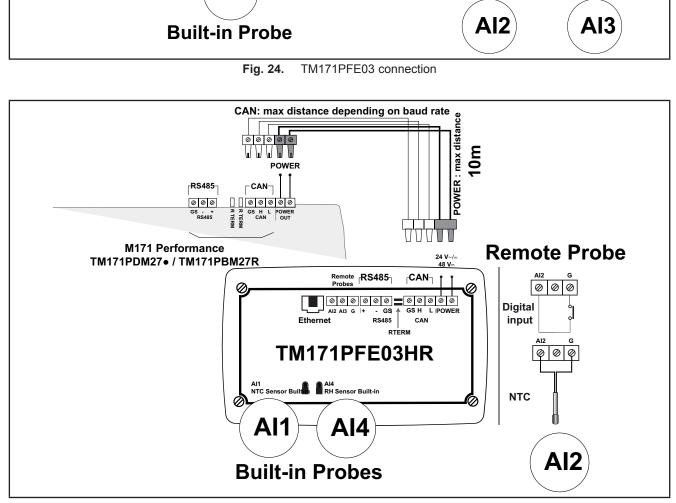


Fig. 25. TM171PFE03HR connection

NOTE: When supplying power from the **M171 Performance logic controllers**, make the power connection cable as short as possible.

NOTICE

INOPERABLE EQUIPMENT

Do not connect a power cable longer than 10m.

Failure to follow these instructions can result in equipment damage.

Label	Description	Notes
POWER	24V~ / or 48V power supply	Pin POWER Vout on TM171PDM27● / TM171PBM27R Max. distance 10m M171 Performance Flush / TM171PDM27● / TM171PBM27R
CAN GS H L	Isolated CAN serial GS ground serial isolated from G	R TERM termination resistors for CAN
RS485 GS - +	Isolated RS485 serial GS ground serial isolated from G	Apply 120 Ω terminal resistors
Ethernet	ETHERNET serial	
Built-in Al1 NTC Sensor	On-board NTC sensor	
Al2 Remote Probes G NTC, D.I. remote Ground GND		Probe not included
Al3 Remote Probes G 420mA/0-10V/0-5V Ground GND		TM171PFE03 Probe not included 12V External power supply
Built-in Al4 RH Sensor On-board RH% sensor		TM171PFE03HR

3.3. M171 Performance protocol connectivity

3.3.1. Example: CAN (Field) network connection

A CAN (Field) network connection can be constituted by:

Max 1 M171 Performance TM171PDM27● functioning as MASTER

Max 12 M171 Performance TM171EP●●R functioning as SLAVES

No more than two M171 Display Graphic (TM171DGRP) can be added to the network connected to M171 Performance TM171PDM27●



The M171 Display Graphic (TM171DGRP) is supplied by TM171PDM27● via the POWER OUT output.

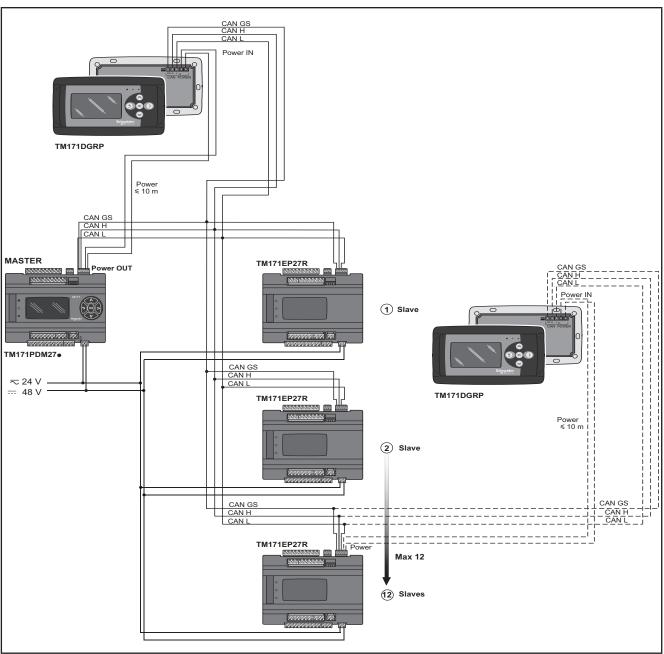


Fig. 26. CAN (Field) network connection using M171 Performance

3.3.2. Example: CAN connection (Network)

A CAN connection (Network) can be constituted by:

1 M171 Performance TM171PDM27•

Max 10 M171 Performance TM171PBM27R connected in CAN (binding)

1 M171 Display Graphic (TM171DGRP) connected in CAN to M171 Performance TM171PDM27● or alternatively, to TM171PBM27R



The M171 Display Graphic (TM171DGRP) is supplied by TM171PDM27● via the POWER OUT output.

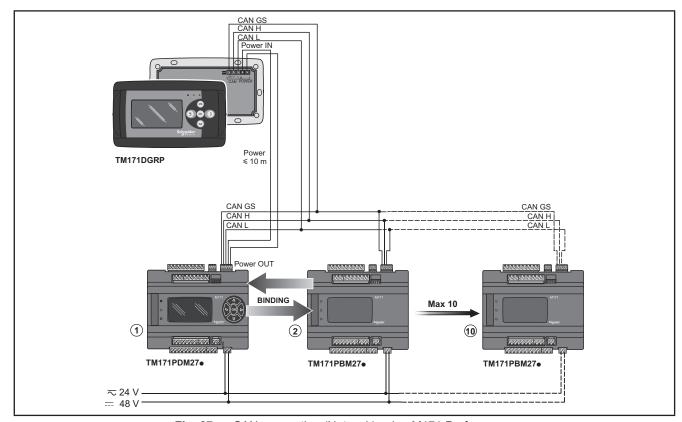


Fig. 27. CAN connection (Network) using M171 Performance

3.3.3. Example: RS485 connection (Field)

A RS485 connection (Field) can be constituted by:

1 M171 Performance TM171PDM27●	TM171PDM27● is in Modbus RTU Master mode
Max 127 M171 Performance TM171EP27R expansion modules connected in RS485	TM171EP27R are in Modbus RTU Slave mode
1 M171 Display Graphic (TM171DGRP) connected in CAN to M171 Performance TM171PDM27●	-



The M171 Display Graphic (TM171DGRP) is supplied by TM171PDM27● via the POWER OUT output.

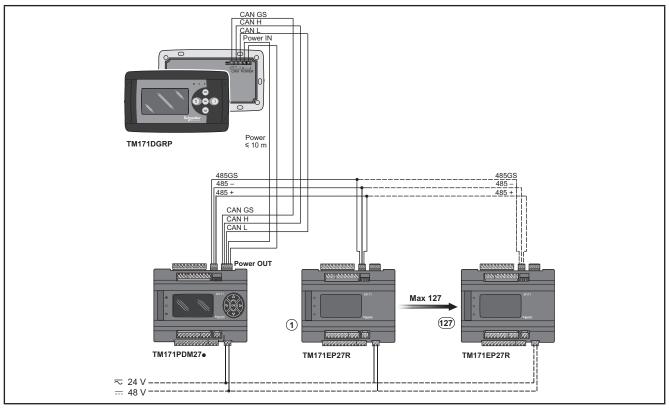


Fig. 28. RS485 connection (Field) using M171 Performance

3.3.4. Example: RS485 connection with the Modicon M171O network

A RS485 connection with the **Modicon M1710** network can be constituted by:

M171 Performance TM171PDM27●	TM171PDM27● is in Modbus RTU Master mode
Max 127 M171 Performance TM171PDM27● / TM171PBM27R or Modicon M171O (TM171O●M●●R / TM171ODM22S) (Modbus Slave) or Schneider Electric and/or third-party instruments equipped with RS485 serial	All devices equipped with RS485 are in Modbus RTU Slave mode (including the M171 Performance modules) See also the Modicon M1710 manual for further details.
CAN network – see 3.3.1. Example: CAN (Field) network connection on pag. 40.	The CAN connection can be • Field, as illustrated • Network, if one or more M171 Performance TM171PDM27 ● / TM171PBM27Rs are connected
1 M171 Display Graphic (TM171DGRP) connected in CAN to M171 Performance TM171PDM27●	-



The M171 Display Graphic (TM171DGRP) is supplied by TM171PDM27● via the POWER OUT output.

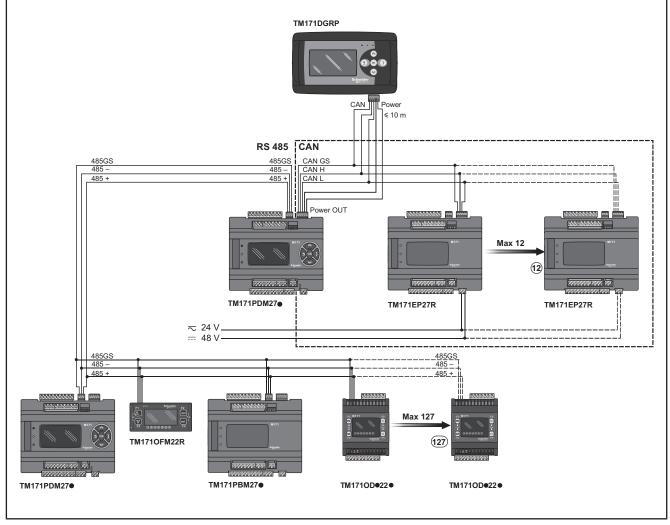


Fig. 29. RS485 connection with the Modicon M171O network using M171 Performance

3.4. M171 Performance Flush protocol connectivity

3.4.1. Example: RS485 connection (Field)

A RS485 connection (Field) can be constituted by:

1 M171 Performance Flush	M171 Performance Flush is in Modbus RTU Master mode
Max 127 M171 Performance TM171EP27R expansion modules connected in RS485	TM171EP27R are in Modbus RTU Slave mode

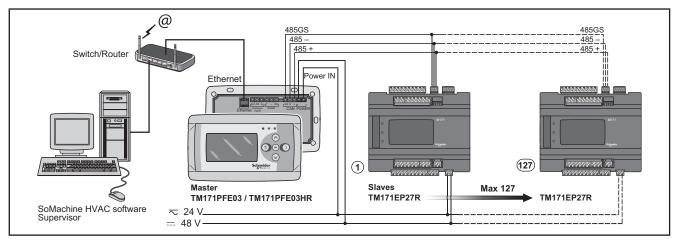


Fig. 30. RS485 connection (Field) using M171 Performance Flush

3.4.2. Example: CAN connection

A CAN connection can be constituted by:

1 M171 Performance Flush Max 12 M171 Performance TM171EP●●R expansion modules connected in CAN

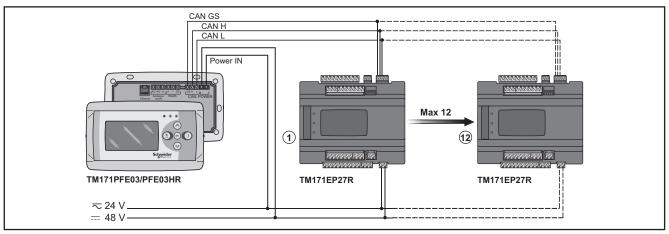


Fig. 31. CAN connection using M171 Performance Flush

3.4.3. Example: RS485 connection with the Modicon M171O network

A RS485 connection with the ${\bf Modicon~M1710}$ network can be constituted by:

1 M171 Performance Flush	M171 Performance Flush is in Modbus RTU Master mode
Max 127 M171 Performance TM171PDM27● / TM171PBM27R or Modicon M171O or Schneider Electric and/or third-party instruments equipped with RS485 serial	All devices equipped with RS485 are in Modbus RTU Slave mode (including the M171 Performance modules) See also the Modicon M1710 manual for further details.
CAN network	see 3.4.2. Example: CAN connection on pag. 45

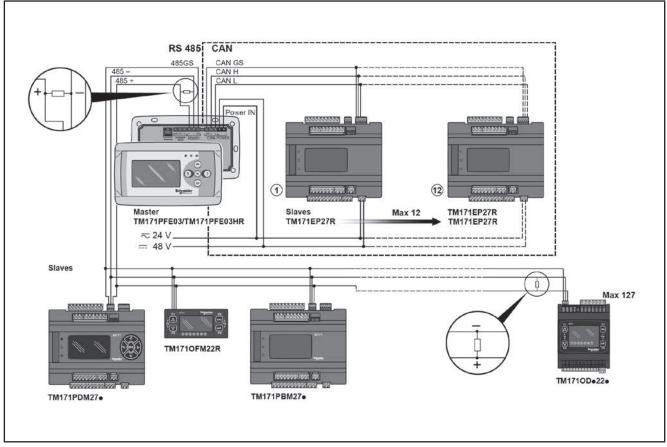


Fig. 32. RS485 connection with the Modicon M171O network using M171 Performance Flush

3.4.4. Example: CAN network connection

A CAN network connection can be constituted by:

1 M171 Performance Flush
Max 10 M171 Performance TM171PDM27● / TM171PBM27R
CAN network: see 3.4.2. Example: CAN connection on pag. 45

HMI menu

M171 Performance Flush can be equipped with its own menu (named Network menu).

In this case M171 Performance Flush logic controller is programmed with the network menu, which can read variables present in the M171 Performance logic controller network.

M171 Performance Flush logic controller can operate from the individual controllers and download up to 10 remote menus from the respective M171 Performance logic controllers.

In this case the remote menu allows 'local' navigation of the individual M171 Performance logic controller.

PLC

The variables of the various controllers are shared (bound together).

A PLC present on **M171 Performance Flush** logic controller can use variables present in the network and share its own variables with other PLCs present on the respective **M171 Performance logic controllers**.

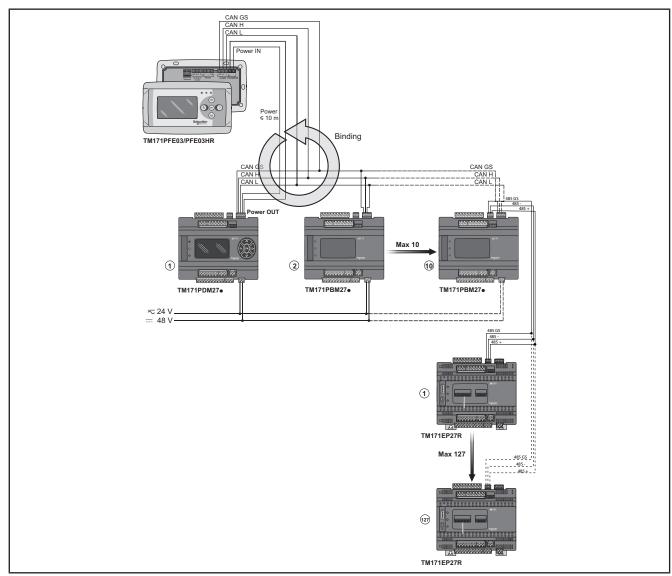


Fig. 33. CAN network connection using M171 Performance Flush

3.5. TM171A ● ● ● plug-in (M171 Performance only)

Plug-ins are 2DIN modules that connect to a M171 Performance TM171PDM27• / TM171PBM27R controller or to an TM171EP••R expansion (*) via the plug-in connector on the left side of the controller, behind the removable flap. The plug-in is anchored to the controller with the fixing screws.

It mounts to the DIN rail in the same way as the controller.

(*) See next table "TM171A•••• vs TM171EP••R".

Interface for	Plug-in	
RS232	TM171ARS232	5A SPDT relay available

Interface for	Plug-in	
RS485	TM171AMB TM171ARS485 TM171AETHRS485	Double RS485 network in parallel**
CAN	TM171ACAN	Double CAN network in parallel**
ETHERNET	TM171AETH TM171AETHRS485	The MACADDRESS is supplied in the box, Expressed as barcode and 12-digit alphanumeric code. The Ethernet connector shield is connected internally to the instrument ground, and therefore to the reference of the input and output channels
		FREE WEB: WEB functionalities of M171 Performance TM171PDM27● or TM171PBM27R + TM171AETH/ TM171AETHRS485 Plug-in
PROFIBUS	TM171APBUS Profibus DP Slave-V0	Contact your local Schneider Electric representative for more information concerning the .GSD Profibus configuration file
		See official Profibus documentation for more detailed information

^{**} A shielded cable is recommended. See 3.1.6. Serial connections on pag. 27.

Plug-in **TM171A••••** are shown below Powered by **M171 Performance**.

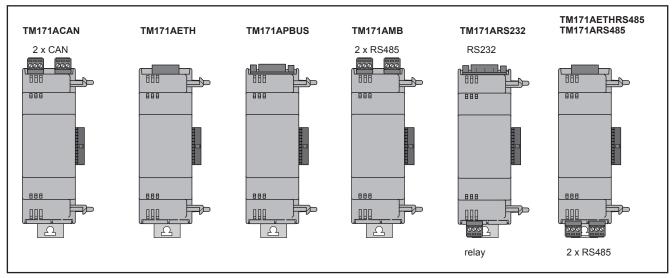
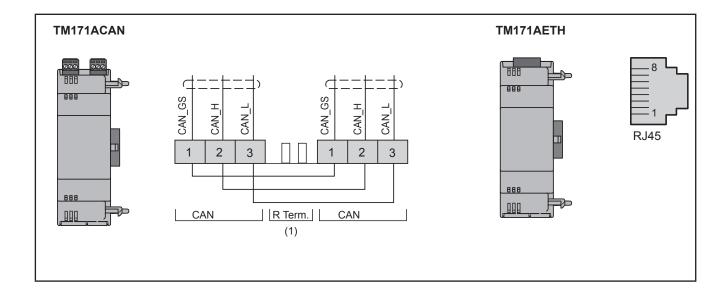


Fig. 34. Plugins



(1) CAN terminal resistance.

Fig. 35. CAN, ETHERNET plug-ins

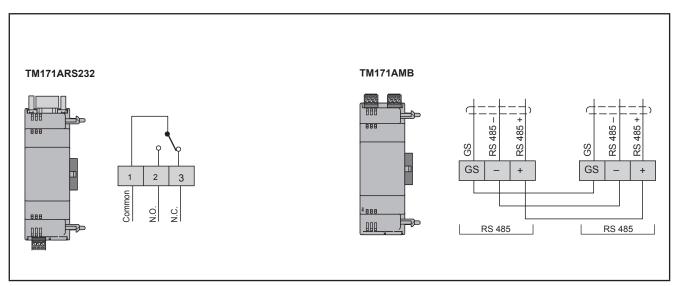


Fig. 36. RS232, RS485 plug-ins

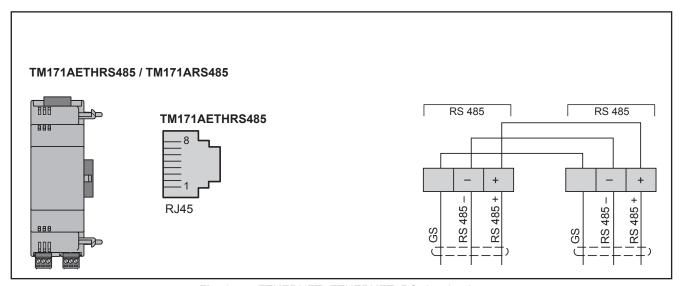
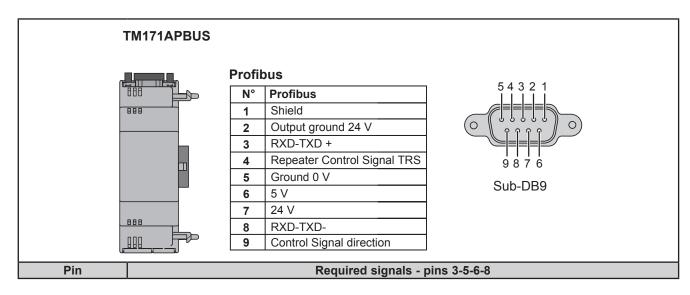


Fig. 37. ETHERNET, ETHERNET+RS485 plug-ins



1	Shield To be connected externally to the protective earth
2	24V output ground
3	RXD-TXD +
4	RTS repeater control signal direction
5	Digital ground
6	5V
7	24V
8	RXD-TXD -
9	Direction control signal ground

Fig. 38. PROFIBUS plug-in

NOTE: In a network with Profibus plug-in modules, the first and last element in the network must terminate with standard Profibus resistors.

TM171A•••• vs TM171EP••R

Plug-ins can be connected to an **TM171EP●●R expansion** with certain restrictions. See the table below:

Plug-in	Connection to TM171EP●●R
TM171ARS232	Modbus RTU Slave only. Connection to modem (Modbus ASCII) not possible
TM171AMB TM171ARS485	SLAVE only
TM171AETH TM171AETHRS485	NO
TM171ACAN	SLAVE only. CAN On-Board serial NOT usable
TM171APBUS	NO

3.5.1. TM171ARS232

The RS232 plug-in allows M171 Performance TM171PDM27• / TM171PBM27R to communicate with an RS232 serial.

Modbus RTU communication protocol

The connection allows:

- · connection to a supervision system using the Modbus RTU protocol
- connection of an IEC 61131-3 TM171SW (SoMachineHVAC) development system

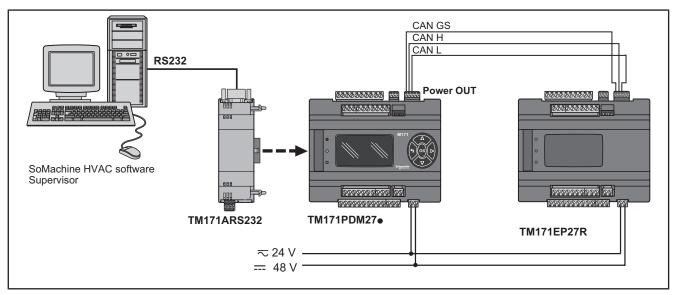


Fig. 39. Modbus RTU communication protocol using TM171ARS232

Modbus ASCII communication protocol send/receive AT commands for modem⁽¹⁾.

This protocol activates when there is a modem connected to the plug-in.

The connection allows:

- connection to a monitoring system using the Modbus ASCII protocol;
- connection of an IEC 61131-3 TM171SW (SoMachineHVAC) * development system;
- send/receive TXT messages via a modem connected to the RS232⁽²⁾ port.
- * The plug-in has a relay that can be piloted from the IEC application to allow the modem to be activated/reset or as an additional digital output.
- (1) Refer to the Modem_IEC.pll software library in
- C:\<Programs>\Schneider Electric\SoMachineHVAC\Catalog\FreeEvolution\PLC
- (2) Refer to the SMS_IEC.pll software library in
- C:\<Programs>\Schneider Electric\SoMachineHVAC\Catalog\FreeEvolution\PLC

See TM171SW (SoMachineHVAC) Manual for details.

NOTE:

Refer to the section on Parameters / RS232 PASSIVE PLUG-IN folder (see **CHAPTER 9 Parameters on pag. 105**). Refer to the section on Parameters / MODEM folder (see **CHAPTER 9 Parameters on pag. 105**).

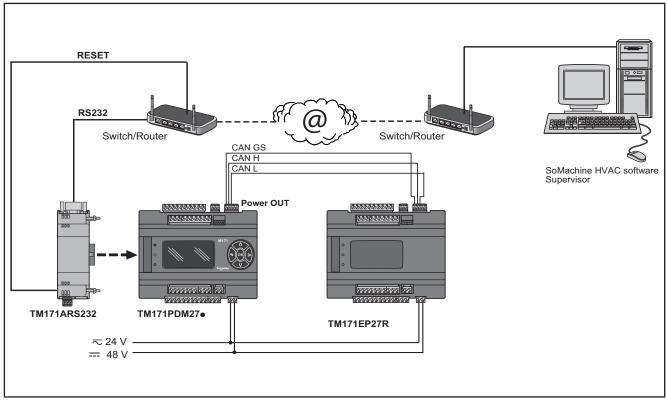


Fig. 40. Modbus ASCII communication protocol using TM171ARS232

3.5.2. TM171AETH

- network connection of different controllers and/or applications exchanging variables and/or parameters (network)
- · connection to a supervision system using the Modbus TCP protocol
- connection of an IEC 61131-3 TM171SW (SoMachineHVAC) development system

NOTE

The MAC ADDRESS (<u>barcode and 12-digit alphanumeric code</u>) is supplied in the box containing the Ethernet plug-in. Refer to the section on Parameters / ETHERNET PASSIVE PLUG-IN folder (see **CHAPTER 9 Parameters on pag. 105**).

NOTE: The Ethernet connector shield is connected internally to the functional ground, and therefore to the reference of the input and output channels. Care must be taken to the fact there may be within the Ethernet communications system other grounding points. Interconnection of multiple protective earth grounding points in the same installation can cause current loops and voltage shifts across conductive parts of the equipment.

WARNING

UNINTENDED EQUIPMENT OPERATION

Do not connect the connector shield to protective earth (PE) or to functional earth (FE) of your installation.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

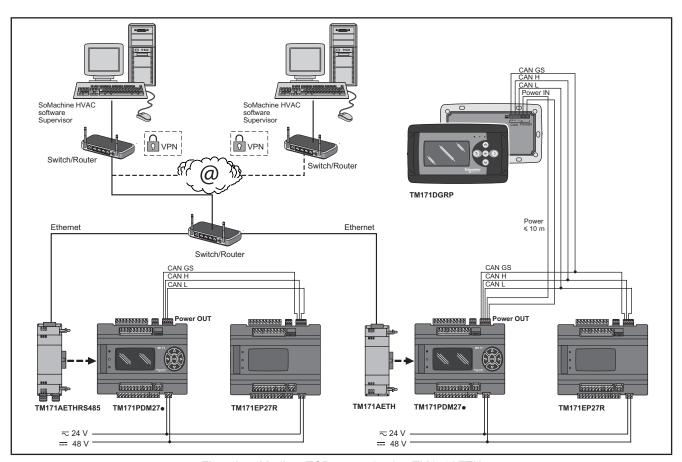


Fig. 41. Modbus TCP protocol using TM171AETH



VPN is not necessary when using DynDNS connection.

Protocol	Field	Network
Modbus TCP	-	Max 10 M171 Performance + 2 M171 Display Graphic (TM171DGRP) Max Modbus Messages = 128 / no. M171 Performance connected

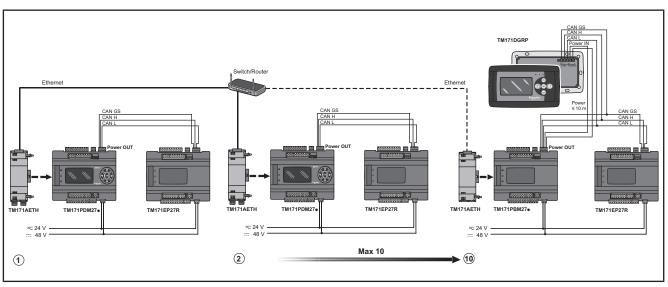


Fig. 42. Modbus TCP protocol using TM171AETH - limits

FREE WEB

FREE WEB is a M171 Performance TM171PDM27 • / TM171PBM27R + TM171AETH Plug-in.

The Ethernet plug-in also uses HTTP protocol, i.e. allowing access to a Web Server contained in M171 Performance.

TM171SW (SoMachineHVAC) allows the creation and management of web pages internally of FREE WEB, i.e. a veritable website in miniature.

WEB functionalities allow complete local or remote access by way of an ordinary browser. Thanks to the web connection, the system provides remote reading and support and remote diagnostics services, as well as e-mail alarm alerts.

Connection to FREE WEB remains possible by way of TM171SW (SoMachineHVAC).



Refer to the section on Parameters / ETHERNET PASSIVE PLUG-IN folder (see **CHAPTER 9 Parameters on pag. 105**).

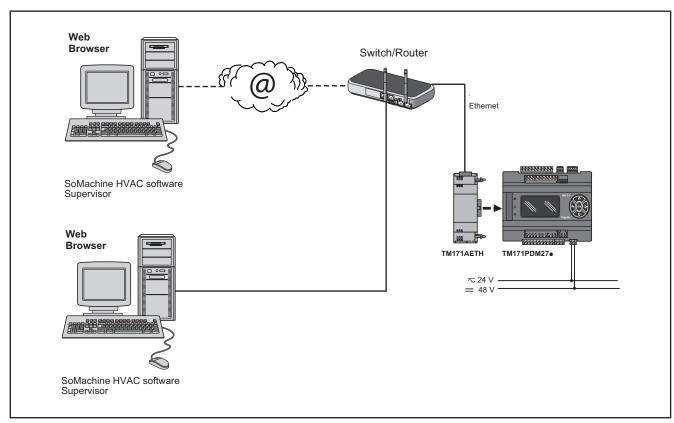


Fig. 43. FREE WEB using TM171AETH

BRIDGE

TM171SW (SoMachineHVAC) allows monitoring of the Modicon M171O tools or third party tools, typically Modbus/RTU slaves, where FREE WEB (or M171 Performance with TM171AETH Plug-In) is the Master Modbus/RTU.

In a **TM171SW** (**SoMachineHVAC**) project, more exactly, **FREE WEB** is used as a Modbus/TCP to Modbus/RTU protocol conversion element for Modbus 0x03 and 0x10 commands.

E.g. from **TM171SW** (**SoMachineHVAC**), set the connection with the **Modicon M171O** as Modbus/TCP, inserting the **FREE WEB** IP address and the Modbus/RTU address of the **Modicon M171O** slave.

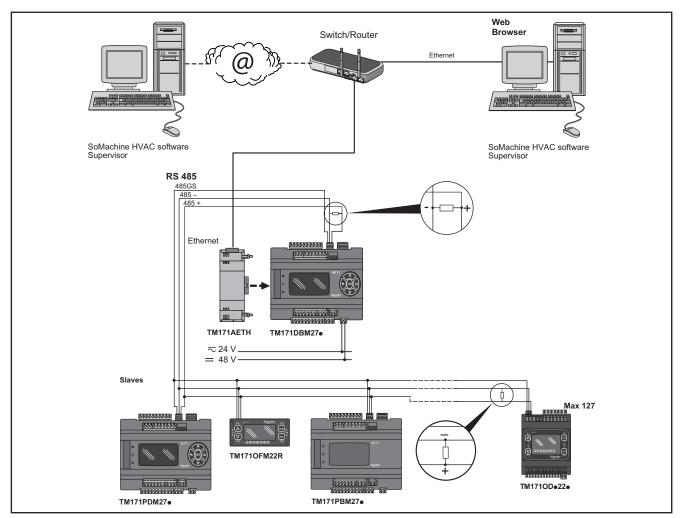


Fig. 44. BRIDGE using TM171AETH

TFTP (Trivial File Transfer Protocol)



TFTP can also be enabled for file transfer between PC and controller on an Ethernet network.

3.5.3. TM171AMB

The RS485 plug-in allows M171 Performance TM171PDM27● / TM171PBM27R to communicate with an RS485 serial using a Modbus RTU Master/Slave communication protocol, in addition to the RS485 serial. The connection allows:

- · connection to a supervision system using the Modbus RTU protocol
- · connection of an IEC 61131-3 TM171SW (SoMachineHVAC) development system
- connection to peripheral Modbus devices (e.g. TM171EP●●R)



The two RS485 serials are interchangeable. **M171 Performance** manages only one of the two as Modbus Master. Both can operate as a Modbus Slave.

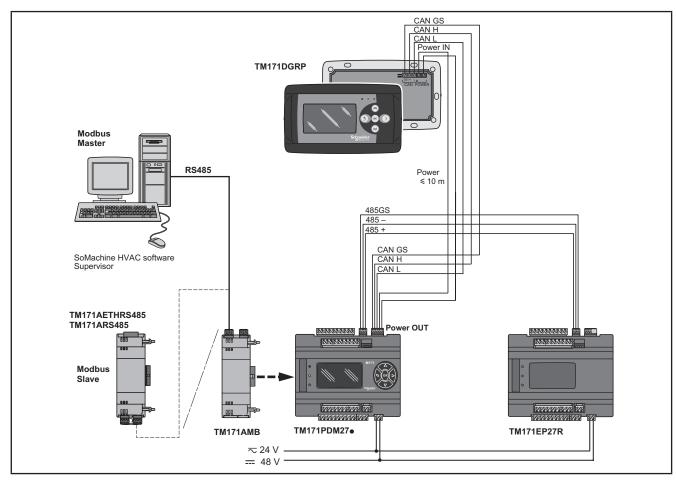


Fig. 45. Modbus RTU protocol using TM171AMB

3.5.4. TM171ACAN

The CAN plug-in allows M171 Performance TM171PDM27• / TM171PBM27R to communicate over a CAN serial using a CAN protocol in addition to the existing CAN serial.

The connection allows:

- · connection to a supervision system using the CAN protocol
- connection of an IEC 61131-3 TM171SW (SoMachineHVAC) development system
- connection to TM171EP●●R expansions
- connection to M171 Display Graphic (TM171DGRP) devices



The two CAN serials are interchangeable. **M171 Performance** manages only one of the two to pilot expansions or third party modules.

Refer to the section on Parameters / CAN PASSIVE PLUG-IN folder (see **CHAPTER 9 Parameters on pag. 105**).

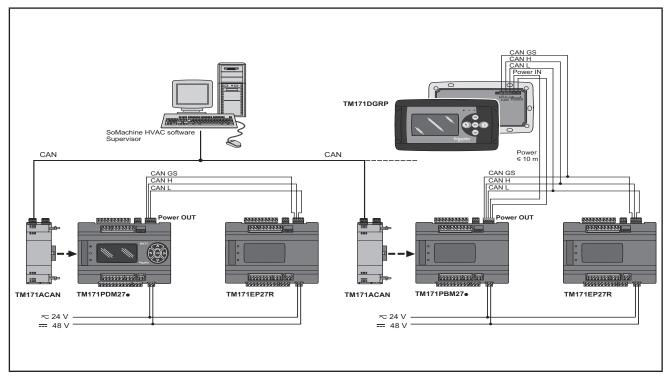


Fig. 46. CAN protocol using TM171ACAN

3.5.5. TM171APBUS

The PROFIBUS plug-in allows M171 Performance TM171PDM27• / TM171PBM27R to communicate over a Profibus serial using the Profibus DP Slave V-0 communication profile.

The connection allows interface with a supervision system or master controller using the Profibus protocol.

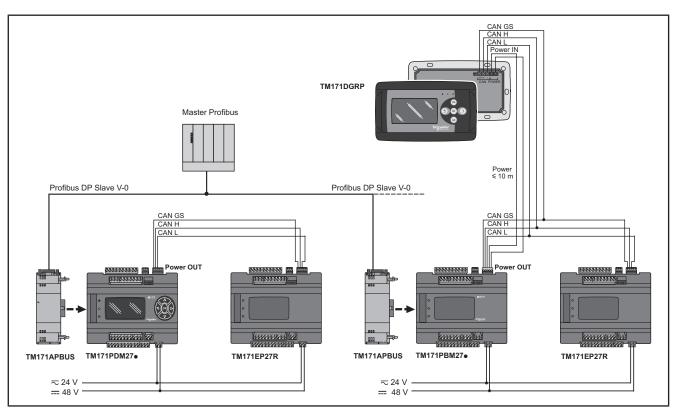


Fig. 47. Profibus protocol using TM171APBUS

3.6. Ethernet connection (for M171 Performance Flush)

The M171 Performance Flush product is also designated FREE WEB

The Ethernet connection also allows communication using HTTP protocol, i.e. access to a Web Server contained in **M171 Performance**.

FREE WEB

TM171SW (SoMachineHVAC) allows the creation and management of web pages internally of FREE WEB, i.e. a veritable website in miniature.

WEB functionalities allow complete local or remote access by way of an ordinary browser. Thanks to the web connection, the system provides remote reading and support and remote diagnostics services, as well as e-mail alarm alerts.



Connection to WEB remains possible by way of TM171SW (SoMachineHVAC).

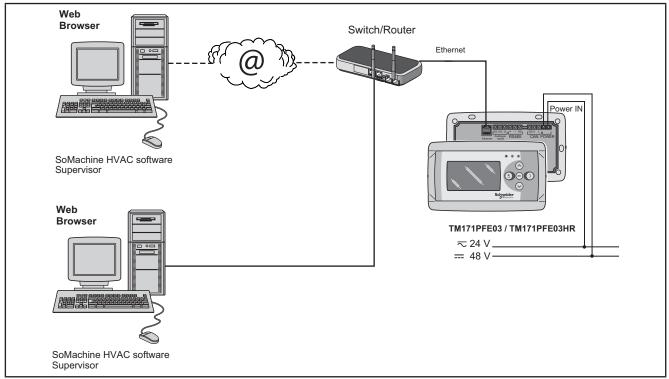


Fig. 48. FREE WEB using M171 Performance Flush

BRIDGE

TM171SW (SoMachineHVAC) allows monitoring of the Modicon M1710 tools or third party tools, typically Modbus/RTU slaves, where FREE WEB (or M171 Performance logic controller with Plug-In TM171AETH) is the Master Modbus/RTU. In a TM171SW (SoMachineHVAC) project, more exactly, FREE WEB is used as a Modbus/TCP to Modbus/RTU protocol conversion element for Modbus 0x03 and 0x10 commands.

E.g. from **TM171SW** (**SoMachineHVAC**), set the connection with the **Modicon M171O** as Modbus/TCP, inserting the **FREE WEB** IP address and the Modbus/RTU address of the **Modicon M171O** slave.

TFTP (Trivial File Transfer Protocol)



TFTP (Trivial File Transfer Protocol) can also be enabled for file transfer between PC and controller on an Ethernet network.

CHAPTER 4

Technical data

All **M171 Performance logic controllers** system components meet European Community (CE) requirements for open equipment. You must install them in an enclosure or other location designed for the specific environmental conditions and to minimize the possibility of unintended contact with hazardous voltages. Use metal enclosures to improve the electromagnetic immunity of your **M171 Performance logic controllers** system. This equipment meets CE requirements as indicated in the table below.

A WARNING

UNINTENDED EQUIPMENT OPERATION

Do not exceed any of the rated values specified within this chapter.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

Applying incorrect current or voltage levels on analog inputs and outputs could damage the electronic circuitry. Further, connecting a current input device to an analog input configure for voltage, and vice-versa, will likewise damage the electronic circuitry.

NOTICE

INOPERABLE EQUIPMENT

- Do not apply voltages above 11 Vdc to the analog inputs of the controller or Input/Output expansion module when analog input is configured as 0-10V input.
- Do not apply current above 30 mA to the analog inputs of the controller or Input/Output expansion module when analog input is configured as 0-20 mA or 4-20 mA input.
- Do not mismatch applied signal with analog input configuration.

Failure to follow these instructions can result in equipment damage.

4.1. General specifications

	Standard	Min	Max
Supply voltage ¹	24V~/ ±20% or by 48V ±20%	21V	60V
Supply voltage TM171EP14R	24V~/ ±10% NOT ISOLATED	20V	38V
Supply frequency	50Hz/60Hz		
Power draw	22VA / 18W (M171 Performance) 10VA / 7W max (M171EP14R) 5W (M171 Performance Flush and M171 Display Graphic)		
Insulation class	2		
Ambient operating temperature	25°C	-10°C	+55°C
Ambient operating temperature of M171 Display Graphic (TM171DGRP)	25°C	-5°C	+55°C
Ambient operating humidity (non-condensing)	30%	10%	90%
Ambient storage temperature	25°C	-20°C	+85°C
Ambient storage humidity (non-condensing)	30%	10%	90%

¹ For M171 Performance Flush / M171 Display Graphic (TM171DGRP): powered by M171 Performance TM171PDM27● / TM171PBM27R or directly from an independent, properly rated power supply.

NOTE: When supplying power from the **M171 Performance logic controllers**, make the power connection cable as short as possible.

NOTICE

INOPERABLE EQUIPMENT

Do not connect a power cable longer than 10m.

Failure to follow these instructions can result in equipment damage.

Classification	
The product meets the requirements of the following European Community Directives:	Directive 2006/95/EC Directive 89/108/EC
It also complies with the following harmonized regulations:	EN 60730-2-6 / EN 60730-2-9 / EN 60730-1
Use	In terms of construction, as an independently mounted temperature-sensitive automatic electronic controller
Mounting	Panel, wall or on DIN Omega bar support
Type of action	1.C – 1.Y
Pollution class	2 (normal)
Over voltage category	II
Nominal pulse voltage	2500V
Digital outputs	refer to the label on the device
Fire resistance category	D
Software class and structure	A
Type of disconnection or suspension for each circuit	Microswitch disconnection
PTI of materials used for insulation	PTI 250V
Period of electrical stress on the insulating parts	Long period

4.2. I/O features

4.2.1. M171 Performance I/O features

M171 Performance features for inputs and outputs.

Type and Label	No.	Description	TM171PDM27R TM171PBM27R TM171EP27R	TM171PDM27S
SELV Digital input DI1DI8	8	8 opto-isolated digital inputs Working voltage 24V~/= ±20% or 48V= ±20% Power draw max. 5mA Digital inputs can be used as pulse counters. The length of the pulse (both positive or negative) must be greater than 12ms. See CHAPTER 8 Physical I/O and ports configuration on pag. 90.	J	J
Digital input FAST DI	1	1 no-voltage digital input (Pulse count + Read frequency) Note: measure a signal with a maximum frequency of 1 KHz See CHAPTER 8 Physical I/O and ports configuration on pag. 90.	J	✓
Relay digital outputs High voltage DO1, DO2	7	2 x 8A 250V~ relays	V	-
Relay digital outputs High voltage DO3DO7	,	5 x 5A 250V~ relays	J	-
Relay digital outputs High voltage DO1, DO2	5	2 x 8A 250V~ relays	-	J
Relay digital outputs High voltage DO5, DO6, DO7	3	3 x 5A 250V∼ relays	-	J
SSR digital outputs High voltage DO3, DO4	2	2 x 1A 250V~ SSR	-	J
SELV Analog outputs 5 AO1AO5		5 x 0-10V / 420mA / ON-OFF configurable outputs: • 010V 2% full scale Min.load 500Ω ; 1% full scale with load greater than $5K\Omega$ • 420mA 2% full scale max. 400Ω • ON-OFF Max.load 400Ω Note: AO4 and AO5 can be configured as Open Collector. See CHAPTER 8 Physical I/O and ports configuration on pag. 90.	J	✓
Analog inputs Al1 Al2 Al3 Al4 Al5 Al6	6	See the following table	V	√

	NTC (NK103) 10kΩ @25°C BETA value 3435	DI	NTC (103AT-2) 10kΩ @25°C BETA value 3435	4-20 mA	0-10 V	0-5 V Ratiometric (*)	PT1000	hΩ (NTC)	daΩ (PT1000)
Al1	J	√	✓	-	-	-	-	-	-
Al2	✓	√	J	-	-	-	-	-	-
AI3	✓	√	J	√	√	\checkmark	\checkmark	√	✓
Al4	\checkmark	✓	J	\checkmark	√	\checkmark	\checkmark	\checkmark	✓
AI5	\checkmark	✓	J	\checkmark	✓	\checkmark	\checkmark	\checkmark	✓
Al6	\checkmark	J	J	\checkmark	√	\checkmark	\checkmark	\checkmark	✓
Range	-40+150°C (-40302°F)		-50°C110°C (-58230 °F)	01000	01000	01000	-200+800°C (-3281472°F)	0 150kΩ	030kΩ
Accuracy	0.5% full scale + 1 digit		0.5% full scale + 1 digit	1% full scale + 1 digit	1% full scale + 1 digit	1% full scale + 1 digit	0.5% full scale + 1 digit	1% full scale + 1 digit	1% full scale + 1 digit
Corrective action	0.1°C		0.1°C	1 digit	1 digit	1 digit	0.1°C	1hΩ	1daΩ
Input impedance	10kΩ	20kΩ	10kΩ	100Ω	21ΚΩ	21ΚΩ	2kΩ	10kΩ	2kΩ

^{(*) 0-5}V Ratiometric. 50mA maximum current @5V



DI: voltage free digital input.



Also see **8.1.1. Analog inputs configuration for M171 Performance on pag. 91** for instructions on offsets and calibrations.

4.2.2. M171EP14R Performance I/O features

M171EP14R Performance features for inputs and outputs.

Type and Label	No.	Description	TM171EP14R
SELV Digital input DI1DI4	4	4 digital inputs NOT ISOLATED Working voltage 24V∼/ ±10% (V∼: max 38V∼) Power draw max. 5mA	√
Relay digital outputs High voltage DO1DO4	4	1 x 5A 250V~ SPDT relay 3 x 3A 250V~ SPST relays (common max 10A)	V
SELV Analog outputs AO1AO2	2	2 x 0-10V outputs: 4% full scale Min.load 5K Ω ; 2% full scale with load greater than 5K Ω	V
Analog inputs Al1 Al2 Al3 Al4	4 See the following table		V

	NTC (NK103) 10kΩ @25°C BETA value 3435	DI	NTC (103AT-2) 10kΩ @25°C BETA value 3435	4-20 mA	0-10 V	0-5 V (*)	PT1000	hΩ (NTC)	daΩ (PT1000)	PTC (KTY81)
Al1	√	√	√	-	-	-	-	-	-	✓
Al2	✓	V	√	-	-	-	-	-	-	✓
Al3	✓	J	√	√	√	J	J	✓	√	✓
Al4	✓	V	√	√	√	\checkmark	\checkmark	√	√	✓
Range	-50+120°C (-58248°F)		-50°C110°C (-58230 °F)	01000	01000	01000	-100+400°C (-148392°F)	0 150kΩ	030kΩ	-50°C150°C (-58302 °F)
Accuracy	0.5% full scale + 1 digit		0.5% full scale + 1 digit	0.5% full scale + 1 digit	0.5% full scale + 1 digit	0.5% full scale + 1 digit	0.5% full scale + 1 digit	1% full scale + 1 digit	1% full scale + 1 digit	0.5% full scale + 1 digit
Corrective action	0.1°C		0.1°C	1 digit	1 digit	1 digit	0.1°C	1hΩ	1daΩ	0.1°C
Input impedance	10kΩ	20kΩ	10kΩ	<200Ω	>10kΩ	>10kΩ	2kΩ	10kΩ	2kΩ	2kΩ

^(*) Ratiometric. 50mA maximum current @5V



DI: voltage free digital input.



Also see **8.1.1. Analog inputs configuration for M171 Performance on pag. 91** for instructions on offsets and calibrations.

4.2.3. M171 Performance Flush I/O features

M171 Performance Flush features for inputs.

Type and Label Analog inputs	Probe	Description	Resolution	Accuracy	Measurement range	Impedance	TM171PFE03	TM171PFE03HR
Al1	On-board	NTC	0.1°C/°F	0.5% f.s. + 1 digit		10ΚΩ	✓	✓
	Remote	NTC 103AT	0.1°C/°F	0.5% f.s. + 1 digit	-50+110 °C (-58230°F)	10ΚΩ		
Al2 configurable	NOT included	NTC NK103	0.1°C/°F	0.5% f.s. + 1 digit	-40+150 °C (-40302°F)	10ΚΩ	✓	✓
	iriciaaca	D.I.**				20ΚΩ		
	Remote	420mA	1 digit	1% f.s. +1 digit	01000	100Ω	√	
AI3		0-5V*	1 digit	1% f.s. +1 digit	01000	21ΚΩ		
configurable	NOT included	010V	1 digit	1% f.s. +1 digit	01000	21ΚΩ		
Al4	On-board	On-board %RH input	0.01%RH (0%=0pt, 100% = 1000pt)	±3% [2080%] ±5%elsewhere	0-100 %RH			V

^{*50}mA maximum current @5V. **Clean contact.



Also see **8.1.2.** Analog inputs configuration for M171EP14R on pag. 92 for instructions on offsets and calibrations.

4.3. Display

M171 Performance TM171PDM27● references, remote display and M171 Performance Flush:

- · backlit with LEDs +
- 3 LEDs



LEDs and backlighting can be controlled from IEC application.

4.3.1. M171 Display Graphic (TM171DGRP) / M171 Performance Flush display

Display	Monochromatic LCD graphic display 128x64px backlit with LEDs
Container	Backplate + frame in PC+ABS UL94 V-0 plastic resin, transparent polycarbonate front cover, polyester membrane keypad

4.4. Serials

Serial	Description	Notes	References
		max50m@500kpbs; 200m@125kpbs	
CAN	Opto-isolated CAN serial	2 jumpers available for CAN terminal resistance	TM171P•••• TM171EP••R
		TM171EP14R 2 dip-switch available for CAN terminal resi- stance	M171 Display Graphic (TM171DGRP)
RS485	Opto-isolated RS485 serial	Pay special attention when con- necting serial lines: do not cable RS485 in CAN port or vice versa	TM171P•••• TM171EP27R
USB	1 type A female USB con- nector (Host)	'Mass Storage' profile External memory, FAT32 format-	TM171P••••
000	1 type B mini USB female connector (Device)	ting Maximum size managed 2TB	TWITT II COOL
ETHERNET	Modbus TCP/IP ETHERNET port	Pack includes MACADDRESS, in barcode and 12-digit alphanumeric format	M171 Performance Flush

4.4.1. TM171A●●●● plug-in (for M171 Performance)

	Serial	Notes	Terminals
TM171ARS232	RS232 Nullmodem	Digital outputs 1 x SPDT 5A 250V∼ relay	terminals 13 screw type* removable, spacing 5, 90° insertion for cables with 2.5 mm² cross-section. + DB9 connector
TM171ACAN	Double serial port	Opto-isolated CAN serial	removable screw type *, spacing 3.81, 90° insertion for cables with 2.5 mm² cross-section.
TM171AMB	Double serial port	Opto-isolated RS485 serial	
TM171AETH	Modbus TCP ETHERNET port	MPBUS serial to pilot up to 8 Belimo actuators	RJ45 connector

^{*} Available spring-loaded from semi-finished product.



Power supply: from TM171PDM27 • / TM171PBM27R base.

4.5. Power supply

The **M171 Performance logic controllers** and associated devices require power supplies with a nominal voltage of 24 Vac / 24 Vdc or 48 Vdc. The power supplies/transformers must be rated Safety Extra Low Voltage (SELV) according to IEC 61140. These sources of power are isolated between the electrical input and output circuits of the power supply as well as simple separation from ground (earth), PELV and other SELV systems.

A A DANGER

GROUND LOOP CAUSING ELECTRIC SHOCK AND/OR INOPERABLE EQUIPMENT

- Do not connect the 0 V power supply/transformer connection supplying this equipment to any external ground (earth) connection.
- Do not connect any 0 V or ground (earth) of the sensors and actuators connected to this equipment to any external ground connection.
- If necessary, use separate power supplies/transformers to power sensors or actuators isolated from this equipment.

Failure to follow these instructions will result in death or serious injury.

If the specified voltage range is not maintained, or the effective separation of the SELV circuit connected to the concerned equipment is compromised, the products may not function as intended or may become damaged and inoperable.

A WARNING

POTENTIAL OF OVERHEATING AND FIRE

- · Do not connect the equipment directly to line voltage.
- · Use only isolating SELV power supplies/transformers to supply power to this equipment.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

The equipment must be connected to a suitable power supply/transformers with the following features:

Primary voltage	Depending on requirements of the individual device and/or country of installation.
Secondary voltage	24 V~/ or 48 V ±20%
Power supply frequency V~	50/60Hz
Power	18W min. (M171 Performance), 5W min. (M171 Performance Flush)

4.6. Mechanical dimensions

	Length (L) mm	Depth (d) mm	Height (H) mm	Notes
M171 Performance TM171PDM27● / TM171PBM27R / TM171EP27R	140	61.6	110	1
M171 Performance TM171EP14R	70	61.6	87	1
TM171A•••• PLUG-IN	35	61.6	110	1
M171 Display Graphic (TM171DGRP) (Hole for panel-mounting)	160 (68)	10 (/)	96 (138)	/ (+0.2mm / -0.1mm)
M171 Performance Flush (Hole for panel-mounting)	160 (68)	10 (/)	96 (138)	/ (+0.2mm / -0.1mm)

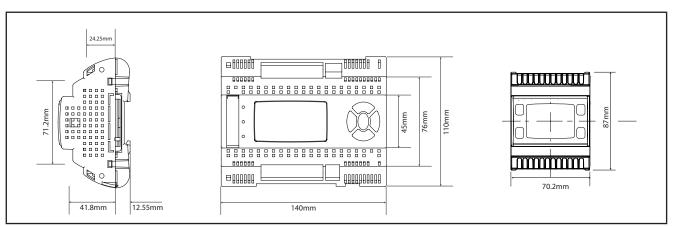


Fig. 49. TM171PDM27● / TM171PBM27R / TM171EP27R / TM171EP14R

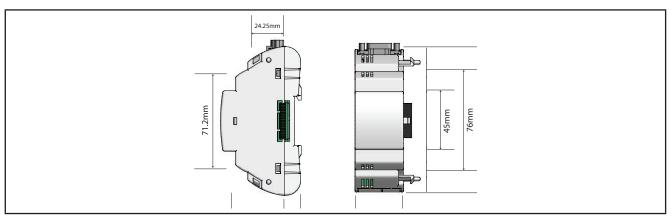


Fig. 50. TM171A••••

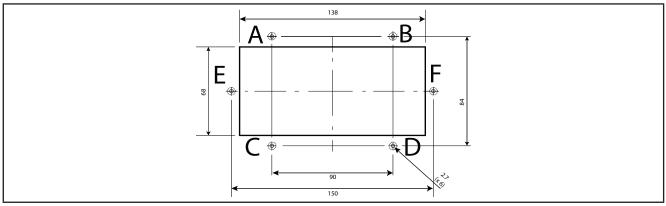


Fig. 51. Cut out M171 Performance Flush

CHAPTER 5

M171 Performance User interface

The interface, comprising the front cover of the controller, allows you to perform all operations needed to use the device.

5.1. TM171PDM27 • Keys and LEDs

The data provided refers to TM171PDM27● references.



The TM171PBM27R module has no display. Use the M171 Display Graphic (TM171DGRP) to work on the device.

The TM171EP •• R expansion module has no display.

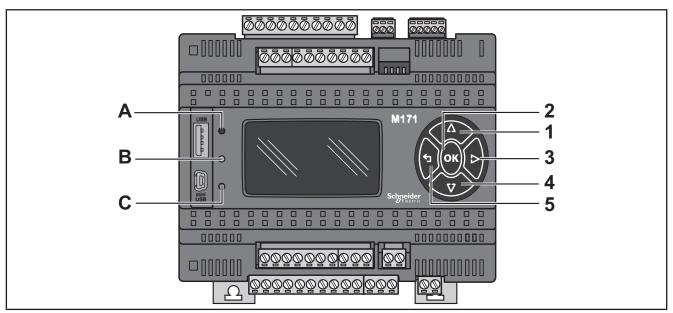


Fig. 52. TM171PDM27●

The keys can be programmed from the IEC application. By default, the device displays a short menu containing the following default settings.

No.	Key	Press once (press and release)
1	Δ UP	Scroll upIncrease/modify a valueGo to next label
2	ок	 Scroll down Move to next level/menu (open folder, subfolder, parameter, value) Enter/exit edit mode Confirm operation
3	RIGHT ⊳	Move cursor to right in Edit Mode
4	DOWN ♡	Scroll downDecrease/modify a valueGo to previous label
5	Exit	 Exit menu page / go back to previous menu Move cursor to left in Edit Mode (press and hold) Exit Edit Mode without saving

The LEDs can be programmed from the IEC application.



By default, they are used for USB management - see the relative section on USB-Handling (see **3.1.6. Serial connections on pag. 27**).

LEDs	Description
ABC	ABC programmable via IEC application

5.2. First power on

When the instrument is powered on for the first time, a few summary pages are displayed showing system status (SYSTEM INFO).

SYSTEM INFO		
HW		
BIOS		
DATE		
BOOT		
EEPROM		

NOR FLASH	OK
NAND FLASH	OK
SDRAM	OK
BATRAM	OK
RTC	OK
Plug-in	None
USB-H	OK
USB-D	Service area

5.3. Menu

M171 Performance has a minimal system menu to configure inputs/outputs, display I/O values and USB operations where present (TM171PDM27● references).



The User interface is available in English only.

5.3.1. System Menu

System Menu
BIOS Configuration
BIOS I/O Values
BIOS RTC Values
USB-Host Handling

5.3.2. BIOS Configuration

Parameter configuration menu. See CHAPTER 9 Parameters on pag. 105.

BIOS Configuration		
Analog Input		
Analog Output		
On-board RS485		
On-board CAN		

The table below lists the parameters that can be configured from the LCD display (TM171PDM27● reference) and/or M171 Display Graphic (TM171DGRP).

The menu for parameter configuration is **System Menu > BIOS Configuration**.

BIOS Configuration	Parameter Folder
Analog Input	ANALOG INPUTS
Analog Output	ANALOG OUTPUTS V/I
On-board RS485	On-board RS485
On-board CAN	On-board CAN

5.3.3. BIOS I/O Values

Shows input (read only) and output values (modifiable).

BIOS I/O Values		
Analog Input		
Analog Output		
Digital Output		
Digital Input		

Inputs are read only. Digital input example:

Digital Input		
DI1 Off	DI5 Off	
DI2 Off	DI6 Off	
DI3 Off	DI7 Off	
DI4 Off	DI8 Off	

The analog and digital outputs are modifiable.

Move the cursor to the resource required.

Press the **OK** key to enter Edit Mode. Use the **UP** and **DOWN** keys to modify value. Confirm with the **OK** key. Analog output example.

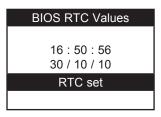
Analog Output 1/2		
AO1	0.2	%
AO2	0.0	%
AO3	0.0	%
V Prev		Next ^

Digital Output example.

Digital Output		
DO1 On	DO5 Off	
DO2 Off	DO6 Off	
DO3 Off	DO7 Off	
DO4 Off		

5.3.4. BIOS RTC Values

Shows time (HH: MM: SS) and date (DD/MM/YY) internal clock.



Press **OK**.

Select the value that you want to modify.

Press the **OK** key to enter Edit Mode. Use the **UP** and **DOWN** keys to modify value. Confirm with the **OK** key. Go to RTC "Update" and press **OK** to update the clock.

BIOS RTC Values
47 . 50 . 50
17 : 50 : 56 31 / 10 / 10
RTC update

5.3.5. USB-Host Handling

For references with USB only (TM171PDM27•): This menu provides options to work on project files.



Type A USB (HOST) - USB memory key.

USB-Host Handling
USB--> M171 PERFORMANCE
M171 PERFORMANCE--> USB

NOTE: Only use one USB connection at a time.

Menu description

M171 PERFORMANCE --> USB

Menu that allows you to download parameters to the USB memory key.

This should only be done for BIOS parameters:

Parameters

USB -> M171 PERFORMANCE

Menu that allows you to upload parameters, applications and menus from a USB memory key to **M171 PERFORMANCE**. The operation should be done individually for each **TM171SW (SoMachineHVAC)** development file and for BIOS parameters:

- Application
- User Interface
- Connection
- Parameters

Preliminary operations

- 1. Check USB memory key
- · Connect the USB to the PC.
- · Check that it has been FAT32 formatted
- · Select Computer.
- · Right click the external drive.
- · Select Properties and check System File type: FAT32.

2. Create PARAM.DAT file

Use this menu: M171 PERFORMANCE --> USB

- · Connect the USB memory key.
- Select M171 PERFORMANCE --> USB.



Parameters is the only available option.

USB-Host Handling M171 PERFORMANCE-->USB

USB Host -> M171 PERFORMANCE
Parameters



On completion, the USB memory key will contain the PARAM.DAT file.

3. Copy file from M171 PERFORMANCE to PC

Type B mini USB (DEVICE)

Connect M171 Performance to a PC or third party device using a suitable mini USB A/B cable.

This can be done from a PC or other device.

M171 Performance supplies the following files to be copied to PC and then transferred to a USB memory key:

File	Development environment	Description	Note
HMIIEC.COD	User Interface	Menu	Available after M171
PLCIEC.COD	Application	IEC application	Performance has been rebo-
CONNEC.PAR	Connection	Network configuration file	oted

4. UPLOAD.TXT file creation

The UPLOAD.txt file can be created by any text editor with the following contents:

Example: files in UPLOAD.txt

Example UPLOAD.txt	Example 03UPLOAD.txt	
; Application PLCIEC.COD	; Application 03PLCIEC.COD	
; User Interface HMIIEC.COD	; User Interface 03HMIIEC.COD	
; Connection CONNEC.PAR	; Connection 03CONNEC.PAR	
; Parameters PARAM.DAT	; Parameters 03PARAM.DAT	
; User Interface Remote HMIREM.KBD	; User Interface Remote 03HMIREM.KBD	

The remote interface, if available, can also be added to each file.



When more than one M171 Performance is being used, use dipswitches for updating.

File names will be preceded by 00, 01, 02, 03 etc and **M171 Performance** will only load the relative file if it matches the dipswitch setting.

Example: 4 files on USB memory key



The file HMIIEC.COD and 00HMIIEC.COD are identical.

Files on USB	Dipswitch M171 Performance	Description	Note
HMIIEC.COD	00	Parameter file downloaded to M171 Performance	See previous example
00HMIIEC.COD	01	File ignored	
01HMIIEC.COD	01	Parameter file downloaded to M171 Performance	
02HMIIEC.COD	01	File ignored	
02HMIIEC.COD	02	Parameter file downloaded to M171 Performance	

Example: 1 file on USB memory key

Files on USB	Dipswitch M171 Performance	Description	Note
02HMIIEC.COD	01	File ignored	Message "file not present" displayed.

5. Transfer file to USB memory key

The following files will be saved to the USB memory key:

File	Development environment	Description	Note
HMIIEC.COD	User Interface	Menu	The remote interface, if available, can also be added. Available after M171 Performance has been rebooted
PLCIEC.COD	Application	IEC application	Available after M171 Performance has been reboo-
CONNEC.PAR	Connection	Network configuration file	ted
PARAM.DAT	Parameters	Parameters	Type A USB (HOST) Instant update without having to reboot
UPLOAD.TXT	1	"boot" file needed to upload parameters.	The UPLOAD.TXT file must be on the USB memory key

You can now use the following menu:

USB --> M171 PERFORMANCE

- · Connect the USB memory key.
- Select USB -> M171 PERFORMANCE
- · Select the required option.

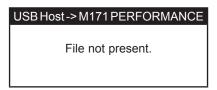
USB-Host Handling		
USB>M171 PERFORMANCE		

USBHost->M171PERFORMANCE Application User Interface Connection Parameters

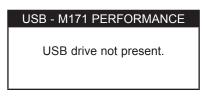
If the action completes successfully, the following screens are shown:



If the file is not found, the following message will be displayed:



If there is no USB memory key, the following message will be displayed:



File management not using the menu

Alternatively, files can be downloaded automatically without using the menu or display (TM171PBM27R reference).

NOTE: The UPLOAD.TXT file must be on the USB memory key (USB drive).

Connect the USB memory key.

The files on the USB memory key will be transferred automatically to M171 Performance.

At the user interface level, the LEDs will behave as follows:

LED		Upload
Red	Flashing 2 seconds	Failed
Yellow	On	Underway
Green	Flashing 2 seconds	Completed successfully

Once all LEDs have gone off, the USB memory key can be removed. Switch off or restart the controller and make the data download effective.

CHAPTER 6 M171 Display Graphic (TM171DGRP) user interface

The interface, comprising the front cover of the controller, allows you to perform all operations needed to use the device.

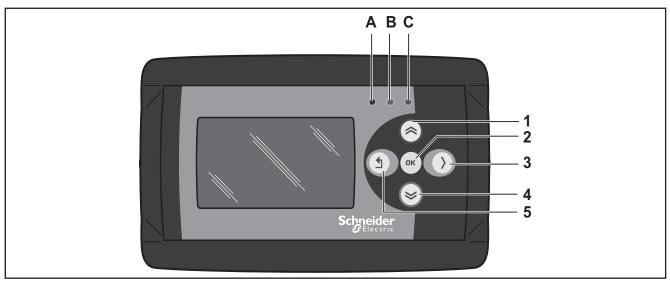


Fig. 53. M171 Display Graphic (TM171DGRP)

6.1. Keys and LEDs

The keys can be programmed from the IEC application. By default, the device displays a short menu containing the following default settings.

No.	Key	Press once (press and release)
	*	 Scroll up Return to previous page (e.g. 1/3 ←2/3)
1	UP	Increase / modify a value Go to next label
		Scroll down
2	ок	Move to next level/menu (open folder, subfolder, parameter, value)
_	J. C.	Enter/exit edit mode
		Confirm operation
3	RIGHT >	Move cursor to right in Edit Mode
		Scroll down
4	DOWN	Move to the next page (e.g. 1/3→2/3)
1	҂	Decrease / modify a value
		Go to previous label
		Exit menu page / go back to previous menu
5	← Exit	Move cursor to left in Edit Mode
		(press and hold) Exit Edit Mode without saving

DIA Menu

M171 Display Graphic (TM171DGRP) is factory-configured with a default DIAGNOSTICS (DIA) menu that appears when the instrument is powered on.

After uploading an IEC application and/or a HMI menu from **TM171SW** (**SoMachineHVAC**), the main display consists of the application menu created with **TM171SW** (**SoMachineHVAC**) Interface.

In which case, to open the DIAGNOSTICS menu proceed as follows:

No.	Key combination	Long press (press and hold for about 3 seconds)
	DOWN	Open DIAGNOSTICS menu
4+5	← Exit	

To return to the IEC application menu, open the "HMI Management" page, select L1 and press the **OK** key. See **6.4. Remote interface on pag. 82**.

The LEDs can be programmed from the IEC application.

LEDs	Description
ABC	ABC programmable via IEC application

6.2. First power on

When the instrument is powered on for the first time, a few summary pages are displayed showing system status (SYSTEM INFO).

SYSTEM INFO
HW
BIOS
DATE
BOOT
EEPROM

NOR FLASH	OK
SDRAM	OK

The system will also search for the PLC application and the local menu... If present, the menu will appear on the display.

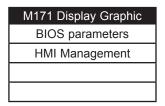
HMI searching	
DIA	

6.3. DIAGNOSTICS menu

The native DIAGONISTICS menu on **M171 Display Graphic** (**TM171DGRP**) allows you to manage system parameters (BIOS parameters) and the interface (HMI).

The DIA menu can be displayed in 5 languages: English, Italian, German, Spanish and French.

To change the default language, open BIOS Parameters > Display.



6.3.1. BIOS parameters

Parameter configuration menu. See CHAPTER 9 Parameters on pag. 105.



This menu is depopulated with respect to the parameters table contained in the corresponding chapter and in the **TM171SW** (SoMachineHVAC) device.

A language change example:

BIOS parameters \rightarrow < **OK** key > Display 1/3 \rightarrow < **OK** key > Edit Mode < **UP/DOWN** key > select language < **OK** key > < \leftarrow key >



See parameter Display/Hmi_Language.

6.3.2. HMI Management

See 6.4. Remote interface on pag. 82.

6.4. Remote interface

M171 Display G	raphic
Language: 0	ĹŢ
HMI Managen	nent

6.4.1. Language

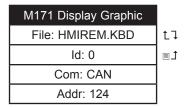
This section is for setting the language of the remote menu, defined from the **TM171SW** (**SoMachineHVAC**) User Interface. The number of languages and the order are established by the corresponding application/menu. See parameter HMI Management/**Hmi_Language** (see **CHAPTER 9 Parameters on pag. 105**).

6.4.2. L↓

To return to the menu of the IEC application, move the cursor onto the 17 symbol and press the **OK** key.

6.4.3. HMI Management

This page shows the configuration of the remote page.

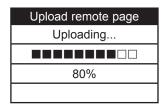


From these pages it is possible to "launch" (run) the corresponding menu – if present. Move the cursor to LI and press the **OK** key.

To "upload" a remote page use ■1

Upload remote page			
Upload page?			
The	process interru	cannot l pted	Эе
Ca	ncel	OK	

Press **OK** to upload or any other key to cancel





The upload may take up to a minute.

If there are no data to upload, the following screen displays

Upload remote page
There are no remote
pages on the card.
Press OK

CHAPTER 7

M171 Performance Flush user interface

The interface, comprising the front cover of the controller, allows you to perform all operations needed to use the device.

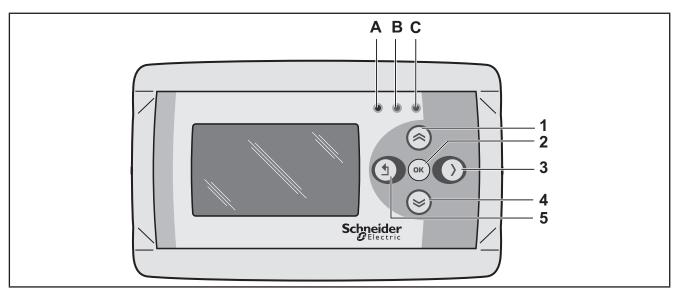


Fig. 54. M171 Performance Flush

The keys can be programmed from the IEC application. By default, the device displays a short menu containing the following default settings.

7.1. Keys and LEDs

No.	Key	Press once (press and release)
		Scroll up
1		• Return to previous page (e.g. 2/10 ← 3/10)
'	UP	Increase / modify a value
		Go to the next label
		Scroll down
2	ок	Move to next level/menu (open folder, subfolder, parameter value)
	OK .	Enter/exit edit mode
		Confirm operation
3	RIGHT >	Moves cursor to right in Edit Mode
		Scroll down
4	DOWN	Move to the next page (e.g. 1/10 → 2/10)
4	×	Decrease / modify a value
		Go to previous label
		Exit menu page / go back to previous menu
5	⊢ ← Exit	Move cursor to left in Edit Mode
		(press and hold) Exit Edit Mode without saving any changes

M171 Performance Flush is factory configured with a default DIAGNOSTICS (DIA) menu that appears when the instrument is powered on.

After uploading of an IEC application and/or a HMI menu from **TM171SW** (**SoMachineHVAC**), the main display consists of the application

menu created with TM171SW (SoMachineHVAC) Interface.

In which case, to open the DIAGNOSTICS menu proceed as follows:

Key combination		Prolonged press (press and hold for about 3 seconds)
	DOWN	
4+5	←	Open DIAGNOSTICS menu
	Exit	

The LEDs can be programmed from the IEC application.

LEDs	Description
ABC	ABC programmable via IEC application

To return to the IEC application menu open the 'HMI Management' page (7.3.2. HMI management on pag. 86), select tl and press the **OK** key.

See 7.4. Remote interface on pag. 88.

7.2. First power on

When the instrument is powered up for the first time, a few summary pages are displayed showing system status (SYSTEM INFO).

SYSTEM INFO
HW
BIOS
DATE
BOOT
EEPROM

NOR FLASH	OK
NAND FLASH	OK
SDRAM	OK
BATRAM	OK
RTC	OK

The system will also search for the PLC application and the local menu... If present, the menu will appear on the display

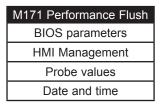
PLC searching	
HMI searching	
CON	loaded

7.3. DIAGNOSTIC menu

The DIAGONISTICS menu, native to **M171 Performance Flush**, is used to manage system parameters (BIOS parameters), remote interfaces (HMI) and to display I/O values and clock.

The DIA menu can be displayed in 5 languages: English, Italian, German, Spanish and French.

To change the default language, open BIOS Parameters > Display



7.3.1. BIOS parameters

For Parameter configuration menu, see CHAPTER 9 Parameters on pag. 105.



This menu is depopulated with respect to the parameters table contained in the corresponding chapter and in the **TM171SW** (SoMachineHVAC) device.

A language change example:

BIOS parameters \rightarrow < **OK** key > Display 1/3 \rightarrow < **OK** key > Edit Mode < **UP/DOWN** key > select language < **OK** key > < \leftarrow key >



See parameter Display/Hmi Language.

7.3.2. HMI management

See 7.4. Remote interface on pag. 88.

7.3.3. Probe values

Shows input values (read only).

M171 Performance Flush has 3 inputs.

A TM171PFE03HR example:

Probes values	1/3
Internal NTC	
27.3	
°C, °F	

Probes values	2/3
External NT	С
°C, °F	

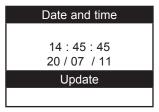
Probes values	3/3
Humidity sens	or
43.38	
RH%	



For offset programming see 8.1.2. Analog inputs configuration for M171EP14R on pag. 92.

7.3.4. Date and time

Shows time (HH: MM: SS) and date (DD/MM/YY) of the internal clock.



To edit the value press **OK**. Select the value that you want to modify. Press the **OK** key to enter Edit Mode. Use the **UP** and **DOWN** keys to modify value. Confirm with the **OK** key. Select 'Update' and press **OK** to update the clock.

Date and time
16 : 50 : 56 20 / 07 / 11
Update

7.4. Remote interface

M171 Performance	e Flush
Language: 0	ĹŢ
HMI sel: Netw	ork
COM setting	
HMI Management	

7.4.1. Language

This section is for setting the language of the remote menu, defined from the **TM171SW** (**SoMachineHVAC**) User Interface. The number of languages and the order are established by the corresponding application/menu. See parameter HMI Management/**Hmi_Language**.

7.4.2. L ↓

To return to the menu of the IEC application, move the cursor onto the LI symbol and press the **OK** key. See **7.4.3. HMI sel on pag. 88**.

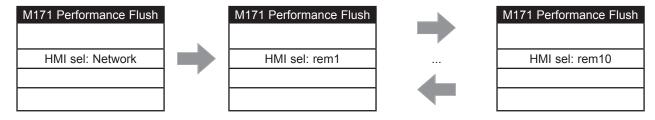
7.4.3. HMI sel

This section is for setting the menu to be shown on the display.

By default HMI menus are NOT present (only the DIA menu is available).

Network: this is the M171 Performance Flush 'local' menu (local HMI).

rem1...rem10: menus located on max 10 M171 Performance devices connected to the network that can be 'uploaded' to M171 Performance Flush.



To move from one page to the next press the $\bf UP$ and $\bf DOWN$ keys. After selecting the desired menu move the cursor onto $\bf L1$ to view the menu

Launch remote page	
Please Wait	

If OK the display will show the selected menu (IEC application). If the menu is not present, the following screen appears

Warning
Upload failed
Press OK

7.4.4. COM Setting

This **read-only** page shows the configuration of the **M171 Performance Flush** serial ports.

M171 Performance Flush
CAN: 1.500000
485s: 1.38400.P81
ETH: 010.000.000.100

7.4.5. HMI Management

This page shows the configuration of the 10 remote pages.

M171 Performance Flush 1/10	
File: HMIREM.KBD	Ĺ↓
ld: 0	t∎
Com: CAN	
Addr: 125	

	M171 Performance Flush 1/10	
l		ĹŢ
1	ld: 0	€
	Com: CAN	
	Addr: 000	

M171 Performance Flush 10/10	
	ĹŢ
ld: 0	€
Com: CAN	
Addr: 000	

From these pages it is possible to 'launch' (run) the corresponding menu – if present Move the cursor onto 11 and press the **OK** key.



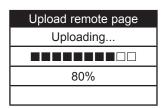
It will not be possible to launch the local (network) menu from this section. In the example only one remote page is present.

To 'upload' a remote page use ■1.

After selecting the desired menu move the cursor onto LI to view the menu.

Up	Upload remote page					
	Upload page?					
The	The process cannot be interrupted					
Ca	ncel	OK				

Press **OK** to upload or any other key to cancel





The upload may take up to a minute.

If there are no data to upload, the following screen displays

	Warning
	There are no remote
ſ	pages on the card
ſ	
	Press OK

CHAPTER 8

Physical I/O and ports configuration

From time to time, new input modules, output modules or other devices are made available that are not documented in the following information. For information on new devices, contact your local Schneider Electric representative.

NOTICE

INOPERABLE EQUIPMENT

Update the controller firmware to the latest version every time you install a newly released Input/Output expansion module or other device to this equipment.

Failure to follow these instructions can result in equipment damage.

NOTE: For more information on how to update the controller firmware, contact your local Schneider Electric representative.

	M171 Performance	M171 Performance Flush
Analog inputs	Configurable by parameter (see 8.1.1. Analog inputs configuration for M171 Performance on pag. 91)	Configurable by parameter (see 8.1.2. Analog inputs configuration for M171EP14R on pag. 92)
Analog outputs	Configurable by parameter (see "8.2. Analog outputs (LOW VOLTAGE - SELV) configuration for M171 Performance")	-
Digital inputs (Low voltage - SELV)	Configurable by parameter (see 8.3. Digital inputs (LOW VOLTAGE - SELV) configuration for M171 Performance on pag. 95)	-
Digital outputs (Low voltage - SELV)	Configurable by parameter (see 8.4. Digital outputs configuration for M171 Performance on pag. 95)	-
Serials	Configurable by parameter (see 9.1.1. M171 Performance parameters on pag. 106) or dip-switch (see 8.5. Ports configuration for M171 Performance using DipSwitch on pag. 96)	Configurable by parameter (see 9.1.2. M171EP14R parameters on pag. 118)

Applying incorrect current or voltage levels on analog inputs and outputs could damage the electronic circuitry. Further, connecting a current input device to an analog input configure for voltage, and vice-versa, will likewise damage the electronic circuitry.

NOTICE

INOPERABLE EQUIPMENT

- Do not apply voltages above 11 Vdc to the analog inputs of the controller or Input/Output expansion module when analog input is configured as 0-10V input.
- Do not apply current above 30 mA to the analog inputs of the controller or Input/Output expansion module when analog input is configured as 0-20 mA or 4-20 mA input.
- Do not mismatch applied signal with analog input configuration.

Failure to follow these instructions can result in equipment damage.

8.1. Analog inputs

M171 Performance and M171 Performance Flush have different analog inputs.

8.1.1. Analog inputs configuration for M171 Performance

There are a total of 6 analog inputs, referred to below as Al1...Al6.

Using the parameters, a physical resource (probe, digital input, voltage/current signal) can be "physically" configured for each type of input:

- 2 inputs can be configured as temperature probes (NTC type probe) or as digital inputs.
- 4 inputs (Al3...Al6) can be configured as temperature probes (NTC or Pt1000), as digital inputs or as a current/voltage input (4-20mA signal/ 0-10V, 0-5V ratiometric).

Inputs can be "physically" configured as specified in the table below.

		Value								
Parameter	Description	0	1	2	3	4	5	6	7	8
Cfg_Al1	Type of analog input Al1	NTC probe (NK103)	Probe configured as voltage-free digital input	NTC probe (103AT)	//	//	//	//	//	//
Cfg_Al2	Type of analog input Al2	NTC probe (NK103)	Probe configured as voltage-free digital input	NTC probe (103AT)	//	//	//	//	//	//
Cfg_Al3	Type of analog input Al3	NTC probe (NK103)	Probe configured as voltage-free digital input	NTC probe (103AT)	4-20 mA (§)	0-10 V (§)	0-5 V Ratiometric (§)	PT1000	hΩ (NTC) (*)	daΩ (PT1000) (**)
Cfg_Al4	Type of analog input Al4	NTC probe (NK103)	Probe configured as voltage-free digital input	NTC probe (103AT)	4-20 mA	0-10 V	0-5 V Ratiometric	PT1000	hΩ (NTC)	daΩ (PT1000)
Cfg_Al5	Type of analog input AI5	NTC probe (NK103)	Probe configured as voltage-free digital input	NTC probe (103AT)	4-20 mA	0-10 V	0-5 V Ratiometric	PT1000	hΩ (NTC)	daΩ (PT1000)
Cfg_Al6	Type of analog input Al6	NTC probe (NK103)	Probe configured as voltage-free digital input	NTC probe (103AT)	4-20 mA	0-10 V	0-5 V Ratiometric	PT1000	hΩ (NTC)	daΩ (PT1000)

(§) 4-20 mA / 0-10V / 0-5 V ratiometric

Minimum full scale Alx

- for current probe, value = 4mA,
- for 0÷10V voltage probe, valore = 0V,
- for ratiometric probe (0÷5V), value = 10% (corresponding to 0.5V)

Maximum full scale Alx

- for current probe, value = 20mA,
- for 0÷10V voltage probe, valore = 10V,
- for ratiometric probe (0÷5V), value = 90% (corresponding to 4.5V)
- (*) Cfg_Alx = 7 Resistance value read, expressed in $h\Omega$, for a resistance applied to the input using the controller in NTC configuration, i.e. creating a divider with pull-up resistance of 10k.
- (**) Cfg_Alx = 8 Resistance value read, expressed in $da\Omega$, for a resistance applied to the input using the controller in PT1000 configuration, i.e. **creating a divider with pull-up resistance of 2k**.

Note: Typically used with potentiometer at input.

The resistance range for the $h\Omega(NTC)$ configuration is up to 150K, and up to 30K for the $da\Omega(PT1000)$ configuration.

Parameter	Range	Description
FullScaleMin_Al3	-9999+9999	Analog input Al3 start of scale value
FullScaleMax_Al3	-9999+9999	Analog input Al3 full scale value
FullScaleMin_Al4	-9999+9999	Analog input Al4 start of scale value
FullScaleMax_Al4	-9999+9999	Analog input Al4 full scale value

Parameter	Range	Description
FullScaleMin_Al5	-9999+9999	Analog input Al5 start of scale value
FullScaleMax_Al5	-9999+9999	Analog input AI5 full scale value
FullScaleMin_Al6	-9999+9999	Analog input Al6 start of scale value
FullScaleMaxAl6	-9999+9999	Analog input Al6 full scale value

The values read by analog inputs can be configured via the following parameters:

Parameter	Description	Measurement Unit	Range	
Calibration_Al1	Analog input Al1 differential	°C/10 or °F/10	-180 180	
Calibration_Al2	Analog input Al2 differential	°C/10 or °F/10	-180 180	
Calibration_Al3	Analog input Al3 differential		-1000 1000	
Calibration_Al4	Analog input Al4 differential		-1000 1000	
Calibration_Al5	Calibration_Al5 Analog input Al5 differential		-1000 1000	
Calibration_Al6	Analog input Al6 differential		-1000 1000	

8.1.2. Analog inputs configuration for M171EP14R

There are a total of 4 analog inputs, referred to below as Al1...Al4.

Using the parameters, a physical resource (probe, digital input, voltage/current signal) can be "physically" configured for each type of input

The inputs are configurable in pairs Al1, Al2 and Al3, Al4

Inputs can be "physically" configured as specified in the table below.

			Value									
Par	Description	0	1	2	3	4	5	6	7	8	9	10
Cfg_Alx	Type of	NTC		NTC	4-20	0-10	0-5 V	PT1000	hΩ	daΩ	PTC	0-5
	analog	probe	DI	probe	mA	V	Ratiometric	1 1 1000	(NTC)	(PT1000)	(KTY81)	0-3 V
x=14	input Alx	(NK103)		(103AT)	(§)	(§)	(§)		(*)	(**)	(K1101)	

DI Probe configured as voltage-free digital input

(§) 4-20 mA / 0-10V / 0-5 V ratiometric

Minimum full scale Alx

- for current probe, value = 4mA,
- for 0÷10V voltage probe, valore = 0V,
- for ratiometric probe (0÷5V), value = 10% (corresponding to 0.5V)

Maximum full scale Alx

- for current probe, value = 20mA,
- for 0÷10V voltage probe, valore = 10V,
- for ratiometric probe (0÷5V), value = 90% (corresponding to 4.5V)
- (*) Cfg_Alx = 7 Resistance value read, expressed in $h\Omega$, for a resistance applied to the input using the controller in NTC configuration, i.e. **creating a divider with pull-up resistance of 10k**.
- (**) Cfg_Alx = 8 Resistance value read, expressed in $da\Omega$, for a resistance applied to the input using the controller in PT1000 configuration, i.e. **creating a divider with pull-up resistance of 2k**.

Note: Typically used with potentiometer at input.

The resistance range for the $h\Omega(NTC)$ configuration is up to 150K, and up to 30K for the $da\Omega(PT1000)$ configuration.

8.1.3. Analog inputs configuration for M171 Performance Flush

Inputs can be configured as specified in the table below.

Parameter	Description		Values					
raiailletei	Description	0	1	2	3	4	5	
Cfg_Al1	Type of input analog Al1	NTC probe (NK103)	Probe configured as voltage-free digital input	NTC probe (103AT-2)	-	-	-	
Cfg_Al2	Type of input analog Al2	NTC probe (NK103)	Probe configured as voltage-free digital input	NTC probe (103AT-2)	-	-	-	
Cfg_Al3	Type of input analog Al3	-	-	-	4-20 mA	0-10 V	0-5 V	

Parameter	Range	Description
FullScaleMin_Al3	-9999+9999	Analog input AI3 start of scale value
FullScaleMax_Al3	-9999+9999	Analog input Al3 full scale value

The temperature and humidity measurement, as well as the corresponding precisions and tolerances, refer to the application point of the probes inside the instruments.

If these same measurements are to be referred to air conditions outside of the instrument, e.g. ambient measurements, account must be taken of offset (differential) parameters that depend on the installation and usage conditions of the instrument itself.

The differentials e.g. Calibration parameters that can be set are

Parameter	Description	Unit of measure	Range
Calibration_Al1	ion_Al1 Analog input Al1 differential		-180 180
Calibration_Al2 Analog input Al2 differential		°C/10 or °F/10	-180 180
Calibration_Al3 Analog input Al3 differential		-	-1000 1000
Calibration_Al4	Analog input Al4 differential	-	-1000 1000

For on-board (built-in) sensors, Compensation parameters are also available

Parameter	Description	Unit of measure	Range
Compensation_Al1	Internal compensation Al1 difference between external air temperature and measurement read by NTC sensor Al1	°C/10 or °F/10	-1000 1000
Compensation_Al4	Internal compensation Al4 difference between external temperature and T measurement read by RH sensor Al4 (this temperature is used to calculate the relative humidity based on psychrometric charts)	°C/10 or °F/10	-1000 1000

Factory values for these offsets assume a typical installation with wall mounted backplate in a non-ventilated environment and with the display backlighting mainly OFF. In these conditions the following calibration values are obtained:

Compensation_Al1 = -12.0 °C Compensation_Al4 = -10.5 °C

If the usage conditions require the backlight to be mainly ON, the values must be modified as follows:

Compensation_Al1 = -15.0 °C Compensation_Al4 = -13.0 °C

NOTE: For other mounting conditions, it is advisable to carry out **calibration** during installation, checking the temperature and relative humidity differences between the external air and the internal probes and if necessary correcting the parameters **Compensation_Al1 / Compensation_Al4**.

In any case it is possible to achieve a precision of \pm 1°C on the temperature measurement and \pm 3%RH on the relative humidity measurement.

8.2. Analog outputs (LOW VOLTAGE - SELV) configuration for M171 Performance

See CHAPTER 3 Electrical connections on pag. 23 for the number and type of analog outputs used and for information on the symbols used on labels supplied with the controller.

There are 5 extra-low voltage (SELV) analog outputs with the following characteristics:

Configuration of low voltage (SELV) analog output

AO1/AO5	AO2	AO3	AO4
Always available Current/voltage output Low voltage (SELV) AO1 and AO5 are configured in pairs.	Always available Current/voltage output Low voltage (SELV)	Always available Current/voltage output Low voltage (SELV)	Always available Current/voltage output Low voltage (SELV)
Sub-mode configuration AO5 Only if AO1/AO5 have not been configured as voltage outputs (value ≠2)	-	-	-

Outputs AO1, AO2, AO3, AO4, AO5 are configurable as:

- 0 = 4-20mA current analog output
- 1 = output configured as 0...20mA switch (ON= max 20mA, OFF=0mA) for piloting switch loads such as ON/OFF.
- 2 = 0-10V voltage analog output.

Outputs AO4, AO5 can be configured as Open Collector output. Set:

- Cfg AO4 = 1 (ON/OFF type switching)
- Cfg AO1 AO5 = 0 or 1 (pair of outputs configured as current outputs)
- SubCfg AO5 = 1 (ON/OFF type switching)
- Analog value piloted for both outputs = 0.

For developers using TM171SW (SoMachineHVAC): see the sysAOasOC function (target block) in the TM171SW (SoMachineHVAC) Application Library

8.3. Digital inputs (LOW VOLTAGE - SELV) configuration for M171 Performance

There are 8 low-voltage digital inputs, identified below as DI1...DI8:

They are grouped as:

- DI1...DI4
- DI5...DI8

Each one has its own common contact.

Digital inputs can be used as pulse counters.

The length of the pulse (both positive or negative) must be greater than 12ms.

There is also a fast, voltage-free digital input that also works as a pulse counter:

- It reads the number of times the contact applied to the input closes.
- · It reads frequencies from 0.1Hz to 1KHz at the most.

8.4. Digital outputs configuration for M171 Performance

See CHAPTER 3 Electrical connections on pag. 23 for the number and capacity of relays and/or SSR depending on the reference, and for information on the symbols used on labels supplied with the controller.

- · There are 7 high voltage outputs (relays) identified as DO1...DO7.
- In references TM171PDM27S there are 5 high voltage outputs (relays) identified as DO1...DO3, DO6, DO7 whereas there
 are 2 SSR outputs identified as DO3...DO4.

8.5. Ports configuration for M171 Performance using DipSwitch

Dipswitches are used for the configuration of serial ports, which can be On-Board (OB) or available via plug-in TM171A•••• modules (PI).

4-position lateral DipSwitches

There is a 4-position lateral DipSwitch (microswitch) in all TM171PDM27●, TM171PBM27R and TM171EP●●R expansion references.

6 and 10-position DipSwitches

Under the front panel, TM171PBM27R and TM171EP●●R expansion references have:

- A 6-position DipSwitch (microswitch) (SW2)
- · A 10-position DipSwitch (microswitch) (SW1)

Ease off the front panel with a fingernail, or the tip of a slot head screwdriver.

Configure as necessary then replace the front panel by pressing lightly back into place.



8.5.1. TM171PDM27 DipSwitch

4-position lateral DipSwitch

Used for serial addressing only.

The address is given by the sum of the value of a parameter (*) plus the value defined by the dipswitch (16 addresses).

		4-position dip					
Serial Addressing Default=0	Dip value	Dip4	3	2	1		
4 3 2 1	0	0	0	0	0		
ON	1	0	0	0	1		
	2	0	0	1	0		
LOW Address	15	1	1	1	1		

	Address									
Parameter (*)	Default Parameter		LOW address Default=0							
Addr_RS485_OB	1		4 3 2 1							
Addr_CAN_OB	1		1021							
Addr_RS485_PI	1									
Addr_CAN_PI	1	†								
Addr_RS232_PI	1									
lp_4_ETH_PI	100		LOW Address							

8.5.2. TM171PBM27R DipSwitch

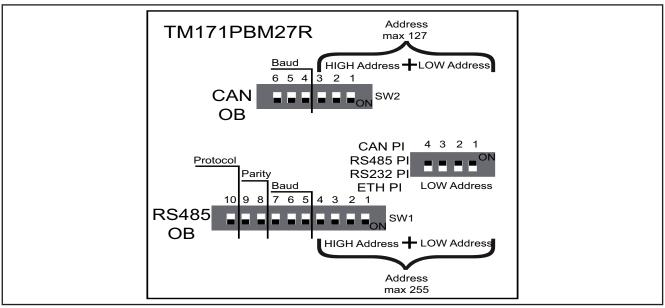


Fig. 55. TM171PBM27R Dipswitch

Serial addressing

4-position lateral DipSwitch

Used for the serial addressing of the plug-in port (PI) only.



In the serial addressing of On-Board (OB) serial ports, the 4-position dip is not used for TM171PBM27R.

The address is given by the sum of the value of a parameter (*) plus the value defined by the dipswitch (16 addresses).

		4-position dip				
Serial Addressing Default=0	Dip value	Dip4	3	2	1	
4 3 2 1	0	0	0	0	0	
	1	0	0	0	1	
	2	0	0	1	0	
LOW Address	15	1	1	1	1	

	Address										
Parameter (*)	Default Parameter		LOW address Default=0								
Addr_RS485_PI	1		4 3 2 1								
Addr_CAN_PI	1		ON								
Addr_RS232_PI	1	+									
lp_4_ETH_PI	100		LOW Address								

Baud

6-position TM171PBM27R DipSwitch

The actual CAN Baud rate comprises the sum of parameter **Baud_CAN_OB** plus the composite value of the 3-position dipswitches (8 values).

CAN baud selection OB Default = 500 baud	Dip value	Dip6	5	4	3	2	1
Baud 6 5 4 3 2 1 CAN NW2	0	0	0	0	//	//	//

Actual CAN Baud Value Default = 500 baud		Parameter Baud_CAN_OB		CAN baud selection Default = 0
2=500				
3=250				Baud 6 5 4 3 2 1
4=125	=	Parameter Baud_CAN_OB		CAN ON SW2
5=125				ON
6=50				
default example		2	+	0

CAN OB serial addressing

6-position dipswitch + 4-position dipswitch

The addressing comprises the sum of parameter **Addr_CAN_OB** plus the composite value of the 6 and 4-position dipswitches (127 addresses).

		6-position dip HIGH address					4-position dip LOW address				
CAN OB serial addressing Default = 1	Dip value	Dip6	5	4	3	2	1	Dip4	3	2	1
CAN Address	0	//	//	//	0	0	0	0	0	0	0
max 127	1	//	//	//	0	0	0	0	0	0	1
HIGH Address + LOW Address	2	//	//	//	0	0	0	0	0	1	0
6 5 4 3 2 1 4 3 2 1 SW2											
LOW Address	126	//	//	//	1	1	1	1	1	1	0

	Address								
Parameter		HIGH+LOW address - Default = 0							
Addr_CAN_OB	+	HIGH Address max 127 HIGH Address + LOW Address 4 3 2 1 SW2 LOW Address							
1	+	0							

RS485 OB serial configuration

10-position dipswitch

		Dip value	Dip10	9	8	7	6	5	4	3	2	1
Protocol	Destroy	0	0	//	//	//	//	//	//	//	//	//
selection RS485 OB Default = 1	selection RS485 OB RS485 OB RS	1	1	//	//	//	//	//	//	//	//	//
Parity selec-	Parity	0	//	0	0	//	//	//	//	//	//	//
tion RS485 OB	RS485 10 9 8 7 6 5 4 3 2 1 SW1	1	//	0	1	//	//	//	//	//	//	//
Default = EVEN	OB ON ON	2	//	1	0	//	//	//	//	//	//	//
		0	//	//	//	0	0	0	//	//	//	//
Baud selec-		1	//	//	//	0	0	1	//	//	//	//
tion RS485 OB	RS485	2	//	//	//	0	1	0	//	//	//	//
I KOTOS OB 1 TOTO	SW/1	3	//	//	//	0	1	1	//	//	//	//
		4	//	//	//	1	0	0	//	//	//	//
		5	//	//	//	1	0	1	//	//	//	//

Parameter	Default Parameter		LOW address Default = 0
	2=Reserved for Schneider Electric use		RS485 10 9 8 7 6 5 4 3 2 1 sw1
Proto_RS485_OB	3= Modbus RTU	+	OB on sw1
Parity_RS485_OB	0= NULL	+	Parity 10 9 8 7 6 5 4 3 2 1
	1= ODD	Ĺ	RS485 OB OSW1
	2= EVEN		
	0=9600		
	1=19200]	
Baud_RS485_OB	2=38400	+	RS485 10 9 8 7 6 5 4 3 2 1
Bauu_K3405_OB	3=57600	Ī	OB on SW1
	4=76800		
	5=115200		

RS485 OB serial addressing

10-position dipswitch + 4-position dipswitch

The address is given by the sum of the value of the two 6 and 4-position dipswitches (255 addresses).

				10-position dip HIGH address					4-position dip LOW address					
	Serial addressing RS485 OB Default = 1	Dip value	Dip105	4	3	2	1	Dip4	3	2	1			
		0	//	0	0	0	0	0	0	0	0			
RS485	10 9 8 7 6 5 4 3 2 1 4 3 2 1	1	//	0	0	0	0	0	0	0	1			
ОВ	W1 FIGH Address LOW Address	2	//	0	0	0	0	0	0	1	0			
	Address max 255	254	//	1	1	1	1	1	1	1	0			

	Address										
Parameter		LOW address Default = 0									
Addr_RS485_OB	+	RS485 OB HIGH Address + LOW Address max 255									
1	+	0									

NOTE: Any other combination of the dipswitches not listed here is not permitted.

To summarize, in the case of **TM171PBM27R**s, the default configuration for all dipswitches is as follows:

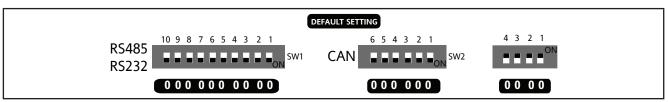


Fig. 56. Default setting

RS232 OB configuration and serial addressing

6 and 10-position dipswitches are not used. See CHAPTER 9 Parameters on pag. 105.

8.5.3. TM171EP27R expansion DipSwitch

TM171EP27R expansion serials are configured by configuring dipswitches, without using the "internal" parameters visible in the **CHAPTER 9 Parameters on pag. 105**.

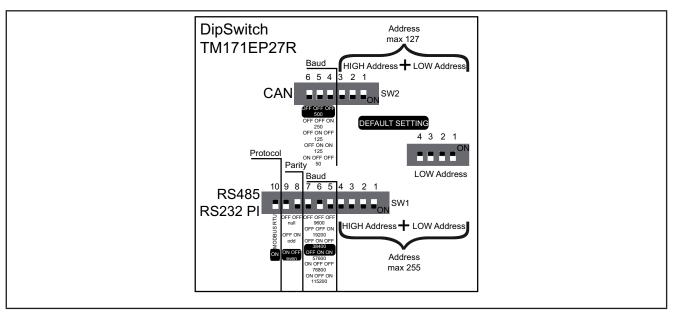


Fig. 57. Dipswitch TM171EP27R

Baud

6-position TM171EP27R dipswitch

CAN baud selection OB and PI Default = 500 baud	Baud	Dip value	Dip6	5	4	3	2	1
Raud	500	0	0	0	0	//	//	//
Baud 6 5 4 3 2 1	250	1	0	0	1	//	//	//
CAN ON SW2	125	2	0	1	0	//	//	//
1	125	3	0	1	1	//	//	//
	50	4	1	0	0	//	//	//

CAN OB and PI serial addressing

6-position dipswitch + 4-position TM171EP27R dipswitch

The address is given by the value of the 6 and 4-position dipswitches (127 addresses).

				6-position dip HIGH address					4-position dip LOW address				
CAN serial addressing OB and PI Default = 1	Address	Dip value	Dip6	5	4	3	2	1	Dip4	3	2	1	
CAN Address	1	0	//	//	//	0	0	0	0	0	0	0	
max 127	2	1	//	//	//	0	0	0	0	0	0	1	
HIGH Address + LOW Address 6 5 4 3 2 1 4 3 2 1	3	2	//	//	//	0	0	0	0	0	1	0	
ON													
LOW Address	127	126	//	//	//	1	1	1	1	1	1	0	

RS232 PI and RS485 OB serial configuration

10-position dipswitch

		Protocol	Dip value	Dip10	9	8	7	6	5	4	3	2	1
Protocol selec- tion RS232 PI / RS485 OB	RS485 RS232 PI ON SW1	Reserved for Schneider Electric use	0	0	//	//	//	//	//	//	//	//	//
Default = 1		ModBus RTU	1	1	//	//	//	//	//	//	//	//	//
Parity selection	RS485 RS232 PI Parity 10 9 8 7 6 5 4 3 2 1 ON SW1	Null	0	//	0	0	//	//	//	//	//	//	//
RS232 PI /		Odd	1	//	0	1	//	//	//	//	//	//	//
RS485 OB Default = EVEN		Even Even	2	//	1	0	//	//	//	//	//	//	//
		9600	0	//	//	//	0	0	0	//	//	//	//
Baud selection	Baud	19200	1	//	//	//	0	0	1	//	//	//	//
RS232 PI / RS485 OB	RS485 10 9 8 7 6 5 4 3 2 1	38400	2	//	//	//	0	1	0	//	//	//	//
Default = 38400	RS232 PI	57600	3	//	//	//	0	1	1	//	//	//	//
baud		76800	4	//	//	//	1	0	0	//	//	//	//
			5	//	//	//	1	0	1	//	//	//	//

RS485 OB and PI serial addressing

10-position dipswitch + 4-position dipswitch

The address is given by the sum of the value of the two 6 and 4-position dipswitches (255 addresses).

	10-position dip HIGH address				4-position dip LOW address						
CAN serial addressing OB and PI Default = 1	Address	Dip value	Dip105	4	3	2	1	Dip4	3	2	1
	1	0	// //	0	0	0	0	0	0	0	0
RS485 RS232 PI	2	1	// //	0	0	0	0	0	0	0	1
HIGH Address + LOW Address	3	2	// //	0	0	0	0	0	0	1	0
Address max 255											
	255	254	// //	1	1	1	1	1	1	1	0

NOTE: Any other combination of the dipswitches not listed here is not permitted.

To summarize, in the case of **TM171EP27R**, the default configuration for all dipswitches is as follows:

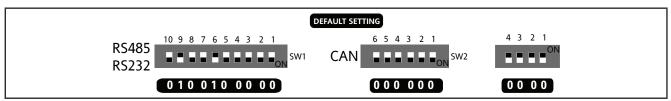


Fig. 58. Default setting

8.5.4. TM171EP14R expansion DipSwitch

4-position lateral DipSwitch

Used for:

- serial addressing (dip 1 and 2)
- line termination (dip 3 and 4)

				4-posit	ion dip	
Serial Addressing	Address = DipValue+1	Dip value	Dip4	3	2	1
	1	0	-	-	0	0
4 3 2 1	2 1		-	-	0	1
I I	3	2	-	-	1	0
■ ■ ■ ON	4	3	-	-	1	1
R Term LOW Address	Dip value (Address)	Dip value (Address)	Dip4	3	2	1
CAN	120Ω termination	120Ω termination	1	1	-	-

CAN OB serial addressing

The addressing comprises the sum of parameter **Addr_CAN_OB** plus the composite value of the 4-position dipswitches (only dip 1 and 2).

Actual CAN Adresss Default = 1		Parameter Addr_CAN_OB Default = 1		CAN address selection Default = 0
1				4 3 2 1
	_	Paramotor Raud CAN OR	+	■ ■ ON
	_	Parameter Baud_CAN_OB		LOW Address
127 max				CAN
default example		1	+	0

Baud

Baud rate is set by Baud_CAN_OB parameter

Line Termination resistors

Dip4 and 3 both = 1 connects L/H CAN lines to 120Ω termination

CHAPTER 9

Parameters

User-parameterization renders the **Modicon M171P** fully configurable. Parameters can be changed using:

- Keys on the TM171PDM27● / M171 Performance Flush front panel or remote M171 Display Graphic (TM171DGRP) panel.
- PC and TM171SW (SoMachineHVAC) software

The following sections provide a detailed analysis of each parameter, divided into categories (folders).

For **M171 Performance**, the parameter table shows all configuration parameters for the controller saved in the non-volatile memory.

For M171 Performance Flush, the parameter table contains all the device configuration parameters available in TM171SW (SoMachineHVAC) Device and in the DIAGNOSTICS (DIA) / BIOS Parameters menu.

Description of columns:

Description of columns contains a legend to explain parameter table.

LABEL	This indicates the label used to display the parameters in the menu of the controller.
PAR. VALUE ADDRESS	Indicates the address of the modbus register containing the resource to be accessed.
DATA SIZE	Indicates the size of the data in bits.
CPL	When the field indicates "-1", the value read by the register requires conversion, because the value represents a number with a sign. In other cases the value is always positive or null. To carry out the conversion, proceed as follows: If the value in the register is between 0 and 32.767, the result is the value itself (zero and positive values) If the value in the register is between 32.768 and 65.535, the result is the value of the register – 65.536 (negative values)
RESET (Y/N)	Indicates whether the device MUST be rebooted after the parameter has been modified. • Y=YES the device MUST be rebooted to modify the parameter. • Empty " "=NO the device DOESN'T need to be rebooted to modify the parameter
RANGE	Describes the interval of values that can be assigned to the parameter. It can be correlated with other instrument parameters (indicated in the parameter label).
DEFAULT	Indicates the factory setting for the standard reference of the instrument.
U.M.	Unit of measurement for values converted according to the rules indicated in the CPL column The unit of measurement shown is for example purposes only, as it may change depending on the application (e.g. parameters with a UoM in °C/bar could also have %RH)

Modbus commands available and data areas

The following commands are implemented:

Modbus command	Description of command
3	Read multiple registers on Client side
16	Write multiple registers on Client side
43	Read device ID
	DESCRIPTION Manufacturer ID Model ID Version ID

9.1. Parameter table

(See next page).

All resources can be both read and written to.

9.1.1. M171 Performance parameters

TM171PDM27• / TM171PBM27R / TM171EP27R parameters

LABEL	PAR. VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
ACKNOWLEDGEM	ENT fold	ler						
Par_TAB	15716	WORD		Υ	Map code Note: read/write parameter	0 65535	0	num
Par_POLI	15717	WORD		Υ	Model Code Note: read/write parameter	0 65535	1025	num
Par_PARMOD	15719	BOOL			Parameter modified Flag indicating change to default settings. • 0= map not modified. • 1= at least one parameter has been modified with respect to the original configuration.	0 1	0	num
AI CALIBRATION f	older							
Gain_Ntc_Al1	15616	WORD			Ai1 NTC calibration gain	0 65535	32768	num
Gain_Ntc_Al2	15617	WORD			Ai2 NTC calibration gain	0 65535	32768	num
Gain_Ntc_Al3	15618	WORD			Ai3 NTC calibration gain	0 65535	32768	num
Gain_PT1000_Al3	15619	WORD			Ai3 PT1000 calibration gain	0 65535	32768	num
Gain_5V_Al3	15620	WORD			Ai3 0-5V calibration gain	0 65535	32768	num
Gain_10V_Al3	15621	WORD			Ai3 0-10V calibration gain	0 65535	32768	num
Gain_mA_Al3	15622	WORD			Ai3 4-20mA calibration gain	0 65535	32768	num
Gain_Ntc_Al4	15623	WORD			Ai4 NTC calibration gain	0 65535	32768	num
Gain_PT1000_Al4	15624	WORD			Ai4 PT1000 calibration gain	0 65535	32768	num

LABEL	PAR. VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.	
Gain_5V_AI4	15625	WORD			Ai4 0-5V calibration gain	0 65535	32768	num	
Gain_10V_AI4	15626	WORD			Ai4 0-10V calibration gain	0 65535	32768	num	
Gain_mA_Al4	15627	WORD			Ai4 4-20mA calibration gain	0 65535	32768	num	
Gain_Ntc_Al5	15628	WORD			Ai5 NTC calibration gain	0 65535	32768	num	
Gain_PT1000_Al5	15629	WORD			Ai5 PT1000 calibration gain	0 65535	32768	num	
Gain_5V_AI5	15630	WORD			Ai5 0-5V calibration gain	0 65535	32768	num	
Gain_10V_AI5	15631	WORD			Ai5 0-10V calibration gain	0 65535	32768	num	
Gain_mA_Al5	15632	WORD			Ai5 4-20mA calibration gain	0 65535	32768	num	
Gain_Ntc_Al6	15633	WORD			Ai6 NTC calibration gain	0 65535	32768	num	
Gain_PT1000_Al6	15634	WORD			Ai6 PT1000 calibration gain	0 65535	32768	num	
Gain_5V_AI6	15635	WORD			Ai6 0-5V calibration gain	0 65535	32768	num	
Gain_10V_Al6	15636	WORD			Ai6 0-10V calibration gain	0 65535	32768	num	
Gain_mA_Al6	15637	WORD			Ai6 0-10mA calibration gain	0 65535	32768	num	
Offs_Ntc_Al1	15650	WORD	-1		Ai1 NTC calibration offset	-32768 32767	0	num	
Offs_Ntc_Al2	15651	WORD	-1		Ai2 NTC calibration offset	-32768 32767	0	num	
Offs_Ntc_Al3	15652	WORD	-1		Ai3 NTC calibration offset	-32768 32767	0	num	
Offs_PT1000_AI3	15653	WORD	-1		Ai3 PT1000 calibration offset	-32768 32767	0	num	
Offs_5V_Al3	15654	WORD	-1		Ai3 0-5V calibration offset	-32768 32767	0	num	
Offs_10V_AI3	15655	WORD	-1		Ai3 0-10V calibration offset	-32768 32767	0	num	
Offs_mA_Al3	15656	WORD	-1		Ai3 4-20mA calibration offset	-32768 32767	0	num	
Offs_Ntc_Al4	15657	WORD	-1		Ai4 NTC calibration offset	-32768 32767	0	num	
Offs_PT1000_AI4	15658	WORD	-1		Ai4 PT1000 calibration offset	-32768 32767	0	num	
Offs_5V_Al4	15659	WORD	-1		Ai4 0-5V calibration offset	-32768 32767	0	num	
Offs_10V_AI4	15660	WORD	-1		Ai4 0-10V calibration offset	-32768 32767	0	num	
Offs_mA_AI4	15661	WORD	-1		Ai4 4-20mA calibration offset	-32768 32767	0	num	
Offs_Ntc_AI5	15662	WORD	-1		Ai5 NTC calibration offset	-32768 32767	0	num	
Offs_PT1000_AI5	15663	WORD	-1		Ai5 PT1000 calibration offset	-32768 32767	0	num	
Offs_5V_AI5	15664	WORD	-1		Ai5 0-5V calibration offset	-32768 32767	0	num	
Offs_10V_AI5	15665	WORD	-1		Ai5 0-10V calibration offset	-32768 32767	0	num	
Offs_mA_AI5	15666	WORD	-1		Ai5 4-20mA calibration offset	-32768 32767	0	num	
Offs_Ntc_Al6	15667	WORD	-1		Ai6 NTC calibration offset	-32768 32767	0	num	
Offs_PT1000_Al6	15668	WORD	-1		Ai6 PT1000 calibration offset	-32768 32767	0	num	
Offs_5V_AI6	15669	WORD	-1		Ai6 0-5V calibration offset	-32768 32767	0	num	
Offs_10V_Al6	15670	WORD	-1		Ai6 0-10V calibration offset	-32768 32767	0	num	
Offs_mA_Al6	15671	WORD	-1		Ai6 4-20mA calibration offset	-32768 32767	0	num	
AO CALIBRATION folder									
Gain_10V_AO1	15684	WORD			AO1 0-10V calibration gain	0 65535	32768	num	
Gain_mA_AO1	15685	WORD			AO1 4-20mA calibration gain	0 65535	32768	num	

LABEL	PAR. VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.			
Gain_10V_AO2	15686	WORD			AO2 0-10V calibration gain	0 65535	32768	num			
Gain_mA_AO2	15687	WORD			AO2 4-20mA calibration gain	0 65535	32768	num			
Gain_10V_AO3	15688	WORD			AO3 0-10V calibration gain	0 65535	32768	num			
Gain_mA_AO3	15689	WORD			AO3 4-20mA calibration gain	0 65535	32768	num			
Gain_10V_AO4	15690	WORD			AO4 0-10V calibration gain	0 65535	32768	num			
Gain_mA_AO4	15691	WORD			AO4 4-20mA calibration gain	0 65535	32768	num			
Gain_10V_AO5	15692	WORD			AO5 0-10V calibration gain	0 65535	32768	num			
Gain_mA_AO5	15693	WORD			AO5 4-20mA calibration gain	0 65535	32768	num			
Offs_10V_AO1	15700	WORD	-1		AO1 0-10V calibration offset	-32768 32767	0	num			
Offs_mA_AO1	15701	WORD	-1		AO1 4-20mA calibration offset	-32768 32767	0	num			
Offs_10V_AO2	15702	WORD	-1		AO2 0-10V calibration offset	-32768 32767	0	num			
Offs_mA_AO2	15703	WORD	-1		AO2 4-20mA calibration offset	-32768 32767	0	num			
Offs_10V_AO3	15704	WORD	-1		AO3 0-10V calibration offset	-32768 32767	0	num			
Offs_mA_AO3	15705	WORD	-1		AO3 4-20mA calibration offset	-32768 32767	0	num			
Offs_10V_AO4	15706	WORD	-1		AO4 0-10V calibration offset	-32768 32767	0	num			
Offs_mA_AO4	15707	WORD	-1		AO4 4-20mA calibration offset	-32768 32767	0	num			
Offs_10V_AO5	15708	WORD	-1		AO5 0-10V calibration offset	-32768 32767	0	num			
Offs_mA_AO5	15709	WORD	-1		AO5 4-20mA calibration offset	-32768 32767	0	num			
ANALOG INPUTS folder											
Temp_UM	15725	WORD		Υ	Temperature unit of measurement • 0 = °C; • 1 = °F	0 1	0	num			
Cfg_Ai1	15726	WORD			Type of analog input Ai1 O= NTC (NK103) 1= DI 2= NTC (103AT)	0 2	2	num			
Cfg_Ai2	15727	WORD			Type of analog input Ai2 See Cfg_Ai1	0 2	2	num			

LABEL	PAR. VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
Cfg_Ai3	15728	WORD			Type of analog input Ai3 • $0 = NTC (NK103)$ • $1 = DI$ • $2 = NTC (103AT)$ • $3 = 420mA$ • $4 = 0-10V$ • $5 = 0-5V$ • $6 = Pt1000$ • $7 = h\Omega(NTC)$ • $8 = da\Omega(PT1000)$	0 8	3	num
Cfg_Ai4	15729	WORD			Type of analog input Ai4 See Cfg_Ai3	0 8	3	num
Cfg_Ai5	15730	WORD			Type of analog input Ai5 See Cfg_Ai3	0 8	3	num
Cfg_Ai6	15731	WORD			Type of analog input Ai6 See Cfg_Ai3	0 8	3	num
FullScaleMin_Ai3	15736	WORD	-1		Analog input Ai3 start of scale value Note: Minimum full scale: for current probes, value at 4mA, for 0-10V voltage probes, value at 0V, for ratiometric probes (0-5V), value at 10% (corresponding to 0.5V).	-9999+9999	0	
FullScaleMax_Ai3	15737	WORD			Analog input Ai3 full scale value Note: Maximum full scale for current probes, value at 20mA, for 0-10V voltage probes, value at 10V, for ratiometric probes (0-5V), value at 90% (corresponding to 4.5V).	-9999+9999	1000	
FullScaleMin_Ai4	15738	WORD	-1		Analog input Ai4 start of scale value See FullScaleMin_Ai3	-9999+9999	0	
FullScaleMax_A4	15739	WORD			Analog input Ai4 full scale value See FullScaleMAx_Ai3	-999+999	1000	
FullScaleMin_Ai5	15740	WORD	-1		Analog input Ai5 start of scale value See FullScaleMin_Ai3	-9999+9999	0	
FullScaleMax_Ai5	15741	WORD			Analog input Ai5 full scale value See FullScaleMax_Ai3	-999+999	1000	
FullScaleMin_Ai6	15742	WORD	-1		Analog input Ai6 start of scale value See FullScaleMin_Ai3	-9999+9999	0	

LABEL	PAR. VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
FullScaleMaxAi6	15743	WORD			Analog input Ai6 full scale value See FullScaleMax_Ai3	-999+999	100	
Calibration_Ai1	15748	WORD	-1		Analog input Ai1 differential	-180 180	0	°C/10 or °F/10
Calibration_Ai2	15749	WORD	-1		Analog input Ai2 differential	-180 180	0	°C/10 or °F/10
Calibration_Ai3	15750	WORD	-1		Analog input Ai3 differential	-1000 1000	0	
Calibration_Ai4	15751	WORD	-1		Analog input Ai4 differential	-1000 1000	0	
Calibration_Ai5	15752	WORD	-1		Analog input Ai5 differential	-1000 1000	0	
Calibration_Ai6	15753	WORD	-1		Analog input Ai6 differential	-1000 1000	0	
ANALOG OUTPUT	S V/I fold	ler						
Cfg_AO1_AO5	15758	WORD		Y	Type of analog output AO1/AO5 AO1 and AO5 are configured in pairs. See SubCfg_AO5 • 0 = 4-20mA current analog output • 1 = ON/OFF output configured as 0/420mA switch (ON=max 20mA, OFF=0mA) for piloting switch loads such as ON/OFF. • 2=0-10V analog output - voltage Note. AO4 and AO5 can be configured as Open Collector → A04=1, A01/A05=0 or 1, SubCfg_AO5=1	0 2	0	num
Cfg_AO2	15759	WORD		Υ	Type of analog output AO2 See Cfg_ AO1_AO5	0 2	0	num
Cfg_AO3	15760	WORD		Υ	Type of analog output AO3 See Cfg_ AO1_AO5	0 2	0	num
Cfg_AO4	15761	WORD		Υ	Type of analog output AO4	0 2	0	num

LABEL	PAR. VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
SubCfg_AO5	15762	WORD		Υ	Analog output AO5 sub-mode function Only applies if Cfg_AO1_AO5≠2 • 0 = 4-20mA current analog output • 1 = ON/OFF output configured as 0/420mA switch (ON=max 20mA, OFF=0mA) for piloting switch loads such as ON/OFF. Note. AO4 and AO5 can be configured as Open Collector → A04=1, A01/A05=0 or 1, SubCfg_AO5=1	0 1	0	num

TM171PDM27• / TM171PBM27R parameters

LABEL	PAR. VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
ON BOARD RS485 fo	lder							
Addr_RS485_OB	15774	WORD		Υ	On-board RS485 serial address The actual address is determined by the sum of this value + the value of the dip switch.	0 255	1	num
Proto_RS485_OB	15775	WORD		Υ	On-board RS485 protocol selection • 2 = uNET • 3 = Modbus/RTU	2 3	3	num
Databit_RS485_OB	15776	WORD		Υ	On-board RS485 data bit number Fixed setting 8	8 8	8	num
Stopbit_RS485_OB	15777	WORD		Υ	On-board RS485 stop bit number 1= 1 stop bit 2= 2 stop bit	1 2	1	num
Parity_RS485_OB	15778	WORD		Υ	On-board RS485 protocol parity 0= NULL • 1= ODD • 2= EVEN	0 2	2	num
Baud_RS485_OB	15779	WORD		Υ	On-board RS485 protocol baudrate O=9600 baud 1=19200 baud 2=38400 baud 3=57600 baud 4=76800 baud 5=115200 baud	0 5	2	num
ON BOARD CAN fold	er							!
Addr_CAN_OB	15780	WORD		Υ	On-board CAN serial address The actual address is determined by the sum of this value + the value of the dip switch.	1 127	1	num
Baud_CAN_OB	15781	WORD		Υ	On-board CAN protocol baudrate • 2=500 Kbaud • 3=250 Kbaud • 4=125 Kbaud • 5=125 Kbaud • 6=50 Kbaud	2 6	2	num
CAN PLUGIN PASSIV	/E folder							
Addr_RS485_PI	15782	WORD		Υ	RS485 passive plug-in serial address The actual address is determined by the sum of this value + the value of the dip switch.	0 255	1	num

LABEL	PAR. VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
Proto_RS485_PI	15783	WORD		Υ	RS485 passive plug-in protocol selection 2 = uNET 3 = Modbus/RTU	2 3	3	num
Databit_RS485_PI	15784	WORD		Υ	RS485 passive plug-in data bit number Fixed setting 8	8 8	8	num
Stopbit_RS485_PI	15785	WORD		Υ	RS485 passive plug-in stop bit number 1 = 1 stop bit 2 = 2 stop bit	1 2	1	num
Parity_RS485_PI	15786	WORD		Υ	RS485 passive plug-in protocol parity 0= NULL 1= ODD 2= EVEN	0 2	2	num
Baud_RS485_PI	15787	WORD		Υ	RS485 passive plug-in protocol baudrate • 0=9600 baud • 1=19200 baud • 2=38400 baud • 3=57600 baud • 4=76800 baud • 5=115200 baud	0 5	2	num
Addr_CAN_PI	15788	WORD		Υ	CAN passive plug-in serial address The actual address is determined by the sum of this value + the value of the dip switch.	1 127	1	num
Baud_CAN_PI	15789	WORD		Υ	CAN passive plug-in protocol baudrate • 2=500 Kbaud • 3=250 Kbaud • 4=125 Kbaud • 5=125 Kbaud • 6=50 Kbaud	2 6	2	num
RS232 PASSIVE PLU	G-IN fol	der						
Addr_ RS232_PI	15790	WORD		Υ	RS232 passive plug-in serial address The actual address is determined by the sum of this value + the value of the dip switch.	0 255	1	num
Proto_ RS232_PI	15791	WORD		Υ	RS232 passive plug-in protocol selection • 2 = uNET • 3 = Modbus/RTU	2 3	3	num

LABEL	PAR. VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
Databit_ RS232_PI	15792	WORD		Y	RS232 passive plug-in data bit number • 7= 7 bit • 8= 8 bit	7 8	8	num
Stopbit_ RS232_PI	15793	WORD		Υ	RS232 passive plug-in stop bit number 1 = 1 stop bit 2 = 2 stop bit	1 2	1	num
Parity_ RS232_PI	15784	WORD		Υ	RS232 passive plug-in protocol parity • 0= NULL • 1= ODD • 2= EVEN	0 2	2	num
Baud_RS232_PI	15795	WORD		Y	RS232 passive plug-in protocol baudrate • 0=9600 baud • 1=19200 baud • 2=38400 baud • 3=57600 baud • 4=76800 baud • 5=115200 baud	0 5	2	num

PASSIVE ETHERNET PLUG-IN

ETHERNET configuration parameters for passive plug-in require configuration of the TCP/IP communication port (e.g. 502), the IP address, the gateway and the subnet mask

The 'Default Gateway' and 'Net mask' parameters are of no significance in the local point-to-point network.

For connections via a router the 'Default Gateway' parameters must match the IP address, as in the following example:

		Value			Value
lp_1_ETH_PI	Ethernet Passive Plug- In IP address (part 1)	192	DefGtwy_1_ETH_PI	Default Gateway (part 1)	192
lp_2_ETH_PI	Ethernet Passive Plug- In IP address (part 2)	168	DefGtwy_2_ETH_PI	Default Gateway (part 2)	168
lp_3_ETH_PI	Ethernet Passive Plug- In IP address (part 3)	0	DefGtwy_3_ETH_PI	Default Gateway (part 3)	0
lp_4_ETH_PI	Ethernet Passive Plug- In IP address (part 4)	100	DefGtwy_4_ETH_PI	Default Gateway (part 4)	1

The parameters necessary for the configuration of ports and protocols are these:



FREE WEB allows the use of HTTP and TFTP servers.

Parameter	Description	Label
HTTP ports	HTTP HyperText Transfer Protocol. An HTTP server generally listens on port 80 using TCP protocol.	Port_HTTP_PI
TFTP ports	TFTP Trivial File Transfer Protocol. Protocol using basic FTP functionalities. Typical use: transfer of small files between hosts on a network. TFTP USES PORT 69	Port_TFTP_PI
DHCP protocol	DHCP Dynamic Host Configuration Protocol	EnableDHCP_ETH_ PI
		PriDNS_1_ETH_PI
		PriDNS_2_ETH_PI
		PriDNS_3_ETH_PI
DNS system	DNS Domain Name System System for the conversion of host names, or network nodes, to IP addresses	PriDNS_4_ETH_PI
DIVO System	Used by TM171SW (SoMachineHVAC) to send text e-mails (strings)	SecDNS_1_ETH_PI
		SecDNS_2_ETH_PI
		SecDNS_3_ETH_PI
		SecDNS_4_ETH_PI

LABEL	PAR VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
ETHERNET PASS	SIVE PLUC	G-IN folder	r					
Port_TFTP_PI	15772	WORD		Υ	TFTP port TFTP communication Port number Default 0 corresponds to port 69	0 65535	0	num
Port_HTTP_PI	15796	WORD		Y	HTTP port HTTP communication Port number Default 0 corresponds to port 80	0 65535	0	num
Port_ETH_PI	15797	WORD		Υ	Port TCP/IP Modbus communication port. Port 502 for example	0 65535	502	num
lp_1_ETH_PI	15798	WORD		Υ	Ethernet passive Plug-in IP address (part 1)	0 255	10	num
lp_2_ETH_PI	15799	WORD		Υ	Ethernet passive Plug-in IP address (part 2)	0 255	0	num
lp_3_ETH_PI	15800	WORD		Υ	Ethernet passive Plug-in IP address (part 3)	0 255	0	num
lp_4_ETH_PI	15801	WORD		Υ	Ethernet passive Plug-in IP address (part 4)	0 255	100	num
DefGtwy_1_ ETH_PI	15802	WORD		Υ	Default Gateway (part 1)	0 255	192	num
DefGtwy_2_ ETH_PI	15803	WORD		Υ	Default Gateway (part 2)	0 255	168	num
DefGtwy_3_ ETH_PI	15804	WORD		Υ	Default Gateway (part 3)	0 255	0	num
DefGtwy_4_ ETH_PI	15805	WORD		Υ	Default Gateway (part 4)	0 255	1	num
NetMsk_1_ ETH_PI	15806	WORD		Υ	Net mask (part 1)	0 255	255	num
NetMsk_2_ ETH_PI	15807	WORD		Υ	Net mask (part 2)	0 255	255	num
NetMsk_3_ ETH_PI	15808	WORD		Υ	Net mask (part 3)	0 255	255	num
NetMsk_4_ ETH_PI	15809	WORD		Υ	Net mask (part 4)	0 255	0	num
PriDNS_1_ ETH_PI	15810	WORD		Υ	Primary DNS server (part 1)	0 255	194	num
PriDNS_2_ ETH_PI	15811	WORD		Υ	Primary DNS server (part 2)	0 255	25	num
PriDNS_3_ ETH_PI	15812	WORD		Υ	Primary DNS server (part 3)	0 255	2	num
PriDNS_4_ ETH_PI	15813	WORD		Υ	Primary DNS server (part 4)	0 255	129	num
SecDNS_1_ ETH_PI	15814	WORD		Υ	Secondary DNS server (part 1)	0 255	194	num

LABEL	PAR VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
SecDNS_2_ ETH_PI	15815	WORD		Υ	Secondary DNS server (part 2)	0 255	25	num
SecDNS_3_ ETH_PI	15816	WORD		Υ	Secondary DNS server (part 3)	0 255	2	num
SecDNS_4_ ETH_PI	15817	WORD		Υ	Secondary DNS server (part 4)	0 255	130	num
EnableDHCP_ ETH_PI	15819	WORD		Υ	Enable DHCP	0 1 (False, True)	False	flag
Modems folder								
Modem_ RS232_PI	15820	BOOL		Υ	Presence of Modem	0 1	0	num
Modem_InitStr1	15821	19 BYTES		Υ	Modem initialization string (part I)	******	(*)	string
Modem_InitStr2	15831	19 BYTES		Υ	Modem initialization string (part II)	******		string
Modem_ Hangup	15851	19 BYTES		Υ	Hangup String	******	ATH0	string
Display folder								
Hmi_Language	15819	WORD		Υ	Display language	0 65535	0	num
Par_ContrLCD	15723	WORD		Υ	LCD Contrast Allows adjustment of the LCD display contrast.	0 64	30	num
Par_ BackLightTim e	15724	WORD		Υ	Backlight switch-on time Allows adjustment of LCD display switch-on time.	0 3600	10	num
(*) AT&F&C&D2E	0X1S0=0							

9.1.2. M171EP14R parameters

LABEL	PAR. VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
ACKNOWLEDGEM	ENT fold	ler						
Par_TAB	15716	WORD		Υ	Map code Note: read/write parameter	0 65535	0	num
Par_POLI	15717	WORD		Υ	Model Code Note: read/write parameter	0 65535	1025	num
Par_PCH	15718	WORD			Model ID Code	0 65535	262	num
AI CALIBRATION f	older							
Gain_Ntc_Al1	15616	WORD			Ai1 NTC calibration gain	0 65535	32768	num
Gain_Ntc_Al2	15617	WORD			Ai2 NTC calibration gain	0 65535	32768	num
Gain_Ntc_Al3	15618	WORD			Ai3 NTC calibration gain	0 65535	32768	num
Gain_Ntc_Al4	15619	WORD			Ai4 NTC calibration gain	0 65535	32768	num
Offs_Ntc_Al1	15621	WORD	-1		Ai1 NTC calibration offset	-32768 32767	0	num
Offs_Ntc_Al2	15622	WORD	-1		Ai2 NTC calibration offset	-32768 32767	0	num
Offs_Ntc_Al3	15623	WORD	-1		Ai3 NTC calibration offset	-32768 32767	0	num
Offs_Ntc_Al4	15624	WORD	-1		Ai4 NTC calibration offset	-32768 32767	0	num
Gain_PTC_Al1	15626	WORD			Ai1 PTC calibration gain	0 65535	32768	num
Gain_PTC_Al2	15627	WORD			Ai2 PTC calibration gain	0 65535	32768	num
Gain_PTC_Al3	15628	WORD			Ai3 PTC calibration gain	0 65535	32768	num
Gain_PTC_Al4	15629	WORD			Ai4 PTC calibration gain	0 65535	32768	num
Offs_PTC_AI1	15631	WORD	-1		Ai1 PTC calibration offset	-32768 32767	0	num
Offs_PTC_Al2	15632	WORD	-1		Ai2 PTC calibration offset	-32768 32767	0	num
Offs_PTC_Al3	15633	WORD	-1		Ai3 PTC calibration offset	-32768 32767	0	num
Offs_PTC_AI4	15634	WORD	-1		Ai4 PTC calibration offset	-32768 32767	0	num
Gain_daOhm_Al1	15636	WORD			Ai1 daOhm calibration gain	0 65535	32768	num
Gain_daOhm_Al2	15637	WORD			Ai2 daOhm calibration gain	0 65535	32768	num
Gain_daOhm_Al3	15638	WORD			Ai3 daOhm calibration gain	0 65535	32768	num
Gain_daOhm_Al4	15639	WORD			Ai4 daOhm calibration gain	0 65535	32768	num
Offs_daOhm_Al1	15641	WORD	-1		Ai1 daOhm calibration offset	-32768 32767	0	num
Offs_daOhm_Al2	15642	WORD	-1		Ai2 daOhm calibration offset	-32768 32767	0	num
Offs_daOhm_Al3	15643	WORD	-1		Ai3 daOhm calibration offset	-32768 32767	0	num
Offs_daOhm_Al4	15644	WORD	-1		Ai4 daOhm calibration offset	-32768 32767	0	num
Gain_mA_Al1	15646	WORD			Ai1 4-20mA calibration gain	0 65535	32768	num
Gain_mA_Al2	15647	WORD			Ai2 4-20mA calibration gain	0 65535	32768	num
Gain_mA_Al3	15648	WORD			Ai3 4-20mA calibration gain	0 65535	32768	num

LABEL	PAR. VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
Gain_mA_Al4	15649	WORD			Ai4 4-20mA calibration gain	0 65535	32768	num
Offs_mA_Al1	15651	WORD	-1		Ai1 4-20mA calibration offset	-32768 32767	0	num
Offs_mA_Al2	15652	WORD	-1		Ai2 4-20mA calibration offset	-32768 32767	0	num
Offs_mA_Al3	15653	WORD	-1		Ai3 4-20mA calibration offset	-32768 32767	0	num
Offs_mA_Al4	15654	WORD	-1		Ai4 4-20mA calibration offset	-32768 32767	0	num
Gain_5V_Ratio_ Al1	15656	WORD			Ai1 5V Ratiometric calibration gain	0 65535	32768	num
Gain_5V_Ratio_ Al2	15657	WORD			Ai2 5V Ratiometric calibration gain	0 65535	32768	num
Gain_5V_Ratio_ Al3	15658	WORD			Ai3 5V Ratiometric calibration gain	0 65535	32768	num
Gain_5V_Ratio_ Al4	15659	WORD			Ai4 5V Ratiometric calibration gain	0 65535	32768	num
Offs_5V_Ratio_ Al1	15661	WORD	-1		Ai1 5V Ratiometric calibration offset	-32768 32767	0	num
Offs_5V_Ratio_ Al2	15662	WORD	-1		Ai2 5V Ratiometric calibration offset	-32768 32767	0	num
Offs_5V_Ratio_ Al3	15663	WORD	-1		Ai3 5V Ratiometric calibration offset	-32768 32767	0	num
Offs_5V_Ratio_ Al4	15664	WORD	-1		Ai4 5V Ratiometric calibration offset	-32768 32767	0	num
Gain_10V_AI1	15666	WORD			Ai1 0-10V calibration gain	0 65535	32768	num
Gain_10V_Al2	15667	WORD			Ai2 0-10V calibration gain	0 65535	32768	num
Gain_10V_Al3	15668	WORD			Ai3 0-10V calibration gain	0 65535	32768	num
Gain_10V_AI4	15669	WORD			Ai4 0-10V calibration gain	0 65535	32768	num
Offs_10V_AI1	15671	WORD	-1		Ai1 0-10V calibration offset	-32768 32767	0	num
Offs_10V_AI2	15672	WORD	-1		Ai2 0-10V calibration offset	-32768 32767	0	num
Offs_10V_AI3	15673	WORD	-1		Ai3 0-10V calibration offset	-32768 32767	0	num
Offs_10V_AI4	15674	WORD	-1		Ai4 0-10V calibration offset	-32768 32767	0	num
Gain_5V_Al1	15676	WORD			Ai1 0-5V calibration gain	0 65535	32768	num
Gain_5V_Al2	15677	WORD			Ai2 0-5V calibration gain	0 65535	32768	num
Gain_5V_Al3	15678	WORD			Ai3 0-5V calibration gain	0 65535	32768	num
Gain_5V_AI4	15679	WORD			Ai4 0-5V calibration gain	0 65535	32768	num
Offs_5V_AI1	15681	WORD	-1		Ai1 0-5V calibration offset	-32768 32767	0	num
Offs_5V_AI2	15682	WORD	-1		Ai2 0-5V calibration offset	-32768 32767	0	num
Offs_5V_AI3	15683	WORD	-1		Ai3 0-5V calibration offset	-32768 32767	0	num
Offs_5V_AI4	15684	WORD	-1		Ai4 0-5V calibration offset	-32768 32767	0	num
Gain_PT1000_Al1	15686	WORD			Ai1 PT1000 calibration gain	0 65535	32768	num
Gain_PT1000_Al2	15687	WORD			Ai2 PT1000 calibration gain	0 65535	32768	num
Gain_PT1000_Al3	15688	WORD			Ai3 PT1000 calibration gain	0 65535	32768	num
Gain_PT1000_Al4	15689	WORD			Ai4 PT1000 calibration gain	0 65535	32768	num
Offs_PT1000_AI1	15691	WORD	-1		Ai1 PT1000 calibration offset	-32768 32767	0	num

LABEL	PAR. VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
Offs_PT1000_Al2	15692	WORD	-1		Ai2 PT1000 calibration offset	-32768 32767	0	num
Offs_PT1000_Al3	15693	WORD	-1		Ai3 PT1000 calibration offset	-32768 32767	0	num
Offs_PT1000_Al4	15694	WORD	-1		Ai4 PT1000 calibration offset	-32768 32767	0	num
AO CALIBRATION	folder	Υ						
Gain_10V_AO1	15696	WORD			AO1 0-10V calibration gain	0 65535	32768	num
Gain_10V_AO2	15697	WORD			AO2 0-10V calibration gain	0 65535	32768	num
Offs_10V_AO1	15698	WORD	-1	<u> </u>	AO1 0-10V calibration offset	-32768 32767	0	num
Offs_10V_AO2	15699	WORD	-1		AO2 0-10V calibration offset	-32768 32767	0	num
ANALOG INPUTS f	older							
Temp_UM	15725	WORD		Υ	Temperature unit of measurement • 0 = °C; • 1 = °F	0 1	0	num
Cfg_Ai1	15726	WORD			Type of analog input Ai1 • $0 = NTC (NK103)$ • $1 = DI$ • $2 = NTC (103AT)$ • $3 = 420mA$ • $4 = 0.10V$ • $5 = 0.5V$ Ratiometric • $6 = Pt1000$ • $7 = h\Omega(NTC)$ • $8 = da\Omega(PT1000)$ • PTC • $10 = 0.5V$	0 10	3	num
Cfg_Ai2	15727	WORD			Type of analog input Ai2 See Cfg_Ai1	0 10	3	num
Cfg_Ai3	15728	WORD			Type of analog input Ai3 See Cfg_Ai1	0 10	2	num
Cfg_Ai4	15729	WORD			Type of analog input Ai4 See Cfg_Ai1	0 10	2	num
FullScaleMin_Ai1	15736	WORD	-1		Analog input Ai1 start of scale value	-9999+9999	0	
FullScaleMax_Ai1	15737	WORD			Analog input Ai1 full scale value	-9999+9999	1000	
FullScaleMin_Ai2	15738	WORD	-1		Analog input Ai2 start of scale value See FullScaleMin_Ai1	-9999+9999	0	

LABEL	PAR. VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
FullScaleMax_A2	15739	WORD			Analog input Ai2 full scale value See FullScaleMAx_Ai1	-999+999	1000	
FullScaleMin_Ai3	15740	WORD	-1		Analog input Ai3 start of scale value See FullScaleMin_Ai1	-9999+9999	0	
FullScaleMax_Ai3	15741	WORD			Analog input Ai3 full scale value See FullScaleMax_Ai1	-999+999	1000	
FullScaleMin_Ai4	15742	WORD	-1		Analog input Ai4 start of scale value See FullScaleMin_Ai1	-9999+9999	0	
FullScaleMaxAi4	15743	WORD			Analog input Ai4 full scale value See FullScaleMax_Ai1	-999+999	100	
Calibration_Ai1	15748	WORD	-1		Analog input Ai1 differential	-180 180	0	°C/10 or °F/10
Calibration_Ai2	15749	WORD	-1		Analog input Ai2 differential	-180 180	0	°C/10 or °F/10
Calibration_Ai3	15750	WORD	-1		Analog input Ai3 differential	-1000 1000	0	
Calibration_Ai4	15751	WORD	-1		Analog input Ai4 differential	-1000 1000	0	
SubCfg_Al1	16010	WORD		Υ	 Analog input Al5 sub-mode function 0 = Low Pass filtered disabled, analog value in raw points 1 = Low Pass filtered disabled, analog value converted 2 = Low Pass filtered enabled, analog value in raw points 1 = Low Pass filtered enabled, analog value converted 	0 3	3	num
SubCfg_Al2	16011	WORD		Υ	See SubCfg_Al1	0 3	3	num
SubCfg_Al3	16012	WORD		Υ	See SubCfg_Al1	0 3	3	num
SubCfg_Al4	16013	WORD		Υ	See SubCfg_Al1	0 3	3	num

9.1.3. M171 Performance Flush parameters

LABEL	PAR VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
ACKNOWLEDGE	MENT fo	lder						
Par_TAB	15716	WORD		Υ	Map code Note: read/write parameter	0 65535	0	num
Par_POLI	15717	WORD		Υ	Model Code Note: read/write parameter	0 65535	1025	num
Par_PARMOD	15719	BOOL			Parameter changed Flag indicating change to default settings. • 0= map not modified. • 1= at least one parameter has been changed from the original configuration.	0 1	0	num
AI CALIBRATION	folder							
Gain_Ntc_Al1	15616	WORD			Ai1 NTC calibration gain	0 65535	32768	num
Gain_Ntc_Al2	15617	WORD			Ai2 NTC calibration gain	0 65535	32768	num
Gain_5V_Al3	15620	WORD			Ai3 0-5V calibration gain	0 65535	32768	num
Gain_10V_AI3	15621	WORD			Ai3 0-10V calibration gain	0 65535	32768	num
Gain_mA_Al3	15622	WORD			Ai3 4-20mA calibration gain	0 65535	32768	num
Offs_Ntc_Al1	15650	WORD	-1		Ai1 NTC calibration offset	-32768 32767	0	num
Offs_Ntc_Al2	15651	WORD	-1		Ai2 NTC calibration offset	-32768 32767	0	num
Offs_5V_AI3	15654	WORD	-1		Ai3 0-5V calibration offset	-32768 32767	0	num
Offs_10V_Al3	15655	WORD	-1		Ai3 0-10V calibration offset	-32768 32767	0	num
Offs_mA_Al3	15656	WORD	-1		Ai3 4-20mA calibration offset	-32768 32767	0	num
ANALOG INPUTS	S folder		1					
Temp_UM	15725	WORD		Y	Temperature unit of measure • 0 = °C; • 1 = °F	0 1	0	num
Cfg_Al1	15726	WORD			Type of analog input Ai1 O= NTC (NK103) 1= DI 2= NTC (103AT)	0 2	2	num
Cfg_Ai2	15727	WORD			Type of analog input Ai2 See Cfg_Ai1	0 2	2	num

LABEL	PAR VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
Cfg_Ai3	15728	WORD			Type of analog input Ai3 • 3 = 420mA • 4=0-10V • 5=0-5V	3 5	3	num
Cfg_Ai4	15729	WORD			Type of analog input Ai4 See Cfg_Ai3	3 5	3	num
FullScaleMin_ Ai3	15736	WORD	-1		Analog input Ai3 start of scale value N.B.: Minimum full scale: for current probes, value at 4mA, for 0-10V voltage probes, value at 0V, 10% for (0-5V) probes, value at 10% (corresponding to 0.5V).	-9999+9999	0	
FullScaleMAx_ Ai3	15737	WORD	-1		Analog input Ai3 full scale value N.B.: Maximum full scale for current probes, value at 20mA, for 0-10V voltage probes, value at 10V, for (0-5V) probes, value at 90% (corresponding to 4.5V).	-9999+9999	1000	
Calibration_Ai1	15748	WORD	-1		Analog input Ai1 differential	-180 180	0	°C/10 or °F/10
Calibration_Ai2	15749	WORD	-1		Analog input Ai2 differential	-180 180	0	°C/10 or °F/10
Calibration_Ai3	15750	WORD	-1		Analog input Ai3 differential	-1000 1000	0	
Calibration_Ai4	15751	WORD	-1		Analog input Ai4 differential	-1000 1000	0	
Compensation_ Al1	15752	WORD	-1		Internal compensation Al1	-1000 1000 °C/10	0	°C/10
Compensation_ Al4	15753	WORD	-1		Internal compensation AI4	-1000 1000 °C/10	0	°C/10
RS485 ON BOAR	D folder							
Addr_RS485_ OB	15774	WORD		Υ	On-board RS485 serial address The actual address is determined by the sum of this value + the value of the dip switch.	0 255	1	num
Proto_RS485_ OB	15775	WORD		Υ	On-board RS485 protocol selection • 2 = uNET • 3 = Modbus/RTU	2 3	2	num
Databit_ RS485_OB	15776	WORD		Υ	On-board RS485 data bit number Fixed setting 8	8 8	8	num
Stopbit_ RS485_OB	15777	WORD		Υ	On-board RS485 stop bit number 1 = 1 stop bit 2 = 2 stop bit	1 2	1	num

LABEL	PAR VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
Parity_RS485_ OB	15778	WORD		Υ	On-board RS485 protocol parity O= NULL 1= ODD 2= EVEN	0 2	2	num
Baud_RS485_ OB	15779	WORD		Y	On-board RS485 protocol baudrate • 0=9600 baud • 1=19200 baud • 2=38400 baud • 3=57600 baud • 4=76800 baud • 5=115200 baud	0 5	2	num
Addr_CAN_OB	15780	WORD		Υ	On-board CAN serial address The actual address is determined by the sum of this value + the value of the dip switch.	1 127	1	num
Baud_CAN_OB	15781	WORD		Υ	On-board CAN protocol baudrate 2=500 Kbaud 3=250 Kbaud 4=125 Kbaud 5=125 Kbaud 6=50 Kbaud	2 6	2	num

ON BOARD ETHERNET

The parameters necessary for the configuration of ports and protocols are these:



FREE WEB allows the use of HTTP and TFTP servers.

Parameter	Description	Label
HTTP ports	HTTP HyperText Transfer Protocol. An HTTP server generally listens on port 80 using TCP protocol.	Port_HTTP
TFTP ports	TFTP Trivial File Transfer Protocol. Protocol using basic FTP functionalities. Typical use: transfer of small files between hosts on a network. TFTP USES PORT 69	Port_TFTP
DHCP protocol	DHCP Dynamic Host Configuration Protocol	EnableDHCP_ ETH
		PriDNS_1_ETH
		PriDNS_2_ETH
		PriDNS_3_ETH
DNS system	DNS Domain Name System System for the conversion of host names, or network nodes, to IP addresses	PriDNS_4_ETH
Divo system	Used by TM171SW (SoMachineHVAC) to send text e-mails (strings)	SecDNS_1_ETH
		SecDNS_2_ETH
		SecDNS_3_ETH
		SecDNS_4_ETH

LABEL	PAR VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
ETHERNET ON BO	ARD fold	er						
Port_TFTP	15772	WORD		Υ	TFTP port TFTP communication Port number Default 0 corresponds to port 69	0 65535	0	num
Port_HTTP	15796	WORD		Υ	HTTP port HTTP communication Port number Default 0 corresponds to port 80	0 65535	0	num
Port_ETH	15797	WORD		Υ	Port TCP/IP Modbus communication port. Port 502 for example	0 65535	502	num
lp_1_ETH	15798	WORD		Υ	On-board Ethernet passive IP address (part 1)	0 255	10	num
lp_2_ETH	15799	WORD		Υ	On-board Ethernet passive IP address (part 2)	0 255	0	num
lp_3_ETH	15800	WORD		Υ	On-board Ethernet passive IP address (part 3)	0 255	0	num
lp_4_ETH	15801	WORD		Υ	On-board Ethernet passive IP address (part 4)	0 255	100	num
DefGtwy_1_ETH	15802	WORD		Υ	Default Gateway (part 1)	0 255	192	num
DefGtwy_2_ETH	15803	WORD		Υ	Default Gateway (part 2)	0 255	168	num
DefGtwy_3_ETH	15804	WORD		Υ	Default Gateway (part 3)	0 255	0	num
DefGtwy_4_ETH	15805	WORD		Υ	Default Gateway (part 4)	0 255	1	num
NetMsk_1_ETH	15806	WORD		Υ	Net mask (part 1)	0 255	255	num
NetMsk_2_ETH	15807	WORD		Υ	Net mask (part 2)	0 255	255	num
NetMsk_3_ETH	15808	WORD		Υ	Net mask (part 3)	0 255	255	num
NetMsk_4_ETH	15809	WORD		Υ	Net mask (part 4)	0 255	0	num
PriDNS_1_ETH	15810	WORD		Υ	Primary DNS server (part 1)	0 255	194	num
PriDNS_2_ETH	15811	WORD		Υ	Primary DNS server (part 2)	0 255	25	num
PriDNS_3_ETH	15812	WORD		Υ	Primary DNS server (part 3)	0 255	2	num
PriDNS_4_ETH	15813	WORD		Υ	Primary DNS server (part 4)	0 255	129	num
SecDNS_1_ETH	15814	WORD		Υ	Secondary DNS server (part 1)	0 255	194	num
SecDNS_2_ETH	15815	WORD		Υ	Secondary DNS server (part 2)	0 255	25	num
SecDNS_3_ETH	15816	WORD		Υ	Secondary DNS server (part 3)	0 255	2	num
SecDNS_4_ETH	15817	WORD		Υ	Secondary DNS server (part 4)	0 255	130	num
EnableDHCP_ ETH	15819	WORD		Υ	Enable DHCP	0 1 (False, True)	False	flag
Display folder								
Hmi_Language	15819	WORD			Display language 0 = Italian 1 = English 2 = French 3 = German 4 = Spanish	0 65535	0	num

LABEL	PAR VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
Par_ContrLCD	15723	WORD		Y	LCD Contrast Allows adjustment of the LCD display contrast.	0 64	30	num
Par_ BackLightTime	15724	WORD			Backlight switch-on time Allows adjustment of LCD display switch-on time.	0 3600	10	sec
Buzzer folder								
Buzzer_Mode	15990	WORD			Buzzer mode 0= always off 1= beep per key	0 1	0	num
HMI Management f	older							
Hmi_Language	15989	WORD				0 65535	0	num
HmiList_Current	15820	WORD			Current HMI 0= HMI remote 1 1= HMI remote 2 2= HMI remote 3 3= HMI remote 4 4= HMI remote 5 5= HMI remote 6 6= HMI remote 7 7= HMI remote 8 8= HMI remote 9 9= HMI remote 10 10 = not used 11= Local HMI	0 11	11	num
If HmiList_Current=	=11 the fo	ollowing fo	lders	/para	meters are NOT USED.			
HMI remote 1 folde	r				,			
HmiList_ID_1	15821	WORD			HMI remote 1 navigation ID list	0 254	0	num
HmiList_Res_1	15833	WORD			HMI remote 1 navigation resource type HMI remote 1 navigation resource type 1=RTU (RS485 Modbus RTU) 2=TCP (Modbus TCP) 3=CAN (CAN)	1 3	3	num
HmiList_Addr_1	15845	WORD			HMI remote 1 navigation resource address for CAN, RTU and TCP (IP part 1)	0 255	0	num
HmiList_Addr_2	15846	WORD			HMI remote 1 navigation resource address for TCP (IP part 2)	0 255	0	num
HmiList_Addr_3	15847	WORD			HMI remote 1 navigation resource address for TCP (IP part 3)	0 255	0	num
HmiList_Addr_4	15848	WORD			HMI remote 1 navigation resource address for TCP (IP part 4)	0 255	0	num
HmiList_File_1	15893	15 byte			HMI remote 1 navigation file (DOS 8.3 uppercase format)	*****		string
HMI remote 2 folde	r							
HmiList_ID_2	15822	WORD			HMI remote 2 navigation ID list	0 254	0	num

LABEL	PAR VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
HmiList_Res_2	15834	WORD			HMI remote 2 navigation resource type 1=RTU (RS485 Modbus RTU) 2=TCP (Modbus TCP) 3=CAN (CAN)	1 3	3	num
HmiList_Addr_1	15849	WORD			HMI remote 2 navigation resource address for CAN, RTU and TCP (IP part 1)	0 255	0	num
HmiList_Addr_2	15850	WORD			HMI remote 2 navigation resource address for TCP (IP part 2)	0 255	0	num
HmiList_Addr_3	15851	WORD			HMI remote 2 navigation resource address for TCP (IP part 3)	0 255	0	num
HmiList_Addr_4	15852	WORD			HMI remote 2 navigation resource address for TCP (IP part 4)	0 255	0	num
HmiList_File_2	15901	15 byte			HMI remote 2 navigation file (DOS 8.3 uppercase format)	*****		string
HMI remote 3 folde	r							· 1
HmiList_Res_3	15835	WORD			HMI remote 3 navigation resource type 1=RTU (RS485 Modbus RTU) 2=TCP (Modbus TCP) 3=CAN (CAN)	1 3	3	num
HmiList_Addr_1	15853	WORD			HMI remote 3 navigation resource address for CAN, RTU and TCP (IP part 1)	0 255	0	num
HmiList_Addr_2	15854	WORD			HMI remote 3 navigation resource address for TCP (IP part 2)	0 255	0	num
HmiList_Addr_3	15855	WORD			HMI remote 3 navigation resource address for TCP (IP part 3)	0 255	0	num
HmiList_Addr_4	15856	WORD			HMI remote 3 navigation resource address for TCP (IP part 4)	0 255	0	num
HmiList_File_3	15909	15 byte			HMI remote 3 navigation file (DOS 8.3 uppercase format)	******		string
HMI remote 4 folde]
HmiList_ID_4	15822	WORD			HMI remote 4 navigation ID list	0 254	0	num
HmiList_Res_4	15836	WORD			HMI remote 4 navigation resource type 1=RTU (RS485 Modbus RTU) 2=TCP (Modbus TCP) 3=CAN (CAN)	1 3	3	num
HmiList_Addr_1	15857	WORD			HMI remote 4 navigation resource address for CAN, RTU and TCP (IP part 1)	0 255	0	num
HmiList_Addr_2	15859	WORD			HMI remote 4 navigation resource address for TCP (IP part 2)	0 255	0	num
HmiList_Addr_3	15859	WORD			HMI remote 4 navigation resource address for TCP (IP part 3)	0 255	0	num

LABEL	PAR VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
HmiList_Addr_4	15860	WORD			HMI remote 4 navigation resource address for TCP (IP part 4)	0 255	0	num
HmiList_File_4	15917	15 byte			HMI remote 4 navigation file (DOS 8.3 uppercase format)	*****		string
HMI remote 5 folde	r							
HmiList_ID_5	15825	WORD			HMI remote 5 navigation ID list	0 254	0	num
HmiList_Res_5	15837	WORD			HMI remote 5 navigation resource type 1=RTU (RS485 Modbus RTU) 2=TCP (Modbus TCP) 3=CAN (CAN)	1 3	3	num
HmiList_Addr_1	15861	WORD			HMI remote 5 navigation resource address for CAN, RTH and TCP (IP part 1)	0 255	0	num
HmiList_Addr_2	15862	WORD			HMI remote 5 navigation resource address for TCP (IP part 2)	0 255	0	num
HmiList_Addr_3	15863	WORD			HMI remote 5 navigation resource address for TCP (IP part 3)	0 255	0	num
HmiList_Addr_4	15864	WORD			HMI remote 5 navigation resource address for TCP (IP part 4)	0 255	0	num
HmiList_File_5	15925	15 byte			HMI remote 5 navigation file (DOS 8.3 uppercase format)	*****		string
HMI remote 6 folde	r							
HmiList_ID_6	15826	WORD			HMI remote 6 navigation ID list	0 254	0	num
HmiList_Res_6	15838	WORD			HMI remote 6 navigation resource type 1=RTU (RS485 Modbus RTU) 2=TCP (Modbus TCP) 3=CAN (CAN)	1 3	3	num
HmiList_Addr_1	15865	WORD			HMI remote 6 navigation resource address for CAN, RTH and TCP (IP part 1)	0 255	0	num
HmiList_Addr_2	15866	WORD			HMI remote 6 navigation resource address for TCP (IP part 2)	0 255	0	num
HmiList_Addr_3	15867	WORD			HMI remote 6 navigation resource address for TCP (IP part 3)	0 255	0	num
HmiList_Addr_4	15868	WORD			HMI remote 6 navigation resource address for TCP (IP part 4)	0 255	0	num
HmiList_File_6	15933	15 byte			HMI remote 6 navigation file (DOS 8.3 uppercase format)	*****		string
HMI remote 7 folde	r							
HmiList_ID_7	15827	WORD			HMI remote 7 navigation ID list	0 254	0	num
HmiList_Res_7	15839	WORD			HMI remote 7 navigation resource type 1=RTU (RS485 Modbus RTU) 2=TCP (Modbus TCP) 3=CAN (CAN)	1 3	3	num

LABEL	PAR VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
HmiList_Addr_1	15869	WORD			HMI remote 7 navigation resource address for CAN, RTU and TCP (IP part 1)	0 255	0	num
HmiList_Addr_2	15870	WORD			HMI remote 7 navigation resource address for TCP (IP part 2)	0 255	0	num
HmiList_Addr_3	15871	WORD			HMI remote 7 navigation resource address for TCP (IP part 3)	0 255	0	num
HmiList_Addr_4	15872	WORD			HMI remote 7 navigation resource address for TCP (IP part 4)	0 255	0	num
HmiList_File_7	15941	15 byte			HMI remote 7 navigation file (DOS 8.3 uppercase format)	*****		string
HMI remote 8 folde	r							
HmiList_ID_8	15828	WORD			HMI remote 8 navigation ID list	0 254	0	num
HmiList_Res_8	15840	WORD			HMI remote 8 navigation resource type 1=RTU (RS485 Modbus RTU) 2=TCP (Modbus TCP) 3=CAN (CAN)	1 3	3	num
HmiList_Addr_1	15873	WORD			HMI remote 8 navigation resource address for CAN, RTU and TCP (IP part 1)	0 255	0	num
HmiList_Addr_2	15874	WORD			HMI remote 8 navigation resource address for TCP (IP part 2)	0 255	0	num
HmiList_Addr_3	15875	WORD			HMI remote 8 navigation resource address for TCP (IP part 3)	0 255	0	num
HmiList_Addr_4	15876	WORD			HMI remote 8 navigation resource address for TCP (IP part 4)	0 255	0	num
HmiList_File_8	15949	15 byte			HMI remote 8 navigation file (DOS 8.3 uppercase format)	*****		string
HMI remote 9 folde	r							
HmiList_ID_9	15829	WORD			HMI remote 9 navigation ID list	0 254	0	num
HmiList_Res_9	15841	WORD			HMI remote 9 navigation resource type 1=RTU (RS485 Modbus RTU) 2=TCP (Modbus TCP) 3=CAN (CAN)	1 3	3	num
HmiList_Addr_1	15877	WORD			HMI remote 9 navigation resource address for CAN, RTU and TCP (IP part 1)	0 255	0	num
HmiList_Addr_2	15878	WORD			HMI remote 9 navigation resource address for TCP (IP part 2)	0 255	0	num
HmiList_Addr_3	15879	WORD			HMI remote 9 navigation resource address for TCP (IP part 3)	0 255	0	num
HmiList_Addr_4	15880	WORD			HMI remote 9 navigation resource address for TCP (IP part 4)	0 255	0	num
HmiList_File_9	15957	15 byte			HMI remote 9 navigation file (DOS 8.3 uppercase format)	*****		string

LABEL	PAR VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
HMI remote 10 fold	er							
HmiList_ID_10	15830	WORD			HMI remote 10 navigation ID list	0 254	0	num
HmiList_Res_10	15842	WORD			HMI remote 10 navigation resource type 1=RTU (RS485 Modbus RTU) 2=TCP (Modbus TCP) 3=CAN (CAN)	1 3	3	num
HmiList_Addr_1	15881	WORD			HMI remote 10 navigation resource address for CAN, RTU and TCP (IP part 1)	0 255	0	num
HmiList_Addr_2	15882	WORD			HMI remote 10 navigation resource address for TCP (IP part 2)	0 255	0	num
HmiList_Addr_3	15883	WORD			HMI remote 10 navigation resource address for TCP (IP part 3)	0 255	0	num
HmiList_Addr_4	15884	WORD			HMI remote 10 navigation resource address for TCP (IP part 4)	0 255	0	num
HmiList_File_10	15965	15 byte			HMI remote 10 navigation file (DOS 8.3 uppercase format)	******		string